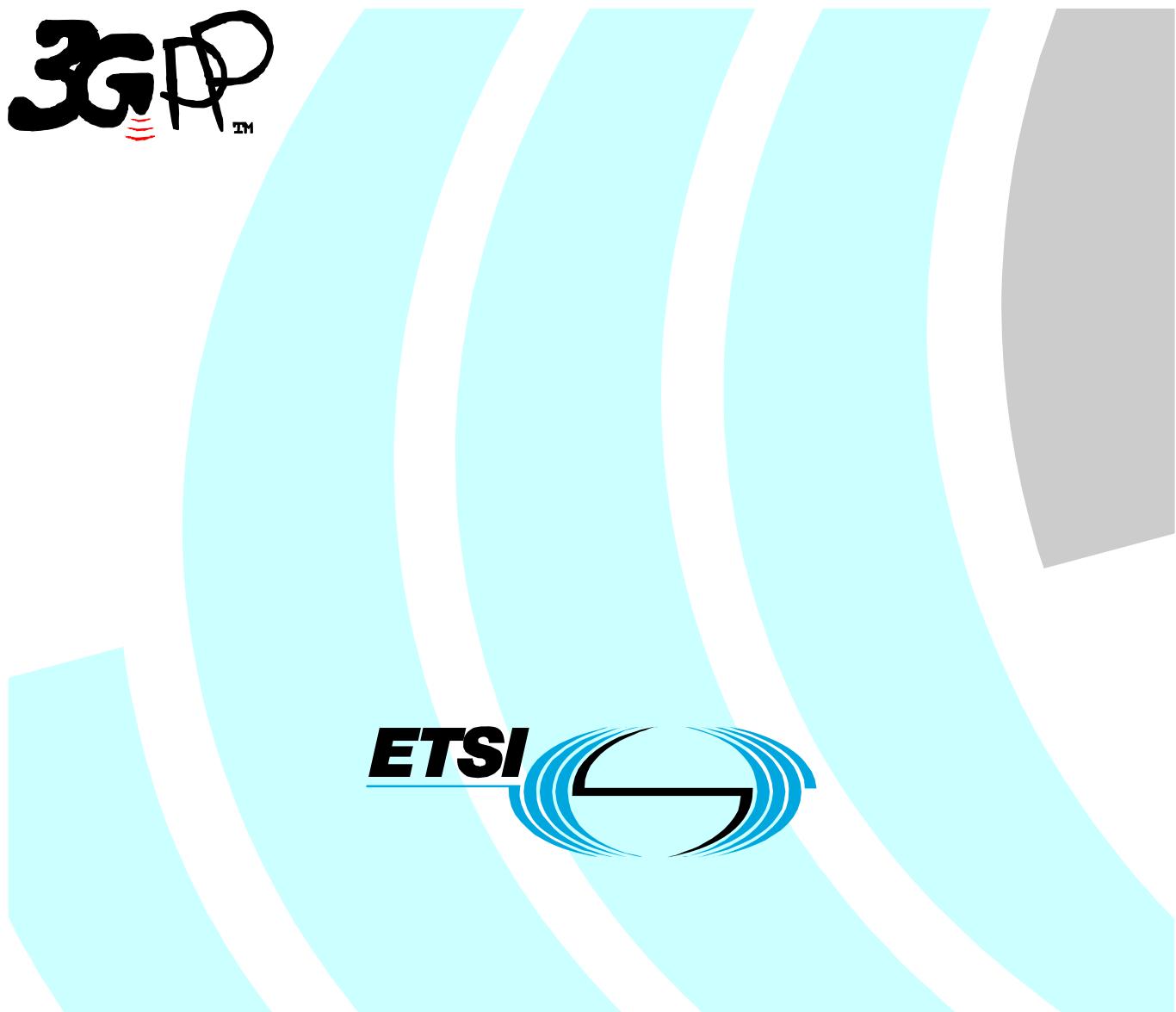


**Universal Mobile Telecommunications System (UMTS);
UTRAN IuPC interface Positioning Calculation
Application Part (PCAP) signalling
(3GPP TS 25.453 version 8.0.0 Release 8)**



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Contents

Intellectual Property Rights	2
Foreword.....	2
Foreword.....	8
1 Scope	9
2 References	9
3 Definitions and abbreviations.....	10
3.1 Definitions.....	10
3.2 Abbreviations	11
4 General	12
4.1 Procedure Specification Principles.....	12
4.2 Forwards and Backwards Compatibility	12
4.3 Specification Notations	12
5 PCAP Services	13
6 Services Expected from Signalling Transport.....	14
7 Functions of PCAP	14
8 PCAP Procedures	14
8.1 Elementary Procedures.....	14
8.2 Position Calculation	15
8.2.1 General.....	15
8.2.2 Successful Operation	15
8.2.3 Unsuccessful Operation	17
8.2.4 Abnormal Conditions.....	17
8.3 Information Exchange Initiation.....	18
8.3.1 General.....	18
8.3.2 Successful Operation	18
8.3.3 Unsuccessful Operation	22
8.3.4 Abnormal Conditions.....	22
8.4 Information Reporting	24
8.4.1 General.....	24
8.4.2 Successful Operation	24
8.4.3 Abnormal Conditions.....	25
8.5 Information Exchange Termination	25
8.5.1 General.....	25
8.5.2 Successful Operation	25
8.5.3 Abnormal Conditions.....	25
8.6 Information Exchange Failure	25
8.6.1 General.....	25
8.6.2 Successful Operation	26
8.7 Error Indication	26
8.7.1 General.....	26
8.7.2 Successful Operation	26
8.7.3 Abnormal Conditions.....	27
8.8 Position Initiation	27
8.8.1 General.....	27
8.8.2 Successful Operation	27
8.8.3 Unsuccessful Operation	28
8.8.4 Abnormal Conditions.....	28
8.9 Position Activation	29
8.9.1 General.....	29
8.9.2 Successful Operation	29
8.9.3 Unsuccessful Operation	31

8.9.4	Abnormal Conditions.....	31
8.10	Position Parameter Modification.....	31
8.10.1	General.....	31
8.10.2	Successful Operation	32
8.10.3	Abnormal Conditions.....	32
8.11	Abort	32
8.11.1	General.....	32
8.11.2	Successful Operation	32
8.11.3	Abnormal Conditions.....	33
8.12	Position Periodic Report.....	33
8.12.1	General.....	33
8.12.2	Successful Operation	33
8.12.3	Abnormal Conditions.....	34
8.13	Position Periodic Result	34
8.13.1	General.....	34
8.13.2	Successful Operation	34
8.13.3	Abnormal Conditions.....	35
8.14	Position Periodic Termination.....	35
8.14.1	General.....	35
8.14.2	Successful Operation	35
8.14.3	Abnormal Conditions.....	36
9	Elements for PCAP Communication.....	36
9.1	Message Functional Definition and Content	36
9.1.1	General.....	36
9.1.2	Message Contents	36
9.1.2.1	Presence	36
9.1.2.2	Criticality	37
9.1.2.3	Range	37
9.1.2.4	Assigned Criticality.....	37
9.1.3	POSITION CALCULATION REQUEST	38
9.1.4	POSITION CALCULATION RESPONSE.....	39
9.1.5	POSITION CALCULATION FAILURE	39
9.1.6	INFORMATION EXCHANGE INITIATION REQUEST	40
9.1.7	Information Exchange Initiation Response.....	41
9.1.8	INFORMATION EXCHANGE INITIATION FAILURE	41
9.1.9	INFORMATION REPORT	41
9.1.10	INFORMATION EXCHANGE TERMINATION REQUEST	41
9.1.11	INFORMATION EXCHANGE FAILURE INDICATION	42
9.1.12	ERROR INDICATION.....	42
9.1.13	POSITION INITIATION REQUEST.....	42
9.1.14	POSITION INITIATION RESPONSE.....	42
9.1.15	POSITION INITIATION FAILURE.....	43
9.1.16	POSITION ACTIVATION REQUEST.....	44
9.1.17	POSITION ACTIVATION RESPONSE.....	45
9.1.18	POSITION ACTIVATION FAILURE.....	46
9.1.19	POSITION PARAMETER MODIFICATION	46
9.1.20	ABORT	46
9.1.21	POSITION PERIODIC REPORT.....	47
9.1.22	POSITION PERIODIC RESULT	48
9.1.23	POSITION PERIODIC TERMINATION	48
9.2	Information Element Functional Definitions and Contents	48
9.2.1	General.....	48
9.2.2	Radio Network Layer Related IEs	49
9.2.2.1	Almanac and Satellite Health SIB.....	49
9.2.2.2	Altitude and direction.....	49
9.2.2.3	Cause	49
9.2.2.4	Criticality Diagnostics.....	53
9.2.2.5	DGPS Corrections.....	55
9.2.2.6	Geographical Area	56
9.2.2.7	Geographical Coordinates	58
9.2.2.8	GPS Acquisition Assistance.....	58

9.2.2.9	GPS Almanac and Satellite Health.....	60
9.2.2.10	GPS Clock and Ephemeris Parameters	60
9.2.2.11	GPS Ionospheric Model	62
9.2.2.12	GPS Measured Results	63
9.2.2.13	GPS Navigation Model	64
9.2.2.14	GPS Real Time Integrity	65
9.2.2.15	GPS Reference Time	66
9.2.2.16	GPS Transmission TOW	67
9.2.2.17	GPS UTC Model	67
9.2.2.18	GPS-UTRAN Time Relationship Uncertainty	67
9.2.2.19	Information Exchange ID.....	67
9.2.2.20	Information Exchange Object Type	67
9.2.2.21	Information Report Characteristics	68
9.2.2.22	Information Type	69
9.2.2.23	Message Structure	73
9.2.2.24	Message Type	74
9.2.2.25	Method Type	74
9.2.2.26	Requested Data Value	75
9.2.2.27	Requested Data Value Information	76
9.2.2.28	Transaction ID.....	76
9.2.2.29	Transmission TOW Indicator.....	77
9.2.2.30	Uncertainty Ellipse.....	77
9.2.2.31	Cell-ID Measured Results Info List	77
9.2.2.32	OTDOA Measured Results Info List	80
9.2.2.33	OTDOA Neighbour Cell Info	83
9.2.2.34	OTDOA Reference Cell Info	85
9.2.2.35	UE Positioning Measurement Quality.....	88
9.2.2.36	UTRAN Access Point Position with Altitude	89
9.2.2.37	UTRAN Cell Identifier (UC-ID).....	89
9.2.2.37A	Extended RNC-ID	89
9.2.2.38	Horizontal Accuracy Code	90
9.2.2.39	Vertical Accuracy Code	90
9.2.2.40	Accuracy Fulfilment Indicator	90
9.2.2.41	Uplink DPCH information	90
9.2.2.42	Frequency information	91
9.2.2.43	PRACH parameters	91
9.2.2.44	Compressed Mode Assistance Data	92
9.2.2.45	C-RNTI	92
9.2.2.46	Primary Scrambling Code	92
9.2.2.47	PRACH information.....	92
9.2.2.48	TFS.....	93
9.2.2.49	CTFC.....	94
9.2.2.50	Request Type.....	94
9.2.2.51	UE Positioning Capability.....	95
9.2.2.52	Response Time	97
9.2.2.53	Positioning Priority	98
9.2.2.54	Client Type.....	98
9.2.2.55	Positioning Method	98
9.2.2.56	U-TDOA Bit Count	99
9.2.2.57	U-TDOA Time Interval.....	100
9.2.2.58	Additional Method Type	100
9.2.2.59	UE Positioning OTDOA Assistance Data	100
9.2.2.60	UL TrCH information	103
9.2.2.61	Semi-static Transport Format Information.....	103
9.2.2.62	Environment Characterisation.....	104
9.2.2.63	Chip Offset.....	104
9.2.2.64	Frame Offset	104
9.2.2.65	Position Data	104
9.2.2.66	Transmission Gap Pattern Sequence Information	107
9.2.2.67	Active Pattern Sequence Information.....	108
9.2.2.68	CFN.....	109
9.2.2.69	Positioning Response Time	109

9.2.2.70	Reference Cell Position.....	110
9.2.2.71	UE Positioning IPDL Parameters.....	110
9.2.2.72	Burst Mode Parameters	110
9.2.2.73	SFN-SFN Relative Time Difference	110
9.2.2.74	UTDOA Group	111
9.2.2.75	Maximum Set of E-DPDCHs.....	111
9.2.2.76	Puncture Limit.....	112
9.2.2.77	E-DCH Transport Format Combination Set Information (E-TFCS Information)	112
9.2.2.78	Reference E-TFCI Power Offset.....	112
9.2.2.79	E-TTI.....	113
9.2.2.80	E-DPCCH Power Offset	113
9.2.2.81	Cell Parameter ID.....	113
9.2.2.82	TFCI Coding	113
9.2.2.83	Repetition Length.....	114
9.2.2.84	Repetition Period.....	114
9.2.2.85	TDD DPCH Offset.....	114
9.2.2.86	UL Timeslot Information	114
9.2.2.87	Time Slot.....	115
9.2.2.88	Midamble Shift And Burst Type.....	115
9.2.2.89	TFCI Presence.....	116
9.2.2.90	TDD UL Code Information.....	116
9.2.2.91	TDD Channelisation Code	117
9.2.2.92	Special Burst Scheduling	117
9.2.2.93	Max PRACH Midamble Shift.....	117
9.2.2.94	PRACH Midamble	117
9.2.2.95	USCH Parameters	118
9.2.2.96	USCH Scheduling Offset	118
9.2.2.97	Include Velocity	118
9.2.2.98	Velocity Estimate	119
9.2.2.99	Horizontal Speed and Bearing.....	120
9.2.2.100	Vertical Velocity	121
9.2.2.101	GPS Positioning Instructions	121
9.2.2.102	UE Position Estimate Info.....	122
9.2.2.103	UTRAN-GPS Reference Time	123
9.2.2.104	UTRAN-GPS Reference Time Result.....	124
9.2.2.105	$T_{UTRAN-GPS}$ Drift Rate.....	124
9.2.2.106	Periodic Position Calculation Info	124
9.2.2.107	Periodic Location Info.....	125
9.2.2.108	Amount of Reporting	125
9.2.2.109	Measurement Instructions Used	125
9.2.2.110	RRC State Change	125
9.2.2.111	Periodic Position Termination Cause	125
9.2.2.112	Requested Cell-ID Measurements.....	126
9.2.2.113	DGANSS Corrections	127
9.2.2.114	GANSS Almanac and Satellite Health.....	129
9.2.2.115	GANSS Clock Model.....	133
9.2.2.115A	GANSS Additional Clock Models	133
9.2.2.116	GANSS Ionospheric Model	135
9.2.2.116A	GANSS Additional Ionospheric Model	135
9.2.2.117	GANSS Measured Results	136
9.2.2.118	GANSS Navigation Model	138
9.2.2.118A	GANSS Additional Navigation Models	139
9.2.2.119	GANSS Orbit Model.....	139
9.2.2.119A	GANSS Additional Orbit Models	140
9.2.2.120	GANSS Positioning Instructions.....	144
9.2.2.121	GANSS-UTRAN Time Relationship Uncertainty	146
9.2.2.122	GANSS Real Time Integrity	146
9.2.2.123	GANSS Reference Measurement Information.....	146
9.2.2.124	GANSS Reference Time	148
9.2.2.125	GANSS Time Model.....	148
9.2.2.125A	GANSS Additional Time Models	149
9.2.2.126	GANSS UTC Model	149

9.2.2.126A	GANSS Additional UTC Models.....	150
9.2.2.127	GANSS Time Indicator.....	152
9.2.2.127A	GANSS Data Bit Assistance	152
9.2.2.128	Additional GPS Assistance Data Required	153
9.2.2.129	Additional GANSS Assistance Data Required.....	154
9.2.2.130	GANSS ID	156
9.2.2.131	GANSS Signal ID	156
9.2.2.132	GPS Reference Time Uncertainty	156
9.2.2.133	GANSS Earth Orientation Parameters	157
9.2.2.134	SBAS ID	157
9.2.2.135	GANSS Auxiliary Information	158
9.2.2.136	UTRAN-GANSS Reference Time Result.....	159
9.3	Message and Information Element Abstract Syntax (with ASN.1).....	160
9.3.0	General.....	160
9.3.1	Usage of private message mechanism for non-standard use	160
9.3.2	Elementary Procedure Definitions	160
9.3.3	PDU Definitions	166
9.3.4	Information Element Definitions	180
9.3.5	Common Definitions.....	267
9.3.6	Constant Definitions	268
9.3.7	Container Definitions.....	272
9.4	Message Transfer Syntax	275
10	Handling of Unknown, Unforeseen and Erroneous Protocol Data	275
10.1	General	275
10.2	Transfer Syntax Error	276
10.3	Abstract Syntax Error	276
10.3.1	General.....	276
10.3.2	Criticality Information	277
10.3.3	Presence Information	278
10.3.4	Not comprehended IE/IE group	278
10.3.4.1	Procedure Code	278
10.3.4.1A	Type of Message	279
10.3.4.2	IEs other than the Procedure Code and Type of Message	279
10.3.5	Missing IE or IE group	280
10.3.6	IEs or IE groups received in wrong order or with too many occurrences or erroneously present	281
10.4	Logical Error	282
10.5	Exceptions	282
Annex A (informative): Guidelines for Usage of the Criticality Diagnostics IE		283
A.1	EXAMPLE MESSAGE Layout	283
A.2	Example on a Received EXAMPLE MESSAGE.....	284
A.3	Content of Criticality Diagnostics	286
A.3.1	Example 1	286
A.3.2	Example 2	288
A.3.3	Example 3	290
A.3.4	Example 4	292
A.3.5	Example 5	294
A.4	ASN.1 of EXAMPLE MESSAGE	295
Annex B (informative): Change history		299
History		301

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1 Scope

The present document specifies the *Positioning Calculation Application Part (PCAP)* between the Radio Network Controller (RNC) and the Stand-Alone SMLC (SAS). It fulfills the RNC-SAS communication requirements specified in [6] and thus defines the Iupc interface and its associated signaling procedures.

2 References

The following documents contain provisions which, through reference in this text, constitute provisions of the present document.

- References are either specific (identified by date of publication, edition number, version number, etc.) or non-specific.
- For a specific reference, subsequent revisions do not apply.
- For a non-specific reference, the latest version applies. In the case of a reference to a 3GPP document (including a GSM document), a non-specific reference implicitly refers to the latest version of that document *in the same Release as the present document*.

- [1] 3GPP TS 25.450: "UTRAN Iupc interface general aspects and principles".
- [2] 3GPP TS 25.451: "UTRAN Iupc interface layer 1".
- [3] 3GPP TS 25.452: "UTRAN Iupc interface signalling transport".
- [4] 3GPP TS 25.331: "Radio Resource Control (RRC) Protocol Specification".
- [5] 3GPP TS 25.401: "UTRAN Overall Description".
- [6] 3GPP TS 25.305: "Stage 2 functional specification of UE positioning in UTRAN".
- [7] ITU-T Recommendation X.680 (07/2002): "Information technology - Abstract Syntax Notation One (ASN.1): Specification of basic notation".
- [8] ITU-T Recommendation X.681 (07/2002): "Information technology - Abstract Syntax Notation One (ASN.1): Information object specification".
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- [10] ICD-GPS-200: (12 April 2000) "Navstar GPS Space Segment/Navigation User Interface".
- [11] 3GPP TS 23.032: "Universal Geographical Area Description (GAD)".
- [12] 3GPP TR 25.921: "Guidelines and principles for protocol description and error handling".
- [13] 3GPP TS 25.133: "Requirements for support of Radio Resource management (FDD)".
- [14] 3GPP TS 25.123: "Requirements for support of Radio Resource management (TDD)".
- [15] 3GPP TS 22.071: "Location Services (LCS); Service Description; Stage1".
- [16] 3GPP TS 25.212: "Multiplexing and Channel Coding (FDD)".
- [17] 3GPP TS 25.213: "Spreading and Modulation (FDD)".
- [18] 3GPP TS 25.223: "Spreading and Modulation (TDD)".
- [19] 3GPP TS 25.221: "Physical channels and mapping of transport channels onto physical channels (TDD)".
- [20] 3GPP TS 25.101: "User Equipment (UE) radio transmission and reception (FDD)".

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- [25] IS-GPS-800, Navstar GPS Space Segment/User Segment L1C Interfaces, March 31, 2008.
- [26] Specification for the Wide Area Augmentation System (WAAS), US Department of Transportation, Federal Aviation Administration, DTFA01-96-C-00025, 2001.
- [27] IS-QZSS, Quasi Zenith Satellite System Navigation Service Interface Specifications for QZSS, Ver.1.0, June 17, 2008.
- [28] Global Navigation Satellite System GLONASS Interface Control Document, Version 5, 2002.

3 Definitions and abbreviations

3.1 Definitions

For the purposes of the present document, the following terms and definitions apply:

Stand-Alone SMLC (SAS): logical node that interconnects to the RNC over the Iupc interface via the PCAP protocol. An SAS performs the following procedures:

- provide GNSS (i.e. GPS or GANSS (e.g. Galileo)) related data to the RNC;
- performs the position calculation function based upon UE Positioning measurement data;
- in SAS centric mode, selects the positioning method and controls the positioning procedure.

Elementary Procedure: PCAP consists of Elementary Procedures (EPs).

An Elementary Procedure is a unit of interaction between the RNC and the SAS. An EP consists of an initiating message and possibly a response message. Two kinds of EPs are used:

- **Class 1:** Elementary Procedures with response (success or failure).
- **Class 2:** Elementary Procedures without response.

For Class 1 EPs, the types of responses can be as follows:

Successful:

- A signalling message explicitly indicates that the elementary procedure successfully completed with the receipt of the response.

Unsuccessful:

- A signalling message explicitly indicates that the EP failed.

Class 2 EPs are considered always successful.

Information Exchange Context: Information Exchange Context is created by the first Information Exchange Initiation Procedure initiated by the RNC and requested from the SAS.

The Information Exchange Context is deleted after the Information Exchange Termination or the Information Exchange Failure procedure when there is no more Information Exchange to be provided by the RNC to the SAS. The Information

Exchange Context is identified by an SCCP connection as, for Information Exchanges, only the connection oriented mode of the signalling bearer is used.

Positioning Initiation Context: In the SAS centric mode of operation each positioning request is assigned a unique logical connection identity, i.e., SCCP Source and Destination Local Reference numbers.

RNC Centric Mode of Operation: The RNC determines, initiates and controls the positioning method to be used for each positioning request.

SAS Centric Mode of Operation: The SAS determines, initiates and controls the positioning method to be used for each positioning request.

Positioning Event: The activity associated with the positioning of a UE resulting from the reception of UE positioning request from the CN.

3.2 Abbreviations

For the purposes of the present document, the following abbreviations apply:

A-GANSS	Assisted GANSS
A-GPS	Assisted GPS
ASN.1	Abstract Syntax Notation One
CN	Core Network
CRNC	Controlling RNC
DGANSS	Differential GANSS
DGPS	Differential GPS
ECEF	Earth-Centered, Earth-Fixed
ECI	Earth-Centered-Inertial
EGNOS	European Geostationary Navigation Overlay Service
EP	Elementary Procedure
FDD	Frequency Division Duplex
GAGAN	GPS Aided Geo Augmented NavigationGANSS Galileo and Additional Navigation Satellite Systems
GLONASS	GLObal'naya NAVigatsionnaya Sputnikovaya Sistema (Engl.: Global Navigation Satellite System)
GNSS	Global Navigation Satellite System
GPS	Global Positioning System
ICD	Interface Control Document
MSAS	Multi-functional Satellite Augmentation System
MSC	Mobile services Switching Center
OTDOA	Observed Time Difference Of Arrival
PCAP	Positioning Calculation Application Part
PRC	Pseudorange Correction
PRN	Pseudo-Random Noise
QZSS	Quasi-Zenith Satellite System
RNC	Radio Network Controller
RNS	Radio Network Subsystem
RRC	Radio Resource Control
SAS	Stand-Alone SMLC
SBAS	Satellite Based Augmentation System
SCCP	Signalling Connection Control Part
SIB	System Information Block
SMLC	Serving Mobile Location Center
SRNC	Serving RNC
SRNS	Serving RNS
SV	Space Vehicle
TDD	Time Division Duplex
TOD	Time of Day
TOW	Time of Week
UE	User Equipment
UTC	Universal Coordinated Time
U-TDOA	Uplink Time Difference Of Arrival
UTRAN	Universal Terrestrial Radio Access Network

WAAS	Wide Area Augmentation System
WGS-84	World Geodetic System 1984

4 General

4.1 Procedure Specification Principles

The principle for specifying the procedure logic is to specify the functional behaviour of the SAS exactly and completely. The RNC functional behaviour is left unspecified.

The following specification principles have been applied for the procedure text in clause 8:

- The procedure text discriminates between:
 - 1) Functionality which "shall" be executed:
 - The procedure text indicates that the receiving node "shall" perform a certain function Y under a certain condition. If the receiving node supports procedure X but cannot perform functionality Y requested in the REQUEST message of a Class 1 EP, the receiving node shall respond with the message used to report unsuccessful outcome for this procedure, containing an appropriate cause value.
 - 2) Functionality which "shall, if supported" be executed:
 - The procedure text indicates that the receiving node "shall, if supported," perform a certain function Y under a certain condition. If the receiving node supports procedure X, but does not support functionality Y, the receiving node shall proceed with the execution of the EP, possibly informing the requesting node about the not supported functionality.
- Any required inclusion of an optional IE in a response message is explicitly indicated in the procedure text. If the procedure text does not explicitly indicate that an optional IE shall be included in a response message, the optional IE shall not be included.

4.2 Forwards and Backwards Compatibility

The forwards and backwards compatibility of the protocol is assured by mechanism where all current and future messages, and IEs or groups of related IEs, include Id and criticality fields that are coded in a standard format that will not be changed in the future. These parts can always be decoded regardless of the standard version.

4.3 Specification Notations

For the purposes of the present document, the following notations apply:

- [FDD] This tagging of a word indicates that the word preceding the tag "[FDD]" applies only to FDD. This tagging of a heading indicates that the heading preceding the tag "[FDD]" and the section following the heading applies only to FDD.
- [TDD] This tagging of a word indicates that the word preceding the tag "[TDD]" applies only to TDD, including 3.84Mcps TDD, 7.68Mcps TDD and 1.28Mcps TDD. This tagging of a heading indicates that the heading preceding the tag "[TDD]" and the section following the heading applies only to TDD, including 3.84Mcps TDD, 7.68Mcps TDD and 1.28Mcps TDD.
- [3.84Mcps TDD] This tagging of a word indicates that the word preceding the tag "[3.84Mcps TDD]" applies only to 3.84Mcps TDD. This tagging of a heading indicates that the heading preceding the tag "[3.84Mcps TDD]" and the section following the heading applies only to 3.84Mcps TDD.
- [1.28Mcps TDD] This tagging of a word indicates that the word preceding the tag "[1.28Mcps TDD]" applies only to 1.28Mcps TDD. This tagging of a heading indicates that the heading preceding the tag "[1.28Mcps TDD]" and the section following the heading applies only to 1.28Mcps TDD.

[7.68Mcps TDD]	This tagging of a word indicates that the word preceding the tag "[7.68Mcps TDD]" applies only to 7.68Mcps TDD. This tagging of a heading indicates that the heading preceding the tag "[7.68Mcps TDD]" and the section following the heading applies only to 7.68Mcps TDD.
[FDD - ...]	This tagging indicates that the enclosed text following the "[FDD - " applies only to FDD. Multiple sequential paragraphs applying only to FDD are enclosed separately to enable insertion of TDD specific (or common) paragraphs between the FDD specific paragraphs.
[TDD - ...]	This tagging indicates that the enclosed text following the "[TDD - " applies only to TDD, including 7.68 Mcps TDD, 3.84Mcps TDD, 7.68Mcps TDD and 1.28Mcps TDD. Multiple sequential paragraphs applying only to TDD are enclosed separately to enable insertion of FDD specific (or common) paragraphs between the TDD specific paragraphs.
[3.84Mcps TDD - ...]	This tagging indicates that the enclosed text following the "[3.84Mcps TDD - " applies only to 3.84Mcps TDD. Multiple sequential paragraphs applying only to 3.84Mcps TDD are enclosed separately to enable insertion of FDD and TDD specific (or common) paragraphs between the 3.84Mcps TDD specific paragraphs.
[1.28Mcps TDD - ...]	This tagging indicates that the enclosed text following the "[1.28Mcps TDD - " applies only to 1.28Mcps TDD. Multiple sequential paragraphs applying only to 1.28Mcps TDD are enclosed separately to enable insertion of FDD and TDD specific (or common) paragraphs between the 1.28Mcps TDD specific paragraphs.
[7.68Mcps TDD - ...]	This tagging indicates that the enclosed text following the "[7.68Mcps TDD - " applies only to 7.68Mcps TDD. Multiple sequential paragraphs applying only to 7.68Mcps TDD are enclosed separately to enable insertion of FDD and TDD specific (or common) paragraphs between the 7.68Mcps TDD specific paragraphs.
Procedure	When referring to an elementary procedure in the specification the Procedure Name is written with the first letters in each word in upper case characters followed by the word "procedure", e.g. Position Calculation procedure.
Message	When referring to a message in the specification the MESSAGE NAME is written with all letters in upper case characters followed by the word "message", e.g. POSITION CALCULATION REQUEST message.
IE	When referring to an information element (IE) in the specification the <i>Information Element Name</i> is written with the first letters in each word in upper case characters and all letters in Italic font followed by the abbreviation "IE", e.g. <i>Request Type</i> IE.
Value of an IE	When referring to the value of an information element (IE) in the specification the "Value" is written as it is specified in clause 9.2 enclosed by quotation marks, e.g. "Abstract Syntax Error (Reject)" or "Geographical Coordinates".

5 PCAP Services

PCAP provides the signalling services between RNC and SAS that are required to fulfill the PCAP functions described in clause 7. PCAP services are categorized as follows:

1. Position Calculation Service: They are related to a single UE and involve the transfer of UE Positioning measurement data and UE position estimate data over the Iupc interface between the SRNC and the SAS. They utilise connectionless signalling transport provided by the Iupc signalling bearer.
2. Information Exchange Service: They involve the transfer of GPS or GANSS related data over the Iupc interface between the RNC and the SAS on demand, on modification, or at regular intervals. They utilise connection-oriented signalling transport provided by the Iupc signalling bearer.
3. SAS Centric Position Service: They are related to the capability of the SAS to determine the positioning method used for individual positioning events. In this case the SRNC may allow A-GPS, A-GANSS, OTDOA, Cell ID and U-TDOA positioning events for a single UE to be originated by the SAS via PCAP messages. They utilise connection-oriented signalling transport provided by the Iupc signalling bearer.

6 Services Expected from Signalling Transport

Signalling transport [3] shall provide the following service for the PCAP.

1. Connection oriented data transfer service. This service is supported by a signalling connection between the RNC and the SAS. It shall be possible to dynamically establish and release signalling connections based on the need. Each point-to-point operation shall have its own signalling connection. The signalling connection shall provide in sequence delivery of PCAP messages. PCAP shall be notified if the signalling connection breaks.
2. Connectionless data transfer service. PCAP shall be notified in case a PCAP message did not reach the intended peer PCAP entity.

7 Functions of PCAP

PCAP has the following functions:

- Position Calculation. This function enables the SRNC to interact with an SAS in the process of performing a position estimate of a UE.
- Information Exchange. This function enables the RNC to obtain GPS or GANSS related data from an SAS.
- Reporting of General Error Situations. This function allows reporting of general error situations for which function specific error messages have not been defined.
- SAS Centric Position. This function enables the SRNC to interact with an SAS in the process of performing a position estimate of a UE.

The mapping between the above functions and PCAP elementary procedures is shown in the table 1.

Table 1: Mapping between functions and PCAP elementary procedures

Function	Elementary Procedure(s)
Position Calculation	a) Position Calculation b) Position Parameter Modification c) Abort
Information Exchange	a) Information Exchange Initiation b) Information Reporting c) Information Exchange Termination d) Information Exchange Failure
Reporting of General Error Situations	a) Error Indication
SAS Centric Position	a) Position Initiation b) Position Activation c) Position Parameter Modification d) Abort e) Position Periodic Report f) Position Periodic Result g) Position Periodic Termination

8 PCAP Procedures

8.1 Elementary Procedures

In the following tables, all EPs are divided into class 1 and class 2 EPs (see clause 3.1 for explanation of the different classes).

Table 2: Class 1

Elementary Procedure	Initiating Message	Successful Outcome	Unsuccessful Outcome
		Response message	Response message
Position Calculation	POSITION CALCULATION REQUEST	POSITION CALCULATION RESPONSE	POSITION CALCULATION FAILURE
Information Exchange Initiation	INFORMATION EXCHANGE INITIATION REQUEST	INFORMATION EXCHANGE INITIATION RESPONSE	INFORMATION EXCHANGE INITIATION FAILURE
Position Initiation	POSITION INITIATION REQUEST	POSITION INITIATION RESPONSE	POSITION INITIATION FAILURE
Position Activation	POSITION ACTIVATION REQUEST	POSITION ACTIVATION RESPONSE	POSITION ACTIVATION FAILURE

Table 3: Class 2

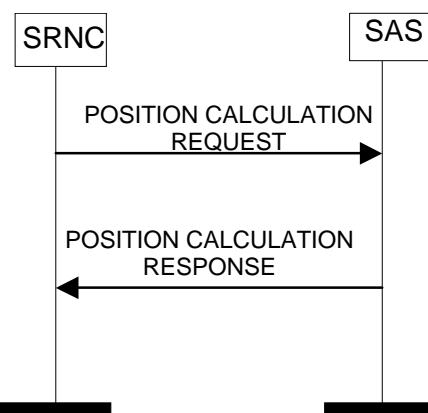
Elementary Procedure	Message
Information Reporting	INFORMATION REPORT
Information Exchange Termination	INFORMATION EXCHANGE TERMINATION REQUEST
Information Exchange Failure	INFORMATION EXCHANGE FAILURE INDICATION
Error Indication	ERROR INDICATION
Position Parameter Modification	POSITION PARAMETER MODIFICATION
Abort	ABORT
Position Periodic Report	POSITION PERIODIC REPORT
Position Periodic Result	POSITION PERIODIC RESULT
Position Periodic Termination	POSITION PERIODIC TERMINATION

8.2 Position Calculation

8.2.1 General

The purpose of the Position Calculation procedure is to enable an SRNC to query an SAS for a position estimate of a UE. The procedure uses connectionless signalling.

8.2.2 Successful Operation

**Figure 1: Position Calculation procedure, Successful Operation**

The procedure is initiated with a POSITION CALCULATION REQUEST message sent from the SRNC to the SAS. When the SAS receives the POSITION CALCULATION REQUEST message, it shall calculate the UE position and, if supported and requested, velocity based on the provided measurement data. This procedure may be repeated by the SRNC as needed for periodic location. If the POSITION CALCULATION REQUEST message is part of periodic location, this message may include the *Periodic Position Calculation Info* IE to enable the SAS to better fulfill future such requests.

If the *Initial UE Position Estimate* IE is included in the POSITION CALCULATION REQUEST message, the SAS shall use this value for the calculation of the UE Position Estimate in case of A-GPS or A-GANSS positioning methods are used. The SAS may use this value for the calculation of the UE Position when any other methods are used.

If the *Cell-ID Measured Results Sets* IE is included in the POSITION CALCULATION REQUEST message and both of the *Round Trip Time Info* IE and the *Round Trip Time Info With Type 1* IE are included in the *Cell-ID Measured Results Info List* IE, the SAS shall use the *Round Trip Time Info* IE.

If the *Horizontal Accuracy Code* IE and possibly the *Vertical Accuracy Code* IE are included in the POSITION CALCULATION REQUEST message, the SAS shall use these values in order to assess whether the resulting position estimation fulfills the requested accuracy.

If the *SAS Response Time* IE is included in the POSITION CALCULATION REQUEST message, the SAS shall send a POSITION CALCULATION RESPONSE message within the indicated time after reception of the POSITION CALCULATION REQUEST message.

If the *Include Velocity* IE is set to "requested" in the POSITION CALCULATION REQUEST message, the SAS shall include the *Velocity Estimate* IE, if available, in the POSITION CALCULATION RESPONSE message.

If a *GANSS Measured Results* IE is included in the POSITION CALCULATION REQUEST message and does not contain the *GANSS Time ID* IE, the SAS shall assume that the corresponding GANSS timing refers to the "Galileo" timing.

The *GANSS Measured Results* IE contains one or several *GANSS Generic Measurement Information* IEs, each of them associated with a given GANSS:

- If a *GANSS Generic Measurement Information* IE does not contain the *GANSS ID* IE, the SAS shall assume that the associated GANSS is "Galileo".
- If a *GANSS Generic Measurement Information* IE associated with a particular GANSS does not contain the *GANSS Signal ID* IE, the SAS shall assume the default value as defined in [4], clause 10.3.3.45a..
- If a *GANSS Generic Measurement Information* IE does not contain the *GANSS Code Phase Ambiguity* IE and the *GANSS Code Phase Ambiguity Extension* IE, the SAS shall assume the value "1" (ms).
- If the *GANSS Integer Code Phase* IE and the *GANSS Integer Code Phase Extension* IE associated to a given satellite (identified by the *Sat ID* IE value) is not present within the *GANSS Measurement Parameters* IE, the SAS shall use the default "1" (ms) for the GANSS Code Phase Ambiguity value in order to compute the value of the Total Code Phase (as defined in [4]) for the related satellite, whatever the value of the *GANSS Code Phase Ambiguity* IE.

Response Message:

If the SAS was able to calculate the position estimate, it shall respond with a POSITION CALCULATION RESPONSE message.

Whenever one of the geographic area shapes *Ellipsoid point with uncertainty Ellipse* IE, *Ellipsoid point with altitude and uncertainty Ellipsoid* IE or *Ellipsoid Arc* IE is reported, the *Confidence* IE shall indicate the probability that the UE is located within the uncertainty region of the shape. The value of the *Confidence* IE shall be in the interval of "1" to "100".

If at least the *Horizontal Accuracy Code* IE was included in the POSITION CALCULATION REQUEST message and the calculated position estimate fulfills the requested accuracy, the *Accuracy Fulfilment Indicator* IE with the value "requested accuracy fulfilled" shall be included in the POSITION CALCULATION RESPONSE message. If the calculated position estimate does not fulfil the requested accuracy, the *Accuracy Fulfilment Indicator* IE with the value "requested accuracy not fulfilled" shall be included in the POSITION CALCULATION RESPONSE message.

8.2.3 Unsuccessful Operation

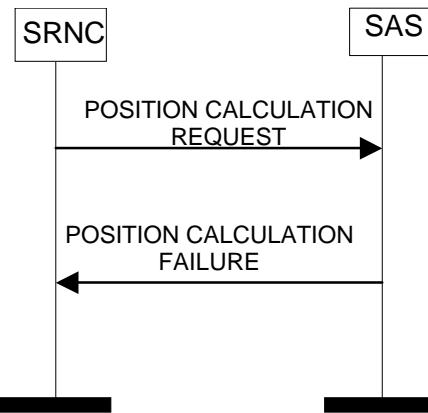


Figure 2: Position Calculation procedure, Unsuccessful Operation

If the SAS is unable to perform the position estimate for any reason, it shall return a POSITION CALCULATION FAILURE message to the SRNC.

Typical cause values are:

- Invalid reference information;
- Position calculation error: invalid GPS, Galileo, GLONASS or GANSS measured results;
- Initial UE Position Estimate missing;
- Processing Overload;
- Hardware Failure;
- O&M Intervention;
- Invalid U-TDOA measured results;
- U-TDOA positioning method not supported;
- U-TDOA positioning method not supported in specified UTRAN cell;
- SAS unable to perform U-TDOA positioning within Response Time.

8.2.4 Abnormal Conditions

If the *Vertical Accuracy Code* IE is included and the *Horizontal Accuracy Code* IE is not included in the POSITION CALCULATION REQUEST message, the SAS shall reject the procedure.

If the *RRC State* included in the *UTDOA Group* IE is indicated as being *CELL_DCH* in the POSITION CALCULATION REQUEST message and [FDD - neither the *DCH Information* IE nor the *E-DPCH Information* IE][TDD - no *DCH Information* IE] is included, the SAS shall reject the procedure using the POSITION CALCULATION FAILURE message.

If the *GPS Measured Results* IE is included in the POSITION CALCULATION REQUEST message but the *Initial UE Position Estimate* IE is not, the SAS shall return the POSITION CALCULATION FAILURE message to the SRNC.

If the *GANSS Measured Results* IE is included in the POSITION CALCULATION REQUEST message but the *Initial UE Position Estimate* IE is not, the SAS shall return the POSITION CALCULATION FAILURE message to the SRNC.

If neither of the *GPS Measurement Results* IE, the *Cell-ID Measured Results Sets* IE, the *OTDOA Measurement Group* IE nor the *GANSS Measured Results* IE is included in the POSITION CALCULATION REQUEST message, the SAS shall return the POSITION CALCULATION FAILURE message to the SRNC.

8.3 Information Exchange Initiation

8.3.1 General

This procedure is used by a RNC to request the initiation of an information exchange with a SAS.

This procedure uses the signalling bearer connection for the Information Exchange Context.

8.3.2 Successful Operation

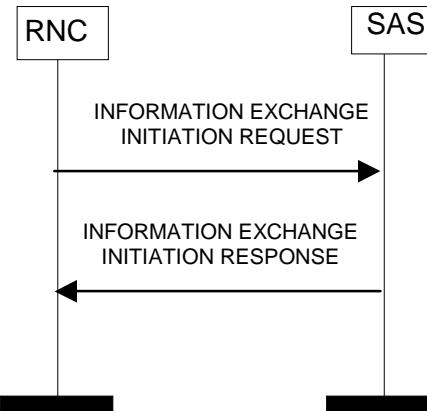


Figure 3: Information Exchange Initiation procedure, Successful Operation

The procedure is initiated with an INFORMATION EXCHANGE INITIATION REQUEST message sent from RNC to SAS.

If the *Information Type* IE is set to "Implicit", the SAS is responsible for selecting the type of assistance data.

Upon reception, the SAS shall provide the requested information according to the parameters given in the request. Unless specified below, the meaning of the parameters are given in other specifications.

If the *Information Exchange Object Type* IE is set to "Cell-ID Measured Results Sets" the SAS shall use the "Cell-ID Measured Results Info List" for obtaining an initial UE position estimate.

If the *GANSS-UTRAN Time Relationship Uncertainty* IE included in the INFORMATION EXCHANGE INITIATION REQUEST message does not contain the *GANSS ID* IE, the SAS shall assume that the *GANSS-UTRAN Time Relationship Uncertainty* IE is associated with "Galileo".

If the *Information Type* IE is set to "Explicit" and an *Explicit Information Item* IE is set to "GANSS Common Data", at least one of the GANSS Reference Time, GANSS Ionosphere Model, GANSS Reference Location, GANSS Additional Ionospheric Model, or GANSS Earth Orientation Parameters types shall be requested.

If the *Information Type* IE is set to "Explicit" and an *Explicit Information Item* IE is set to "GANSS Generic Data", at least one of the *GANSS Real Time Integrity*, *GANSS Data Bit Assistance*, *DGANSS Corrections*, *GANSS Almanac and Satellite Health*, *GANSS Reference Measurement Information*, *GANSS UTC Model*, *GANSS Time Model GNSS-GNSS*, *GANSS Navigation Model*, *GANSS Additional Navigation Models*, *GANSS Additional UTC Models*, or *GANSS Auxiliary Information* IEs shall be present in each *GANSS Generic Data Item* IE associated with a given GANSS.

- If the *GANSS Generic Data Item* IE does not contain the *GANSS ID* IE, the SAS shall assume that the corresponding GANSS is "Galileo".

Information Report Characteristics:

The *Information Report Characteristics* IE indicates how the reporting of the information shall be performed.

If the *Information Report Characteristics* IE is set to "On-Demand", the SAS shall report the requested information immediately.

If the *Information Report Characteristics* IE is set to "Periodic", the SAS shall report the requested information immediately and then shall periodically initiate the Information Reporting procedure for all the requested information, with the requested report frequency.

If the *Information Report Characteristics* IE is set to "On-Modification", the SAS shall report the requested information immediately if available. If the requested information is not available at the moment of receiving the INFORMATION EXCHANGE INITIATION REQUEST message, but expected to become available after some acquisition time, the SAS shall initiate the Information Reporting procedure when the requested information becomes available. The SAS shall then initiate the Information Reporting procedure in accordance to the following conditions:

- If the *Information Type* IE is set to "Explicit" and the *Explicit Information Item* IE includes "Almanac and Satellite Health", the SAS shall initiate the Information Reporting procedure for this specific Explicit Information Type when a change in the t_{oa} or WN_a parameter has occurred in almanac/health information for at least one visible satellite.
- If the *Information Type* IE is set to "Explicit" and the *Explicit Information Item* IE includes "UTC Model", the SAS shall initiate the Information Reporting procedure for this specific Explicit Information Type when a change in the t_{ot} or WN_t parameter has occurred in the GPS UTC model.
 - If the *Transmission TOW Indicator* IE is set to "requested", then the SAS shall include the *GPS Transmission TOW* IE in the INFORMATION REPORT message.
- If the *Information Type* IE is set to "Explicit" and the *Explicit Information Item* IE includes "Ionospheric Model", the SAS shall initiate the Information Reporting procedure for this specific Explicit Information Type when a change has occurred in the GPS ionospheric model.
 - If the *Transmission TOW Indicator* IE is set to "requested", then the SAS shall include the *GPS Transmission TOW* IE in the INFORMATION REPORT message.
- If the *Information Type* IE is set to "Explicit" and the *Explicit Information Item* IE includes "Navigation Model", the SAS shall initiate the Information Reporting procedure for this specific Explicit Information Type when a change has occurred in the clock/ephemeris information for at least one visible satellite or in the list of visible satellites.
 - If the *Transmission TOW Indicator* IE is set to "requested", then the SAS shall include the *GPS Transmission TOW* IE in the INFORMATION REPORT message.
- If the *Information Type* IE is set to "Explicit" and the *Explicit Information Item* IE includes "DGPS Corrections", the SAS shall initiate the Information Reporting procedure for this specific Explicit Information Type when a change has occurred in the quality of the DGPS corrections information for at least one visible satellite or in the list of visible satellites.
- If the *Information Type* IE is set to "Explicit" and the *Explicit Information Item* IE includes "Reference Time", the SAS shall initiate the Information Reporting procedure for this specific Explicit Information Type when a change has occurred in the time-of-week assistance information for at least one visible satellite or in the list of visible satellites.
- If the *Information Type* IE is set to "Explicit" and the *Explicit Information Item* IE includes "Acquisition Assistance", the SAS shall initiate the Information Reporting procedure for this specific Explicit Information Type when a change has occurred in acquisition assistance information for at least one visible satellite or in the list of visible satellites.
- If the *Information Type* IE is set to "Explicit" and the *Explicit Information Item* IE includes "Real Time Integrity", the SAS shall initiate the Information Reporting procedure for this specific Explicit Information Type when a change has occurred in the real-time integrity status of at least one visible satellite.
- If the *Information Type* IE is set to "Explicit" and the *Explicit Information Item* IE includes "Almanac and Satellite Health SIB", the SAS shall initiate the Information Reporting procedure for this specific Explicit Information Type when a change has occurred in almanac/health information for at least one visible satellite.
 - If the *Transmission TOW Indicator* IE is set to "requested", then the SAS shall include the *GPS Transmission TOW* IE in the INFORMATION REPORT message.
- If the *Information Type* IE is set to "Explicit" and the *Explicit Information Item* IE is set to "GANSS Generic Data" and includes the *GANSS Almanac and Satellite Health* IE, the SAS shall initiate the Information Reporting

procedure for this specific Explicit Information Type when a change in the T_{oa} , IOD_a , or Week Number parameter has occurred in almanac/health information for at least one visible satellite.

- If the *GANSS Time Indicator* IE is set to "requested", then the SAS shall include the *GANSS Reference Time* IE in the INFORMATION REPORT message.
- If the *Information Type* IE is set to "Explicit" and the *Explicit Information Item* IE is set to "GANSS Generic Data" and includes the *GANSS UTC Model* IE, the SAS shall initiate the Information Reporting procedure for this specific Explicit Information Type when a change in the t_{ot} or WN_t parameter has occurred in the GANSS UTC model.
 - If the *GANSS Time Indicator* IE is set to "requested", then the SAS shall include the *GANSS Reference Time* IE in the INFORMATION REPORT message.
- If the *Information Type* IE is set to "Explicit" and the *Explicit Information Item* IE is set to "GANSS Generic Data" and includes the *GANSS Additional UTC Models* IE, the SAS shall initiate the Information Reporting procedure for this specific Explicit Information Type when a change in the t_{ot} , WN_{ot} , WN_t , or N^A parameter has occurred in the GANSS Additional UTC model.
 - If the *GANSS Time Indicator* IE is set to "requested", then the SAS shall include the *GANSS Reference Time* IE in the INFORMATION REPORT message.
- If the *Information Type* IE is set to "Explicit" and the *Explicit Information Item* IE is set to "GANSS Common Data" and includes the *GANSS Ionosphere Model* IE, the SAS shall initiate the Information Reporting procedure for this specific Explicit Information Type when a change has occurred in the GANSS ionospheric model.
- If the *Information Type* IE is set to "Explicit" and the *Explicit Information Item* IE is set to "GANSS Common Data" and includes the *GANSS Additional Ionospheric Model* IE, the SAS shall initiate the Information Reporting procedure for this specific Explicit Information Type when a change has occurred in the GANSS additional ionospheric model.
 - If the *Data ID* IE is set to value "11", then the SAS shall include the *GANSS Additional Ionospheric Model* IE for the area as defined in [27]. If the *Data ID* IE is set to value "00", then the SAS shall include the *GANSS Additional Ionospheric Model* IE applicable worldwide as defined in [27].
- If the *Information Type* IE is set to "Explicit" and the *Explicit Information Item* IE is set to "GANSS Common Data" and includes the *GANSS Earth Orientation Parameters* IE, the SAS shall initiate the Information Reporting procedure for this specific Explicit Information Type when a change in the t_{EOP} parameter has occurred in the GANSS Earth Orientation Parameters.
- If the *Information Type* IE is set to "Explicit" and the *Explicit Information Item* IE is set to "GANSS Generic Data" and includes the *GANSS Navigation Model* IE, the SAS shall initiate the Information Reporting procedure for this specific Explicit Information Type when a change has occurred in the ephemeris information for at least one visible satellite or in the list of visible satellites.
- If the *Information Type* IE is set to "Explicit" and the *Explicit Information Item* IE is set to "GANSS Generic Data" and includes the *GANSS Additional Navigation Models* IE, the SAS shall initiate the Information Reporting procedure for this specific Explicit Information Type when a change has occurred in the ephemeris information for at least one visible satellite or in the list of visible satellites.
- If the *Information Type* IE is set to "Explicit" and the *Explicit Information Item* IE is set to "GANSS Generic Data" and includes the *GANSS Time Model GNSS-GNSS* IE, the SAS shall initiate the Information Reporting procedure for this specific Explicit Information Type when a change has occurred in the time information.
 - If the *GANSS Time Indicator* IE is set to "requested", then the SAS shall include the *GANSS Reference Time* IE in the INFORMATION REPORT message.
- If the *Information Type* IE is set to "Explicit" and the *Explicit Information Item* IE is set to "GANSS Generic Data" and includes the *DGANSS Corrections* IE, the SAS shall initiate the Information Reporting procedure for this specific Explicit Information Type when a change has occurred in the quality of the DGANSS corrections information for at least one visible satellite or in the list of visible satellites.
 - If the *GANSS Time Indicator* IE is set to "requested", then the SAS shall include the *GANSS Reference Time* IE in the INFORMATION REPORT message.

- If the *Information Type* IE is set to "Explicit" and the *Explicit Information Item* IE is set to "GANSS Common Data" and includes the *GANSS Reference Time* IE, the SAS shall initiate the Information Reporting procedure for this specific Explicit Information Type when a change has occurred in the time-of-week assistance information for at least one visible satellite or in the list of visible satellites.
- If the *Information Type* IE is set to "Explicit" and the *Explicit Information Item* IE is set to "GANSS Generic Data" and includes the *GANSS Reference Measurement Information* IE, the SAS shall initiate the Information Reporting procedure for this specific Explicit Information Type when a change has occurred in acquisition assistance information for at least one visible satellite or in the list of visible satellites.
 - If the *GANSS Time Indicator* IE is set to "requested", then the SAS shall include the *GANSS Reference Time* IE in the INFORMATION REPORT message.
- If the *Information Type* IE is set to "Explicit" and the *Explicit Information Item* IE is set to "GANSS Generic Data" and includes the *GANSS Real Time Integrity* IE, the SAS shall initiate the Information Reporting procedure for this specific Explicit Information Type when a change has occurred in the real-time integrity status of at least one visible satellite.
 - If the *GANSS Time Indicator* IE is set to "requested", then the SAS shall include the *GANSS Reference Time* IE in the INFORMATION REPORT message.
- If the *Information Type* IE is set to "Explicit" and the *Explicit Information Item* IE is set to "GANSS Generic Data" and includes the *GANSS Auxiliary Information* IE, the SAS shall initiate the Information Reporting procedure for this specific Explicit Information Type when a change in the *Signals Available* or *Channel Number* IEs has occurred in the GANSS Auxiliary Information.
 - If the *GANSS Time Indicator* IE is set to "requested", then the SAS shall include the *GANSS Reference Time* IE in the INFORMATION REPORT message.
- If any of the above *Information Type* IEs becomes temporarily unavailable, the SAS shall initiate the Information Reporting procedure for this specific Information Item by indicating "Information Not Available" in the *Requested Data Value Information* IE. If the Information becomes available again, the SAS shall initiate the Information Reporting procedure for this specific Information.

Response message:

If the SAS is able to determine the information requested by the RNC, it shall respond with the INFORMATION EXCHANGE INITIATION RESPONSE message. The message shall include the same Information Exchange ID that was included in the INFORMATION EXCHANGE INITIATION REQUEST message. When the *Report Characteristics* IE is set to "On Modification" or "Periodic", the INFORMATION EXCHANGE INITIATION RESPONSE message shall contain the *Requested Data Value* IE if the data are available. When the *Report Characteristics* IE is set to "On Demand", the INFORMATION EXCHANGE INITIATION RESPONSE message shall contain the *Requested Data Value* IE.

When the response message includes data to be reported (see above), the SAS shall include at least one IE in the *Requested Data Value* IE.

If the *Requested DataValue* IE contains the *GANSS Common Assistance Data* IE, at least one of the *GANSS Reference Time*, *GANSS Ionospheric Model*, *GANSS Reference Location*, *GANSS Additional Ionospheric Model*, or *GANSS Earth Orientation Parameters* IEs shall be present.

- If the *GANSS Reference Time* IE does not contain the *GANSS Time ID* IE, the corresponding GANSS timing refers to the "Galileo" timing.

Any *GANSS Generic Assistance Data* IE associated with a given GANSS included in the *Requested DataValue* IE shall contain at least one of the *GANSS Real Time Integrity*, *GANSS Data Bit Assistance*, *DGANSS Corrections*, *GANSS Almanac and Satellite Health*, *GANSS Reference Measurement Information*, *GANSS UTC Model*, *GANSS Time Model*, *GANSS Navigation Model*, *GANSS Additional Time Models*, *GANSS Additional Navigation Models*, *GANSS Additional UTC Models*, or *GANSS Auxiliary Information* IEs.

- If the *GANSS Generic Assistance Data* IE does not contain the *GANSS ID* IE, the corresponding GANSS is "Galileo".

- The *DGANSS Corrections* IE contains one or several *DGANSS Information* IE(s), each of them associated with a GANSS Signal. A *DGANSS Information* IE for a particular GANSS that does not contain the *GANSS Signal ID* IE is by default associated with the default signal defined in [4], clause 10.3.3.45a.
- The *GANSS Real Time Integrity* IE contains one or several *Satellite Information* IEs, each of them associated with a satellite and a GANSS Signal. A *Satellite Information* IE for a particular GANSS that does not contain the *Bad GANSS Signal ID* IE is by default associated with all the signals of the corresponding satellite (see [22, 23, 24, 25, 26, 27, 28]).
- The *GANSS Reference Measurement Information* IE is associated with a GANSS Signal. A *GANSS Reference Measurement Information* IE for a particular GANSS that does not contain the *GANSS Signal ID* IE is by default associated with the default signal defined in [4], clause 10.3.3.45a.

If the *Information Type* IE is set to "Explicit" and the *Explicit Information Item* IE is set to "GANSS Generic Data" and includes the *GANSS Time Model GNSS-GNSS* IE with exactly one bit set to value "1" in the *GNSS-GNSS Time ext* IE, the SAS shall include the *GANSS Time Model* IE in the *Requested Data Value* IE with the requested time information.

If the *Information Type* IE is set to "Explicit" and the *Explicit Information Item* IE is set to "GANSS Generic Data" and includes the *GANSS Time Model GNSS-GNSS* IE with more than one bit set to value "1" in the *GNSS-GNSS Time ext* IE, the SAS shall include the *GANSS Additional Time Models* IE in *Requested Data Value* IE with the requested time information for each GANSS.

8.3.3 Unsuccessful Operation

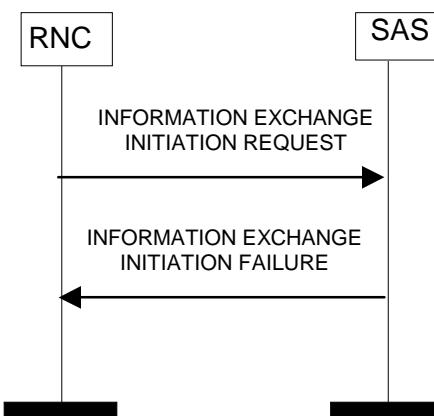


Figure 4: Information Exchange Initiation procedure, Unsuccessful Operation

If the requested Information Type received in the *Information Type* IE indicates a type of information that SAS cannot provide, the SAS shall regard the Information Exchange Initiation procedure as failed.

If the requested information provision cannot be carried out, the SAS shall send the INFORMATION EXCHANGE INITIATION FAILURE message. The message shall include the same Information Exchange ID that was used in the INFORMATION EXCHANGE INITIATION REQUEST message and the *Cause* IE set to an appropriate value.

Typical cause values are as follows:

- Information temporarily not available;
- Information Provision not supported for the object;
- Processing Overload;
- Hardware Failure;
- O&M Intervention.

8.3.4 Abnormal Conditions

If the *Information Exchange Object Type* IE is set to "Reference Position" and the *Information Type* IE set to "Explicit" and the *Explicit Information Item* IE is set to "Reference Location" or "GANSS Reference Location" the SAS shall

reject the Information Exchange Initiation procedure and shall send the INFORMATION EXCHANGE INITIATION FAILURE message.

The allowed combinations of the Information Type and Information Report Characteristics are shown in the table below marked with "X". For not allowed combinations, the SAS shall reject the Information Exchange Initiation procedure using the INFORMATION EXCHANGE INITIATION FAILURE message.

Table 3a: Allowed Information Type and Information Report Characteristics combinations

Type	Information Report Characteristics Type		
	On Demand	Periodic	On Modification
Almanac and Satellite Health	X	X	X
UTC Model	X	X	X
Ionospheric Model	X	X	X
Navigation Model	X	X	X
DGPS Corrections	X	X	X
Reference Time	X	X	X
Acquisition Assistance	X	X	X
Real Time Integrity	X	X	X
Almanac and Satellite Health SIB	X	X	X
Reference Location	X		
GANSS Reference Time	X	X	X
GANSS Ionosphere Model	X	X	X
GANSS Reference Location	X		
GANSS Additional Ionospheric Model	X	X	X
GANSS Earth Orientation Parameters	X	X	X
GANSS Real Time Integrity	X	X	X
GANSS Data Bit Assistance	X	X	
DGANSS Corrections	X	X	X
GANSS Almanac and Satellite Health	X	X	X
GANSS Reference Measurement Information	X	X	X
GANSS UTC Model	X	X	X
GANSS Time Model GNSS-GNSS	X	X	X
GANSS Navigation Model	X	X	X
GANSS Additional Navigation Models	X	X	X
GANSS Additional UTC Models	X	X	X
GANSS Auxiliary Information	X	X	X

8.4 Information Reporting

8.4.1 General

This procedure is used by a SAS to report the result of information requested by a RNC using the Information Exchange Initiation.

This procedure uses the signalling bearer connection for the Information Exchange Context.

8.4.2 Successful Operation

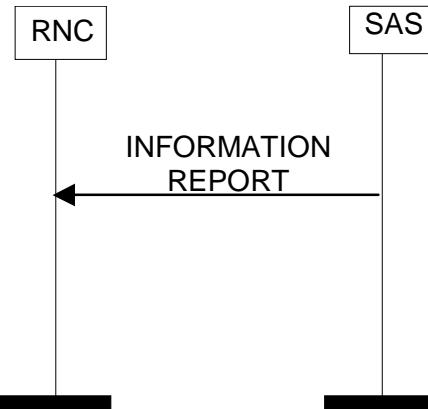


Figure 5: Information Reporting procedure, Successful Operation

If the requested information reporting criteria are met, the SAS shall initiate an Information Reporting procedure. Unless specified below, the meaning of the parameters are given in other specifications.

The *Information Exchange ID* IE shall be set to the Information Exchange ID provided by the RNC when initiating the information exchange with the Information Exchange Initiation procedure.

The *Requested Data Value* IE shall include at least one IE containing the data to be reported.

If the *Requested DataValue* IE contains the *GANSS Common Assistance Data* IE, at least one of the *GANSS Reference Time*, *GANSS Ionospheric Model*, *GANSS Reference Location*, *GANSS Additional Ionospheric Model*, or *GANSS Earth Orientation Parameters* IEs shall be present.

Any *GANSS Generic Assistance Data* IE associated with a given GANSS included in the *Requested DataValue* IE shall contain at least one of the *GANSS Real Time Integrity*, *GANSS Data Bit Assistance*, *DGANSS Corrections*, *GANSS Almanac and Satellite Health*, *GANSS Reference Measurement Information*, *GANSS UTC Model*, *GANSS Time Model*, *GANSS Navigation Model*, *GANSS Additional Time Models*, *GANSS Additional Navigation Models*, *GANSS Additional UTC Models*, or *GANSS Auxiliary Information* IEs.

- If the *GANSS Generic Assistance Data* IE does not contain the *GANSS ID* IE, the corresponding GANSS is "Galileo".
- The *DGANSS Corrections* IE contains one or several *DGANSS Information* IE(s), each of them associated with a GANSS Signal. A *DGANSS Information* IE for a particular GANSS that does not contain the *GANSS Signal ID* IE is by default associated with the default signal defined in [4], clause 10.3.3.45a.
- The *GANSS Real Time Integrity* IE contains one or several *Satellite Information* IEs, each of them associated with a satellite and a GANSS Signal. A *Satellite Information* IE for a particular GANSS that does not contain the *Bad GANSS Signal ID* IE is by default associated with all the signals of the corresponding satellite (see [22, 23, 24, 25, 26, 27, 28]).
- The *GANSS Reference Measurement Information* IE is associated with a GANSS Signal. A *GANSS Reference Measurement Information* IE for a particular GANSS that does not contain the *GANSS Signal ID* IE is by default associated with the default signal defined in [4], clause 10.3.3.45a.

If the *Information Type* IE is set to "Explicit" and the *Explicit Information Item* IE is set to "GANSS Generic Data" and includes the *GANSS Time Model GNSS-GNSS* IE with exactly one bit set to value "1" in the *GNSS-GNSS Time ext* IE, the SAS shall include the *GANSS Time Model* IE in the *Requested Data Value* IE with the requested time information.

If the *Information Type* IE is set to "Explicit" and the *Explicit Information Item* IE is set to "GANSS Generic Data" and includes the *GANSS Time Model GNSS-GNSS* IE with more than one bit set to value "1" in the *GNSS-GNSS Time ext* IE, the SAS shall include the *GANSS Additional Time Models* IE in *Requested Data Value* IE with the requested time information for each GANSS.

8.4.3 Abnormal Conditions

8.5 Information Exchange Termination

8.5.1 General

This procedure is used by a RNC to terminate the information exchange requested using the Information Exchange Initiation.

This procedure uses the signalling bearer connection for the Information Exchange Context.

8.5.2 Successful Operation

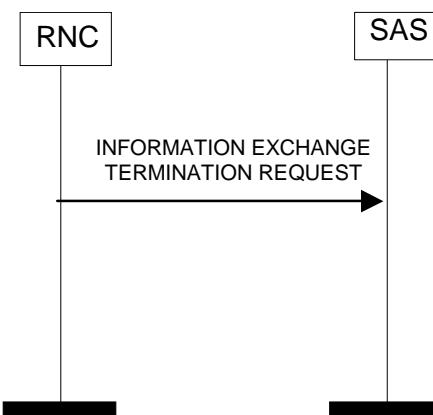


Figure 6: Information Exchange Termination procedure, Successful Operation

This procedure is initiated with an INFORMATION EXCHANGE TERMINATION REQUEST message.

Upon reception, the SAS shall terminate the information exchange corresponding to the Information Exchange ID.

8.5.3 Abnormal Conditions

8.6 Information Exchange Failure

8.6.1 General

This procedure is used by a SAS to notify a RNC that the information exchange it previously requested using the Information Exchange Initiation can no longer be reported.

This procedure uses the signalling bearer connection for the Information Exchange Context.

8.6.2 Successful Operation

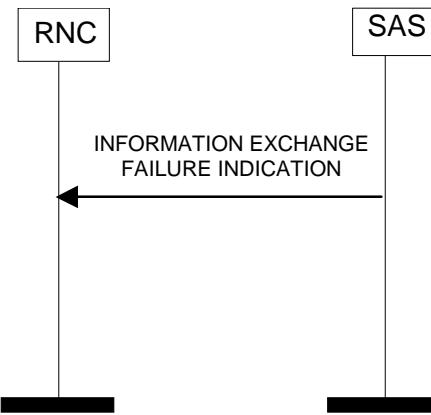


Figure 7: Information Exchange Failure procedure, Successful Operation

This procedure is initiated with a INFORMATION EXCHANGE FAILURE INDICATION message, sent from the SAS to the RNC, to inform the RNC that information previously requested by the Information Exchange Initiation procedure can no longer be reported. The message shall include the same Information Exchange ID that was used in the INFORMATION EXCHANGE INITIATION REQUEST message and the *Cause* IE set to an appropriate value.

Typical cause values are as follows:

- Information temporarily not available.

8.7 Error Indication

8.7.1 General

The Error Indication procedure is used by a node to report detected errors in one incoming message, provided they cannot be reported by an appropriate failure message.

8.7.2 Successful Operation

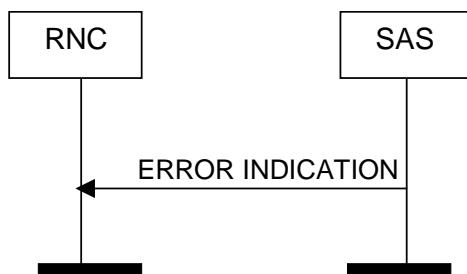


Figure 8: Error Indication procedure, SAS Originated, Successful Operation

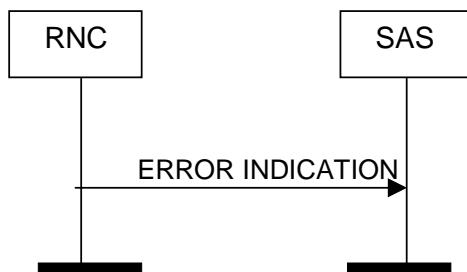


Figure 9: Error Indication procedure, RNC Originated, Successful Operation

When the conditions defined in clause 10 are fulfilled, the Error Indication procedure is initiated by an ERROR INDICATION message sent from the receiving node. This message shall use the same mode of the signalling bearer and the same signalling bearer connection (if connection oriented) as the message that triggers the procedure.

The ERROR INDICATION message shall include either the *Cause* IE, or the *Criticality Diagnostics* IE, or both the *Cause* IE and the *Criticality Diagnostics* IE.

Typical cause values are as follows:

- Transfer Syntax Error;
- Abstract Syntax Error (Reject);
- Abstract Syntax Error (Ignore and Notify);
- Message not Compatible with Receiver State;
- Unspecified.

8.7.3 Abnormal Conditions

8.8 Position Initiation

8.8.1 General

This procedure is used by an SRNC to request from an SAS the position (non-periodic or periodic) of a UE using the SAS centric mode of operation.

The connection-oriented service of the signalling bearer shall be established in conjunction with this procedure.

8.8.2 Successful Operation

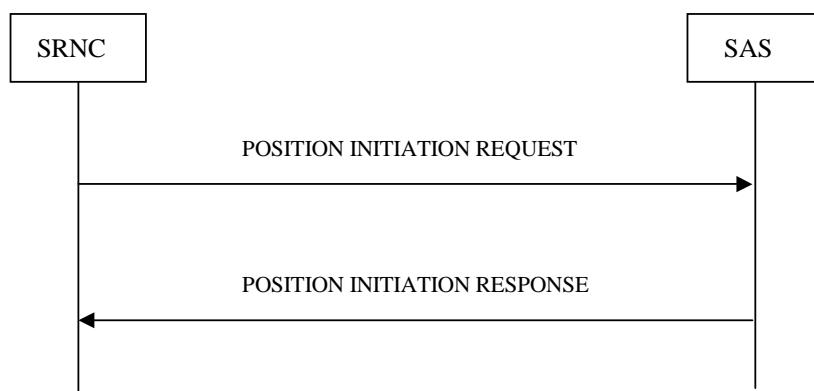


Figure 9a: Position Initiation procedure, Successful Operation

This procedure is initiated with a POSITION INITIATION REQUEST message sent from the SRNC to the SAS and ends with a POSITION INITIATION RESPONSE message from the SAS to the SRNC.

The POSITION INITIATION REQUEST message may contain one or several *Network Assisted GANSS Support* IE(s), each of them indicating the UE position capability with regard to GANSS.

- If a *Network Assisted GANSS Support* IE does not contain the *GANSS ID* IE, the SAS shall assume that the corresponding GANSS is "Galileo".

- If a *Network Assisted GANSS Support* IE corresponding to a particular GANSS does not contain the *GANSS Signal ID* IE and the *GANSS Signal IDs* IE, the SAS shall assume that the corresponding GANSS Signal is the default signal defined in [4], clause 10.3.3.45a.

Response Message:

If the POSITION INITIATION REQUEST message contains a request for direct reporting, and following completion of one or more positioning attempts, possibly using multiple positioning methods, the SAS shall pass the UE position to the SRNC in a POSITION INITIATION RESPONSE message.

If the POSITION INITIATION REQUEST message contains a request for periodic reporting, the SAS shall pass the final UE position to the SRNC in a POSITION INITIATION RESPONSE message.

Whenever one of the geographic area shapes *Ellipsoid point with uncertainty Ellipse* IE, *Ellipsoid point with altitude and uncertainty Ellipsoid* IE or *Ellipsoid Arc* IE is reported, the *Confidence* IE shall indicate the probability that the UE is located within the uncertainty region of the shape. The value of the *Confidence* IE shall be in the interval of "1" to "100".

If at least the *Horizontal Accuracy Code* IE was included in the POSITION INITIATION REQUEST message and the calculated position estimate fulfills the requested accuracy, the *Accuracy Fulfilment Indicator* IE with the value "requested accuracy fulfilled" shall be included in the POSITION INITIATION RESPONSE message. If the calculated position estimate does not fulfil the requested accuracy, the *Accuracy Fulfilment Indicator* IE with the value "requested accuracy not fulfilled" shall be included in the POSITION INITIATION RESPONSE message.

8.8.3 Unsuccessful Operation

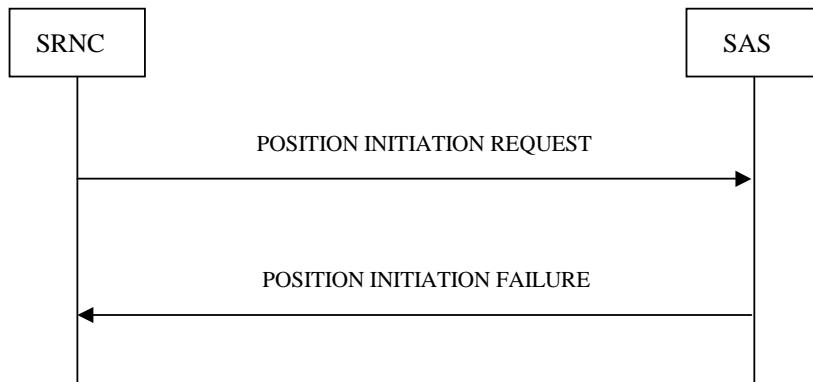


Figure 9b: Position Initiation procedure, Unsuccessful Operation

When the SAS is unable to accept a POSITION INITIATION REQUEST message or the SAS cannot provide a position estimate in case of direct reporting, the POSITION INITIATION FAILURE message shall be sent to the SRNC.

Typical cause values are:

- Processing Overload;
- Hardware Failure;
- O&M Intervention;
- Information temporarily not available.

8.8.4 Abnormal Conditions

If the *Vertical Accuracy Code* IE is included and the *Horizontal Accuracy Code* IE is not included in the POSITION INITIATION REQUEST message, the SAS shall reject the procedure.

8.9 Position Activation

8.9.1 General

The purpose of the Position Activation procedure is to enable the SAS to initiate a particular positioning method used for an individual positioning event. This procedure uses connection-oriented signalling.

8.9.2 Successful Operation

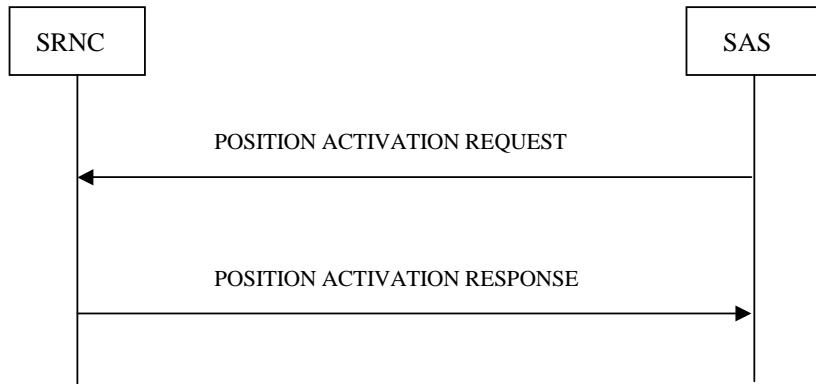


Figure 9c: Position Activation procedure, Successful Operation

The SAS initiates this procedure by sending a POSITION ACTIVATION REQUEST message to the SRNC containing the required positioning method and any assistance data and instructions associated with that positioning method. The SRNC then sends a POSITION ACTIVATION RESPONSE message to the SAS confirming the requested action and providing any information required by the requested positioning method; e.g. UE channel information for the U-TDOA positioning method or A-GPS measurements for UE assisted A-GPS. In the POSITION ACTIVATION RESPONSE message, the SRNC should include either the *UE Position Estimate Info IE*, *GPS Measurement Results IE*, *Cell-ID Measured Results Sets IE*, *OTDOA Measured Results Sets IE*, *UTDOA Group IE*, *GANSS Measurement Results IE*, *Required GPS Assistance Data IE* or *Required GANSS Assistance Data IE*.

If the *Positioning Method IE* in a POSITION ACTIVATION REQUEST message includes the *GNSS Positioning Method IE* indicating allowance of 'GPS' and any other GNSS ('Galileo', 'SBAS', 'Modernized GPS', 'QZSS', 'GLONASS'), the SRNC may include both, the *GPS Measurement Results IE* and the *GANSS Measurement Results IE*, or both, the *Required GPS Assistance Data IE* or *Required GANSS Assistance Data IE* in the POSITION ACTIVATION RESPONSE message.

If the POSITION ACTIVATION REQUEST message contains periodic reporting information to start a periodic RNC positioning procedure (i.e., *Amount of Reporting IE* is included), the POSITION ACTIVATION RESPONSE message may be returned confirming the requested action and not including any measurements. In that case, all periodic measurement reports are conveyed using POSITION PERIODIC REPORT messages.

If the *GPS Positioning Instructions IE* or the *GANSS Positioning Instructions IE* is included in a POSITION ACTIVATION REQUEST message containing the *Measurement Validity IE*, the SRNC should include the *Measurement Instructions Used IE* in a POSITION ACTIVATION RESPONSE message if the Measurement Validity used by the SRNC is different from the Measurement Validity requested by the SAS.

If the POSITION ACTIVATION REQUEST message contains the *Position Method IE* with value "Cell ID", the *Amount of Reporting IE* shall not be included.

If the POSITION ACTIVATION REQUEST message contains the *Position Method IE* with value "Cell ID", the RNC may include the measurements requested in the *Requested Cell-ID Measurements IE* in the POSITION ACTIVATION RESPONSE message. If both of the *Round Trip Time Info IE* and the *Round Trip Time Info With Type 1 IE* are included in the POSITION ACTIVATION RESPONSE message, the SAS shall use the *Round Trip Time Info IE*.

If the SRNC receives a new POSITION ACTIVATION REQUEST message before it has responded to a previous non-periodic request, the SRNC should terminate all activity for the previous request, without sending any response to the initial request, and process the new request.

If the SRNC receives a new POSITION ACTIVATION REQUEST message for UE position measurement reporting using A-GPS or A-GANSS or OTDOA (periodic or non-periodic) while it is still performing activity for a previous A-GPS or A-GANSS or OTDOA periodic request, the SRNC should terminate all activity for the previous request, including terminating the periodic measurement reporting in the UE, and should process the new request.

If the SRNC receives a new POSITION ACTIVATION REQUEST message for Cell-ID or U-TDOA positioning while it is still performing activity for a previous A-GPS or A-GANSS or OTDOA periodic request (but after returning any POSITION ACTIVATION RESPONSE for this request), the SRNC may both continue with the previous request and process the new request.

If the *GANSS Positioning* IE is included in the POSITION ACTIVATION REQUEST message and contains the *Requested Data Value* IE:

- If the *GANSS Generic Assistance Data* IE, associated with a given GANSS, is included in the *Requested DataValue* IE, it shall contain a *GANSS Real Time Integrity*, *GANSS Data Bit Assistance*, *DGANSS Corrections*, *GANSS Almanac and Satellite Health*, *GANSS Reference Measurement Information*, *GANSS UTC Model*, *GANSS Time Model*, *GANSS Navigation Model*, *GANSS Additional Time Models*, *GANSS Additional Navigation Models*, *GANSS Additional UTC Models*, or *GANSS Auxiliary Information* IE.
- If the *GANSS Generic Assistance Data* IE does not contain the *GANSS ID* IE, the corresponding GANSS is "Galileo".
- The *DGANSS Corrections* IE contains one or several *DGANSS Information* IE(s), each of them associated with a GANSS Signal. A *DGANSS Information* IE for a particular GANSS that does not contain the *GANSS Signal ID* IE is by default associated with the default signal defined in [4], clause 10.3.3.45a.
- The *GANSS Real Time Integrity* IE contains one or several *Satellite Information* IEs, each of them associated with a satellite and a GANSS Signal. A *Satellite Information* IE for a particular GANSS that does not contain the *Bad GANSS Signal ID* IE is by default associated with all the signals of the corresponding satellite (see [22, 23, 24, 25, 26, 27, 28]).
- The *GANSS Reference Measurement Information* IE is associated with a GANSS Signal. A *GANSS Reference Measurement Information* IE for a particular GANSS that does not contain the *GANSS Signal ID* IE is by default associated with the default signal defined in [4], clause 10.3.3.45a.

If the RRC State included in the *UTDOA Group* IE is indicated as being *CELL_DCH* in the POSITION ACTIVATION RESPONSE message, [FDD - either the *DCH Information* IE or the *E-DPCH Information* IE][TDD - the *DCH Information* IE] should be included.

If the *GANSS Measured Results* IE is included in the POSITION ACTIVATION RESPONSE message and does not contain the *GANSS Time ID* IE, the SAS shall assume that the corresponding GANSS timing refers to the "Galileo" timing.

The *GANSS Measured Results* IE contains one or several *GANSS Generic Measurement Information* IEs, each of them associated with a given GANSS:

- If a *GANSS Generic Measurement Information* IE does not contain the *GANSS ID* IE, the SAS shall assume that the associated GANSS is "Galileo".
- If a *GANSS Generic Measurement Information* IE associated with a particular GANSS does not contain the *GANSS Signal ID* IE, the SAS shall assume the default value as defined in [4], clause 10.3.3.45a.
- If a *GANSS Generic Measurement Information* IE does not contain the *GANSS Code Phase Ambiguity* IE and the *GANSS Code Phase Extension* IE, the SAS shall assume the value "1" (ms).
- If the *GANSS Integer Code Phase* IE and the *GANSS Integer Code Phase Extension* IE associated to a given satellite (identified by the *Sat ID* IE value) is not present within the *GANSS Measurement Parameters* IE, the SAS shall use the default "1" (ms) for the GANSS Code Phase Ambiguity value in order to compute the value of the Total Code Phase (as defined in [4]) for the related satellite, whatever the value of the *GANSS Code Phase Ambiguity* IE.

8.9.3 Unsuccessful Operation

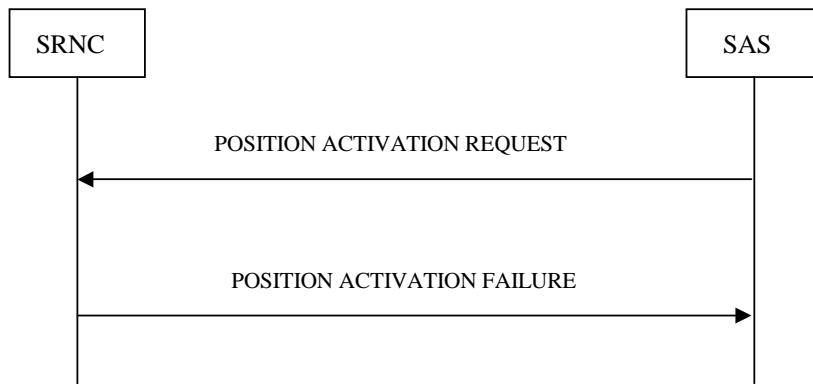


Figure 9d: Position Activation procedure, Unsuccessful Operation

When the SRNC is unable to accept a POSITION ACTIVATION REQUEST message, the POSITION ACTIVATION FAILURE message should be sent to the SAS.

Typical cause values are:

- Processing Overload;
- Hardware Failure;
- O&M Intervention;
- Positioning Method Not Supported;
- Location Measurement Failure.

8.9.4 Abnormal Conditions

8.10 Position Parameter Modification

8.10.1 General

The purpose of the Position Parameter Modification procedure is to inform the SAS of any relevant changes to the RF connection or other changes during a positioning event. This procedure uses connectionless signalling when invoked in RNC centric mode and connection-oriented signalling when invoked in SAS centric mode.

8.10.2 Successful Operation



Figure 9e: Position Parameter Modification procedure, Successful Operation

If the SAS receives a POSITION PARAMETER MODIFICATION message, the SAS shall apply the information to the ongoing position estimate (e.g. reconfigure LMUs for U-TDOA) or to a new positioning attempt (e.g. use new serving cell to provide A-GPS assistance data). If there is more than one signalling connection for a UE, the SRNC should send the POSITION PARAMETER MODIFICATION message on each connection. When operating in the RNC centric mode the *Transaction ID* IE should be used to associate the POSITION PARAMETER MODIFICATION message to the correct positioning event.

In the POSITION PARAMETER MODIFICATION message, only one of the *UTRAN Cell Identifier* IE or the *UTDOA GROUP* IE should be included.

The SRNC should send a POSITION PARAMETER MODIFICATION message if an RRC measurement procedure for periodic UE positioning measurement reporting in the UE has been activated by the SRNC upon reception of a POSITION ACTIVATION REQUEST message, and if there is a RRC state transition during the RRC measurement procedure, which does not result in a termination of the UE measurement reporting. The SRNC should continue to notify the SAS of such RRC state changes until the periodic position measurement reporting has been completed or terminated.

8.10.3 Abnormal Conditions

8.11 Abort

8.11.1 General

The purpose of the Abort procedure is to inform the SAS that the RNC is unable to continue the current positioning activity for a particular UE. This procedure uses connectionless signalling when invoked in RNC centric mode and connection-oriented signalling when invoked in SAS centric mode.

8.11.2 Successful Operation

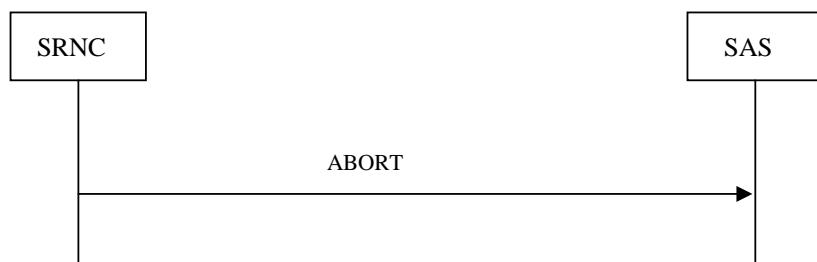


Figure 9f: Abort procedure, Successful Operation

The SRNC should send an ABORT message when the SRNC is unable to continue positioning activity due to cell reselection that results in a different SRNC, loss of contact with the UE or any other reason. When operating in the RNC centric mode the *Transaction ID* IE should be used to associate the ABORT message to the correct positioning event.

If the SAS receives an ABORT message while in the SAS centric mode it should immediately cease positioning attempts and return a POSITION INITIATION RESPONSE message to the SRNC carrying any location estimate already obtained or a POSITION INITIATION FAILURE message if no location estimate was obtained.

If the SAS receives an ABORT message while in the RNC centric mode it should immediately cease positioning attempts and return a POSITION CALCULATION RESPONSE message to the SRNC carrying any location estimate already obtained or a POSITION CALCULATION FAILURE message if no location estimate was obtained. After sending an ABORT message the SRNC should cease positioning activity, if any.

Typical cause values are:

- Processing Overload;
- Hardware Failure;
- O&M Intervention;
- Loss of contact with the UE.

8.11.3 Abnormal Conditions

8.12 Position Periodic Report

8.12.1 General

The purpose of the Position Periodic Report procedure is to send measurement information or UE position estimate from the SRNC to the SAS for periodic location in SAS-centric mode. This procedure uses connection-oriented signalling.

8.12.2 Successful Operation

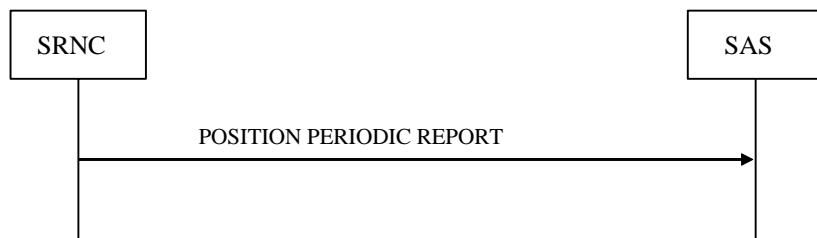


Figure 9g: Position Periodic Report procedure, Successful Operation

This procedure is initiated with a POSITION PERIODIC REPORT message sent from the SRNC to the SAS. The POSITION PERIODIC REPORT message provides the SAS measurement information such as GPS or OTDOA measurements, or an indication of measurement failure.

The SRNC should send the first POSITION PERIODIC REPORT message one reporting interval after the POSITION ACTIVATION RESPONSE message, and should continue to send further POSITION PERIODIC REPORT messages one reporting interval after the previous POSITION PERIODIC REPORT message based on the available measurements. If the RNC can not deliver measurement information when a POSITION PERIODIC REPORT is triggered, the *Cause* IE should be included in the POSITION PERIODIC REPORT message, indicating the reason for measurement failure, e.g. "UE Positioning Error: Not enough OTDOA cells", "UE Positioning Error: Not enough GPS

"Satellites", "UE Positioning Error: Not Accomplished GPS Timing of Cell Frames" or "UE Positioning Error: Undefined Error". If the *Cause* IE is included in a POSITION PERIODIC REPORT message, the *UE Position Estimate Info* IE, *Velocity Estimate* IE, *GPS Measurement Results* IE, *GANSS Measurement Results* IE, *Cell-ID Measured Results Sets* IE, and *OTDOA Measured Results Sets* IE should not be included. If and only if the *Cause* IE indicates the error reason "UE Positioning Error: Assistance Data Missing" the SRNC may include the *Required GPS Assistance Data* IE and/or the *Required GANSS Assistance Data* IE in the POSITION PERIODIC REPORT message.

If the *Cell-ID Measured Results Sets* IE is included in the POSITION PERIODIC REPORT message and both of the *Round Trip Time Info* IE and the *Round Trip Time Info With Type 1* IE are included in the *Cell-ID Measured Results Info List* IE, the SAS shall use the *Round Trip Time Info* IE.

If the *GANSS Measured Results* IE is included in the POSITION PERIODIC REPORT message and does not contain the *GANSS Time ID* IE, the SAS shall assume that the corresponding GANSS timing refers to the "Galileo" timing.

The *GANSS Measured Results* IE contains one or several *GANSS Generic Measurement Information* IEs, each of them associated with a given GANSS:

- If a *GANSS Generic Measurement Information* IE does not contain the *GANSS ID* IE, the SAS shall assume that the associated GANSS is "Galileo".
- If a *GANSS Generic Measurement Information* IE associated with a particular GANSS does not contain the *GANSS Signal ID* IE, the SAS shall assume the default value as defined in [4], clause 10.3.3.45a.
- If a *GANSS Generic Measurement Information* IE does not contain the *GANSS Code Phase Ambiguity* IE and the *GANSS Code Phase Ambiguity Extension* IE, the SAS shall assume the value "1" (ms).
- If the *GANSS Integer Code Phase* IE and the *GANSS Integer Code Phase Extension* IE associated to a given satellite (identified by the *Sat ID* IE value) is not present within the *GANSS Measurement Parameters* IE, the SAS shall use the default "1" (ms) for the GANSS Code Phase Ambiguity value in order to compute the value of the Total Code Phase (as defined in [4]) for the related satellite, whatever the value of the *GANSS Code Phase Ambiguity* IE.

8.12.3 Abnormal Conditions

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8.13 Position Periodic Result

8.13.1 General

The purpose of the Position Periodic Result procedure is to provide UE position estimates from the SAS to the SRNC for periodic location in SAS-centric mode. This procedure uses connection-oriented signalling.

8.13.2 Successful Operation

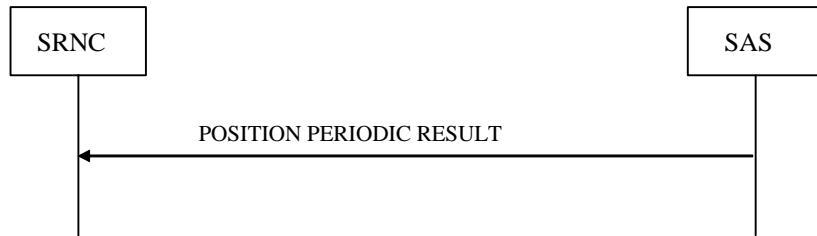


Figure 9h: Position Periodic Result procedure, Successful Operation

This procedure is initiated with a POSITION PERIODIC RESULT message sent from the SAS to the SRNC. The POSITION PERIODIC RESULT message conveys the UE position estimate (or an indication of positioning failure) from the SAS to the SRNC.

The SAS shall send a POSITION PERIODIC RESULT message one reporting interval after the previous POSITION PERIODIC RESULT message. If the SAS can not deliver measurement information when a POSITION PERIODIC RESULT is triggered, the *Cause* IE shall be included in the POSITION PERIODIC RESULT message, indicating the reason for measurement failure, e.g. "Position Calculation error: invalid GPS measured results", "Position Calculation error: invalid Cell-ID measured results", "Position Calculation error: invalid OTDOA measured results" or "Position Calculation error: invalid U-TDOA measured results". If the *Cause* IE is included in a POSITION PERIODIC RESULT message, the *UE Position Estimate* IE, *Velocity Estimate* IE, *Position Data* IE, and *Accuracy Fulfilment Indicator* IE shall not be included.

If the *UE Position Estimate* IE is included in a POSITION PERIODIC RESULT message, the *Position Data* IE shall also be included.

Whenever one of the geographic area shapes *Ellipsoid point with uncertainty Ellipse* IE, *Ellipsoid point with altitude and uncertainty Ellipsoid* IE or *Ellipsoid Arc* IE is reported, the *Confidence* IE shall indicate the probability that the UE is located within the uncertainty region of the shape. The value of the *Confidence* IE shall be in the interval of "1" to "100".

If at least the *Horizontal Accuracy Code* IE was included in a POSITION INITIATION REQUEST message which initiates periodic position reporting, and the periodic position estimate included in a POSITION PERIODIC RESULT messages fulfils the requested accuracy, the *Accuracy Fulfilment Indicator* IE with the value "requested accuracy fulfilled" shall be included. If the calculated position estimate does not fulfil the requested accuracy, the *Accuracy Fulfilment Indicator* IE with the value "requested accuracy not fulfilled" shall be included in the POSITION PERIODIC RESULT message.

8.13.3 Abnormal Conditions

8.14 Position Periodic Termination

8.14.1 General

The Position Periodic Termination procedure is used by a node to request termination of an ongoing periodic location, or to inform a node about termination of periodic location in SAS-centric mode. This procedure uses connection-oriented signalling.

8.14.2 Successful Operation

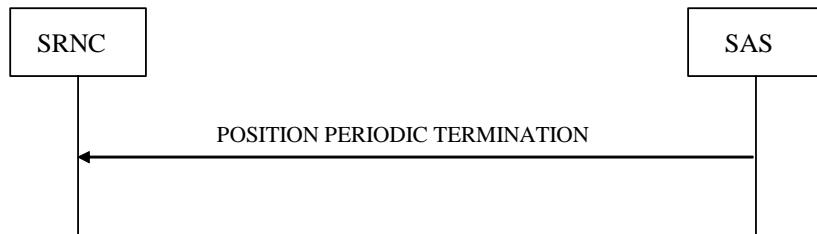


Figure 9i: Position Periodic Termination procedure, SAS Originated, Successful Operation

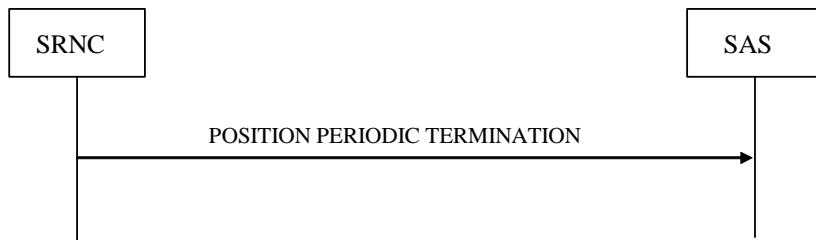


Figure 9k: Position Periodic Termination procedure, RNC Originated, Successful Operation

When the SAS or SRNC needs to terminate ongoing periodic location, a POSITION PERIODIC TERMINATION message is sent to the receiving node.

If an RRC measurement procedure for periodic UE positioning measurement reporting in the UE has been activated by the SRNC upon reception of a POSITION ACTIVATION REQUEST message, and if the SRNC receives a POSITION PERIODIC TERMINATION message, the SRNC should terminate the periodic UE positioning measurement reporting in the UE.

The SRNC should send a POSITION PERIODIC TERMINATION message if an RRC measurement procedure for periodic UE positioning measurement reporting in the UE has been activated by the SRNC upon reception of a POSITION ACTIVATION REQUEST message, and if the SRNC or UE terminates the measurement reporting (e.g., after RRC state transition).

8.14.3 Abnormal Conditions

9 Elements for PCAP Communication

9.1 Message Functional Definition and Content

9.1.1 General

Clause 9.1 presents the contents of PCAP messages in tabular format. The corresponding ASN.1 definitions are presented in clause 9.3. In case there is contradiction between the tabular format in clause 9.1 and the ASN.1 definition, the ASN.1 shall take precedence, except for the definition of conditions for the presence of conditional IEs, where the tabular format shall take precedence.

NOTE: The messages have been defined in accordance to the guidelines specified in [12].

9.1.2 Message Contents

9.1.2.1 Presence

All information elements in the message descriptions below are marked mandatory, optional or conditional according to table 4.

Table 4: Meaning of abbreviations used in PCAP messages

Abbreviation	Meaning
M	IEs marked as Mandatory (M) shall always be included in the message.
O	IEs marked as Optional (O) may or may not be included in the message.
C	IEs marked as Conditional (C) shall be included in a message only if the condition is satisfied. Otherwise the IE shall not be included.

9.1.2.2 Criticality

Each Information Element or Group of Information Elements may have a criticality information applied to it. Following cases are possible.

Table 5: Meaning of content within "Criticality" column

Abbreviation	Meaning
—	No criticality information is applied explicitly.
YES	Criticality information is applied. This is usable only for non-repeatable IEs
GLOBAL	The IE and all its repetitions together have one common criticality information. This is usable only for repeatable IEs.
EACH	Each repetition of the IE has its own criticality information. It is not allowed to assign different criticality values to the repetitions. This is usable only for repeatable IEs.

9.1.2.3 Range

The Range column indicates the allowed number of copies of repetitive IEs/IE groups.

9.1.2.4 Assigned Criticality

This column provides the actual criticality information as defined in clause 10.3.2, if applicable.

9.1.3 POSITION CALCULATION REQUEST

Table 6

IE/Group Name	Presence	Range	IE type and reference	Semantics description	Criticality	Assigned Criticality
Message Type	M		9.2.2.24		YES	reject
Transaction ID	M		9.2.2.28		–	
Initial UE Position Estimate	O		Geographical Area 9.2.2.6		YES	reject
GPS Measured Results		0..<maxNoOfSets>			GLOBAL	reject
>GPS Measured Results	M		9.2.2.12		–	
Cell-ID Measured Results Sets		0..<maxNoOfMeasurements>			GLOBAL	reject
>Cell-ID Measured Results Info List	M		9.2.2.31		–	
OTDOA Measurement Group		0..1			YES	reject
>OTDOA Reference Cell Info	M		9.2.2.34		–	
>OTDOA Neighbour Cell Info List		1..<maxNoOfMeasNCell>			–	
>>OTDOA Neighbour Cell Info	M		9.2.2.33		–	
>OTDOA Measured Results Sets		1..<maxNoOfMeasurements>			–	
>>OTDOA Measured Results Info List	M		9.2.2.32		–	
Horizontal Accuracy Code	O		9.2.2.38		YES	ignore
Vertical Accuracy Code	O		9.2.2.39		YES	ignore
UTDOA Group	O		9.2.2.74		YES	reject
SAS Response Time	O		Positioning Response Time 9.2.2.69	Indicates the interval allowed for a SAS response for U-TDOA positioning.	YES	ignore
Include Velocity	O		9.2.2.97		YES	ignore
Periodic Position Calculation Info	O		9.2.2.106		YES	ignore
GANSS Measured Results		0..<maxNoOfSets>			GLOBAL	reject
>GANSS Measured Results	M		9.2.2.117		–	

Table 7

Range bound	Explanation
maxNoOfMeasNCell	Maximum number of neighbouring cells on which information can be reported. The value of maxNoOfMeasCell is 32.
maxNoOfSets	Maximum number of sets of Measured Results included in the Position Calculation Request message. The value for maxNoOfSets is 3.
maxNoOfMeasurements	Maximum number of Measurements of Cell-ID Measured Results Info List and OTDOA Measured Results Info List included in the Position Calculation Request message. The value for maxNoOfMeasurements is 16.

9.1.4 POSITION CALCULATION RESPONSE

Table 8

IE/Group Name	Presence	Range	IE type and reference	Semantics description	Criticality	Assigned Criticality
Message Type	M		9.2.2.24		YES	reject
Transaction ID	M		9.2.2.28		–	
UE Position Estimate	M		Geographical Area 9.2.2.6		YES	ignore
Criticality Diagnostics	O		9.2.2.4		YES	ignore
Accuracy Fulfilment Indicator	O		9.2.2.40		YES	ignore
Velocity Estimate	O		9.2.2.98		YES	ignore

9.1.5 POSITION CALCULATION FAILURE

Table 9

IE/Group Name	Presence	Range	IE type and reference	Semantics description	Criticality	Assigned Criticality
Message Type	M		9.2.2.24		YES	reject
Transaction ID	M		9.2.2.28		–	
Cause	M		9.2.2.3		YES	ignore
Criticality Diagnostics	O		9.2.2.4		YES	ignore

9.1.6 INFORMATION EXCHANGE INITIATION REQUEST

Table 10

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description	Criticality	Assigned Criticality
Message Type	M		9.2.2.24		YES	reject
Transaction ID	M		9.2.2.28		—	
Information Exchange ID	M		9.2.2.19		YES	reject
CHOICE Information Exchange Object Type	M				YES	reject
>Reference Position					—	
>>Reference Position Estimate/UE Initial Position	M		Geographical Area 9.2.2.6	For RNC-centric mode.	—	
>>>Additional Information Exchange Object Types						
>>>Reference Position UC-ID						
>>>UTRAN Cell Identifier/UE Initial Position	M		UTRAN Cell Identifier 9.2.2.37	For SAS-centric mode.	—	
>>>Cell-ID Measured Results Sets		0..<max NoOfMeasurements>			GLOBAL	ignore
>>>Cell-ID Measured Results Info List	M		9.2.2.31	For SAS-centric mode.	—	
Information Type	M		9.2.2.22		YES	reject
Information Report Characteristics	M		9.2.2.21		YES	reject
GPS-UTRAN Time Relationship Uncertainty	C-GPS		9.2.2.18		YES	reject
GANSS-UTRAN Time Relationship Uncertainty	C-GANSS		9.2.2.121		YES	reject

Table 11

Condition	Explanation
GPS	The IE shall be present if the information requested in the <i>Information Type</i> IE contains GPS-related data
GANSS	The IE shall be present if the information requested in the <i>Information Type</i> IE contains GANSS-related data

Table 11a

Range bound	Explanation
maxNoOfMeasurements	Maximum number of Measurements of Cell-ID Measured Results Sets. The value for maxNoOfMeasurements is 16.

9.1.7 INFORMATION EXCHANGE INITIATION RESPONSE

Table 12

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description	Criticality	Assigned Criticality
Message Type	M		9.2.2.24		YES	reject
Transaction ID	M		9.2.2.28		–	
Information Exchange ID	M		9.2.2.19		YES	ignore
CHOICE <i>Information Exchange Object Type</i>	O				YES	ignore
> <i>Reference Position</i>					–	
>>Requested Data Value	M		9.2.2.26		–	
Criticality Diagnostics	O		9.2.2.4		YES	ignore

9.1.8 INFORMATION EXCHANGE INITIATION FAILURE

Table 13

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description	Criticality	Assigned Criticality
Message Type	M		9.2.2.24		YES	reject
Transaction ID	M		9.2.2.28		–	
Information Exchange ID	M		9.2.2.19		YES	ignore
Cause	M		9.2.2.3		YES	ignore
Criticality Diagnostics	O		9.2.2.4		YES	ignore

9.1.9 INFORMATION REPORT

Table 14

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description	Criticality	Assigned Criticality
Message Type	M		9.2.2.24		YES	ignore
Transaction ID	M		9.2.2.28		–	
Information Exchange ID	M		9.2.2.19		YES	ignore
CHOICE <i>Information Exchange Object Type</i>	M				YES	ignore
> <i>Reference Position</i>					–	
>>Requested Data Value Information	M		9.2.2.27		–	

9.1.10 INFORMATION EXCHANGE TERMINATION REQUEST

Table 15

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description	Criticality	Assigned Criticality
Message Type	M		9.2.2.24		YES	ignore
Transaction ID	M		9.2.2.28		–	
Information Exchange ID	M		9.2.2.19		YES	ignore

9.1.11 INFORMATION EXCHANGE FAILURE INDICATION

Table 16

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description	Criticality	Assigned Criticality
Message Type	M		9.2.2.24		YES	ignore
Transaction ID	M		9.2.2.28		–	
Information Exchange ID	M		9.2.2.19		YES	ignore
Cause	M		9.2.2.3		YES	ignore

9.1.12 ERROR INDICATION

Table 17

IE/Group Name	Presence	Range	IE type and reference	Semantics description	Criticality	Assigned Criticality
Message Type	M		9.2.2.24		YES	ignore
Transaction ID	M		9.2.2.28		–	
Cause	O		9.2.2.3		YES	ignore
Criticality Diagnostics	O		9.2.2.4		YES	ignore

9.1.13 POSITION INITIATION REQUEST

Table 17a

IE/Group Name	Presence	Range	IE type and reference	Semantics description	Criticality	Assigned Criticality
Message Type	M		9.2.2.24		YES	reject
Transaction ID	M		9.2.2.28		–	
Request Type	M		9.2.2.50		YES	reject
UE Positioning Capability	M		9.2.2.51		YES	reject
UTRAN Cell Identifier	M		9.2.2.37		YES	reject
Vertical Accuracy Code	O		9.2.2.39		YES	ignore
Response Time	O		9.2.2.52		YES	ignore
Positioning Priority	O		9.2.2.53		YES	ignore
Client Type	O		9.2.2.54		YES	ignore
Include Velocity	O		9.2.2.97		YES	ignore
Periodic Location Info	O		9.2.2.107		YES	ignore

9.1.14 POSITION INITIATION RESPONSE

Table 17b

IE/Group Name	Presence	Range	IE type and reference	Semantics description	Criticality	Assigned Criticality
Message Type	M		9.2.2.24		YES	reject
Transaction ID	M		9.2.2.28		–	
UE Position Estimate	M		Geographical Area 9.2.2.6		YES	reject
Position Data	M		9.2.2.65		YES	ignore
Accuracy Fulfilment Indicator	O		9.2.2.40		YES	ignore
Velocity Estimate	O		9.2.2.98		YES	ignore

9.1.15 POSITION INITIATION FAILURE

Table 17c

IE/Group Name	Presence	Range	IE type and reference	Semantics description	Criticality	Assigned Criticality
Message Type	M		9.2.2.24		YES	reject
Transaction ID	M		9.2.2.28		–	
Cause	M		9.2.2.3		YES	ignore
Criticality Diagnostics	O		9.2.2.4		YES	ignore

9.1.16 POSITION ACTIVATION REQUEST

Table 17d

IE/Group Name	Presence	Range	IE type and reference	Semantics description	Criticality	Assigned Criticality
Message Type	M		9.2.2.24		YES	reject
Transaction ID	M		9.2.2.28		–	
Positioning Method	M		9.2.2.55		YES	reject
RNC Response Time	M		Positioning Response Time 9.2.2.69	Indicates the interval allowed for a RNC response, or the periodic reporting interval if <i>Amount of Reporting IE</i> is present.	YES	ignore
Positioning Priority	O		9.2.2.53		YES	ignore
Environment Characterisation	O		9.2.2.62		YES	ignore
U-TDOA Positioning		0..1		Only present if Positioning Method is U-TDOA	YES	reject
>U-TDOA Bit Count	M		9.2.2.56	Used if UE is in CELL_FACH mode	–	
>U-TDOA Time Interval	M		9.2.2.57	Used if UE is in CELL_FACH mode	–	
GPS Positioning		0..1		Only present if Positioning Method is A-GPS	YES	reject
>GPS Positioning Instructions	M		9.2.2.101		–	
>Requested Data Value	O		9.2.2.26		–	
OTDOA Assistance Data		0..1		Only present if Positioning Method is OTDOA	YES	reject
>UE Positioning OTDOA Assistance data	M		9.2.2.59		–	
Include Velocity	O		9.2.2.97		YES	ignore
Amount of Reporting	O		9.2.2.108	Amount of reports for periodic reporting.	YES	ignore
Cell-ID Positioning		0..1		Only present if Positioning Method is Cell-ID	YES	ignore
>Requested Cell-ID Measurements	M		9.2.2.112		–	
GNSS Positioning		0..1		Only present if Positioning Method is GNSS	YES	reject
>GNSS Positioning Instructions	M		9.2.2.120		–	

>Requested Data Value	O		9.2.2.26		-	
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9.1.17 POSITION ACTIVATION RESPONSE

Table 17e

IE/Group Name	Presence	Range	IE type and reference	Semantics description	Criticality	Assigned Criticality
Message Type	M		9.2.2.24		YES	reject
Transaction ID	M		9.2.2.28		-	
UE Position Estimate Info	O		9.2.2.102	Position information for UE based positioning methods	YES	ignore
GPS Measured Results		<i>0..<maxNoOfSets></i>			GLOBAL	reject
>GPS Measured Results	M		9.2.2.12		-	
Cell-ID Measured Results Sets		<i>0..<maxNoOfMeasurements></i>			GLOBAL	reject
>Cell-ID Measured Results Info List	M		9.2.2.31		-	
OTDOA Measured Results Sets		<i>0..<maxNoOfMeasurements></i>			GLOBAL	reject
>OTDOA Measured Results Info List	M		9.2.2.32		-	
UTDOA Group	O		9.2.2.74		YES	reject
Velocity Estimate	O		9.2.2.98		YES	ignore
Measurement Instructions Used	O		9.2.2.109		YES	ignore
GANSS Measured Results		<i>0..<maxNoOfSets></i>			GLOBAL	reject
>GANSS Measured Results	M		9.2.2.117		-	
Required GPS Assistance Data	O		Additional GPS Assistance Data Required 9.2.2.128		YES	ignore
Required GANSS Assistance Data	O		Additional GANSS Assistance Data Required 9.2.2.129		YES	ignore

Table 17f

Range bound	Explanation
maxNoOfSets	Maximum number of sets of Measured Results included in the Position Activation Response message. The value for maxNoOfSets is 3.
maxNoOfMeasurements	Maximum number of Measurements of Cell-ID Measured Results Info List and OTDOA Measured Results Info List included in the Position Activation Response message. The value for maxNoOfMeasurements is 16.

9.1.18 POSITION ACTIVATION FAILURE

Table 17g

IE/Group Name	Presence	Range	IE type and reference	Semantics description	Criticality	Assigned Criticality
Message Type	M		9.2.2.24		YES	reject
Transaction ID	M		9.2.2.28		–	
Cause	M		9.2.2.3		YES	ignore
Criticality Diagnostics	O		9.2.2.4		YES	ignore

9.1.19 POSITION PARAMETER MODIFICATION

Table 17h

IE/Group Name	Presence	Range	IE type and reference	Semantics description	Criticality	Assigned Criticality
Message Type	M		9.2.2.24		YES	ignore
Transaction ID	M		9.2.2.28		–	
UTRAN Cell Identifier	O		9.2.2.37		YES	reject
UTDOA Group	O		9.2.2.74		YES	reject
RRC State Change	O		9.2.2.110		YES	ignore

9.1.20 ABORT

Table 17i

IE/Group Name	Presence	Range	IE type and reference	Semantics description	Criticality	Assigned Criticality
Message Type	M		9.2.2.24		YES	ignore
Transaction ID	M		9.2.2.28		–	
Cause	M		9.2.2.3		YES	ignore

9.1.21 POSITION PERIODIC REPORT

Table 17.k

IE/Group Name	Presence	Range	IE type and reference	Semantics description	Criticality	Assigned Criticality
Message Type	M		9.2.2.24		YES	ignore
Transaction ID	M		9.2.2.28		–	
UE Position Estimate Info	O		9.2.2.102		YES	ignore
Velocity Estimate	O		9.2.2.98		YES	ignore
GPS Measured Results		<i>0..<maxNoOfSets></i>			GLOBAL	ignore
>GPS Measured Results	M		9.2.2.12		–	
Cell-ID Measured Results Sets		<i>0..<maxNoOfMeasurements></i>			GLOBAL	ignore
>Cell-ID Measured Results Info List	M		9.2.2.31		–	
OTDOA Measured Results Sets		<i>0..<maxNoOfMeasurements></i>			GLOBAL	ignore
>OTDOA Measured Results Info List	M		9.2.2.32		–	
Cause	O		9.2.2.3		YES	ignore
GANSS Measured Results		<i>0..<maxNoOfSets></i>			GLOBAL	ignore
>GANSS Measured Results	M		9.2.2.117		–	
Required GPS Assistance Data	O		Additional GPS Assistance Data Required 9.2.2.128		YES	ignore
Required GANSS Assistance Data	O		Additional GANSS Assistance Data Required 9.2.2.129		YES	ignore

Table 17.I

Range bound	Explanation
maxNoOfSets	Maximum number of sets of Measured Results included in the Position Periodic Report message. The value for maxNoOfSets is 3.
maxNoOfMeasurements	Maximum number of Measurements of Cell-ID Measured Results Info List and OTDOA Measured Results Info List included in the Position Periodic Report message. The value for maxNoOfMeasurements is 16.

9.1.22 POSITION PERIODIC RESULT

Table 17.m

IE/Group Name	Presence	Range	IE type and reference	Semantics description	Criticality	Assigned Criticality
Message Type	M		9.2.2.24		YES	ignore
Transaction ID	M		9.2.2.28		–	
UE Position Estimate	O		Geographical Area 9.2.2.6		YES	ignore
Velocity Estimate	O		9.2.2.98		YES	ignore
Position Data	O		9.2.2.65		YES	ignore
Accuracy Fulfilment Indicator	O		9.2.2.40		YES	ignore
Cause	O		9.2.2.3		YES	ignore

9.1.23 POSITION PERIODIC TERMINATION

Table 17.n

IE/Group Name	Presence	Range	IE type and reference	Semantics description	Criticality	Assigned Criticality
Message Type	M		9.2.2.24		YES	ignore
Transaction ID	M		9.2.2.28		–	
Periodic Position Termination Cause	O		9.2.2.111		YES	ignore

9.2 Information Element Functional Definitions and Contents

9.2.1 General

Clause 9.2 presents the PCAP IE definitions in tabular format. The corresponding ASN.1 definitions are presented in clause 9.3. In case there is contradiction between the tabular format in clause 9.2 and the ASN.1 definition, the ASN.1 shall take precedence, except for the definition of conditions for the presence of conditional elements, where the tabular format shall take precedence.

When specifying information elements which are to be represented by bitstrings, if not otherwise specifically stated in the semantics description of the concerned IE or elsewhere, the following principle applies with regards to the ordering of bits:

- The first bit (leftmost bit) contains the most significant bit (MSB);
- The last bit (rightmost bit) contains the least significant bit (LSB);
- When importing bitstrings from other specifications, the first bit of the bitstring contains the first bit of the concerned information;

9.2.2 Radio Network Layer Related IEs

9.2.2.1 Almanac and Satellite Health SIB

Table 18

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
GPS Almanac and Satellite Health	M		9.2.2.9	
SatMask	M		BIT STRING(1..32)	indicates the satellites that contain the pages being broadcast in this data set
LSB TOW	M		BIT STRING (8)	

9.2.2.2 Altitude and direction

Table 19

IE/Group Name	Presence	Range	IE type and reference	Semantics description
Direction of Altitude	M		ENUMERATED (Height, Depth)	
Altitude	M		INTEGER (0.. 2^{15} -1)	The relation between the value (N) and the altitude (a) in meters it describes is $N \leq a < N+1$, except for $N=2^{15}-1$ for which the range is extended to include all greater values of (a).

9.2.2.3 Cause

The purpose of the cause information element is to indicate the reason for a particular event for the whole protocol.

Table 20

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
CHOICE Cause Group				
>Radio Network Layer				
>>Radio Network Layer Cause	M		ENUMERATED (invalid reference information, information temporarily not available, information provision not supported for the object, position calculation error: invalid GPS measured results, ... position calculation error: invalid Cell- ID measured results, position calculation error: invalid OTDOA measured results, position calculation error: A-GPS positioning method not supported, position calculation error: Cell-ID positioning method not supported, position calculation error: OTDOA positioning method not supported, Initial UE Position Estimate missing, position calculation error: invalid U- TDOA measured results, position calculation error: U-TDOA positioning method not supported, position calculation error: U-TDOA positioning method not supported in specified UTRAN cell, positioning method not supported, loss of contact with UE, SAS unable to perform U-TDOA positioning within Response Time, Location measurement failure, UE Positioning Error: Not enough OTDOA cells, UE Positioning Error: Not enough GPS Satellites, UE Positioning Error: Reference Cell not serving cell, UE Positioning Error: Not Accomplished GPS Timing of Cell Frames, UE Positioning Error: Undefined Error, position calculation error: invalid Galileo measured results, position calculation error: A-Galileo positioning method not supported, UE Positioning Error: Not enough Galileo Satellites, UE Positioning Error: Not Accomplished Galileo Timing of Cell Frames, UE Positioning Error: Assistance Data Missing position calculation error: invalid GLONASS measured results, position calculation error: invalid GANSS measured results, position calculation error: A-GANSS positioning method not supported, UE Positioning Error: Not enough GANSS Satellites, UE Positioning Error: Not Accomplished GANSS Timing of Cell Frames)	
>Transport Layer				
>>Transport Layer Cause	M		ENUMERATED (Transport Resource Unavailable, Unspecified, ...)	
>Protocol				

>>Protocol Cause	M		ENUMERATED (Transfer Syntax Error, Abstract Syntax Error (Reject), Abstract Syntax Error (Ignore and Notify), Message not Compatible with Receiver State, Semantic Error, Unspecified, Abstract Syntax Error (Falsey Constructed Message), ...)	
>Misc				
>>Misc Cause	M		ENUMERATED (Processing Overload, Hardware Failure, O&M Intervention, Unspecified, ...)	

The meaning of the different cause values is described in the following table. In general, "not supported" cause values indicate that the concerning capability is missing. On the other hand, "not available" cause values indicate that the concerning capability is present, but insufficient resources were available to perform the requested action.

Table 21

Radio Network Layer cause	Meaning
Invalid reference information	The reference information (GPS-UTRAN Time Relationship Uncertainty and/or Initial UE Position Estimate) provided by the RNC are invalid
Information temporarily not available	The information requested by RNC is temporarily not available
Information Provision not supported for the object	The SAS does not support provision of the requested information for the concerned object types
Position calculation error: invalid GPS measured results	The SAS cannot calculate position due to invalid GPS measured results
Position calculation error: invalid Cell-ID measured results	The SAS cannot calculate position due to invalid Cell-ID measured results
Position calculation error: invalid OTDOA measured results	The SAS cannot calculate position due to invalid OTDOA measured results
Position calculation error: A-GPS positioning method not supported	The SAS cannot calculate position because it does not support the A-GPS positioning method
Position calculation error: Cell-ID positioning method not supported	The SAS cannot calculate position because it does not support the Cell-ID positioning method
Position calculation error: OTDOA positioning method not supported	The SAS cannot calculate position because it does not support the OTDOA positioning method
Position calculation error: invalid U-TDOA measured results	The SAS cannot calculate position due to invalid U-TDOA measured results
Position calculation error: U-TDOA positioning method not supported	The SAS cannot calculate position because it does not support the U-TDOA positioning method
Position calculation error: U-TDOA positioning method not supported in specified UTRAN cell	The SAS cannot calculate position because it does not support the U-TDOA positioning method in the specified UTRAN cell
Positioning method not supported	The RNC does not support the requested positioning method
Loss of contact with UE	The RNC reports that it has lost contact with the UE
SAS unable to perform U-TDOA positioning within Response Time	The SAS did not send a U-TDOA position estimate within the interval defined by the Response Time IE
Location measurement failure	The SRNC cannot deliver the requested positioning measurement due to measurement failure.
UE Positioning Error: Not enough OTDOA cells	The SRNC cannot deliver the requested positioning measurement due to UE positioning error reported by the UE with error reason "Not enough OTDOA cells".
UE Positioning Error: Not enough GPS Satellites	The SRNC cannot deliver the requested positioning measurement due to UE positioning error reported by the UE with error reason "Not enough GPS Satellites".
UE Positioning Error: Reference Cell not serving cell	The SRNC cannot deliver the requested positioning measurement due to UE positioning error reported by the UE with error reason "Reference Cell not serving cell"
UE Positioning Error: Not Accomplished GPS Timing of Cell Frames	The SRNC cannot deliver the requested positioning measurement due to UE positioning error reported by the UE with error reason "Not Accomplished GPS Timing of Cell Frames"
UE Positioning Error: Undefined Error	The SRNC cannot deliver the requested positioning measurement due to UE positioning error reported by the UE with error reason "Undefined Error"
Position calculation error: invalid Galileo measured results	The SAS cannot calculate position due to invalid Galileo measured results
Position calculation error: A-Galileo positioning method not supported	The SAS cannot calculate position because it does not support the A-Galileo positioning method
UE Positioning Error: Not enough Galileo Satellites	The SRNC cannot deliver the requested positioning measurement due to UE positioning error reported by the UE with error reason "Not enough Galileo Satellites".
UE Positioning Error: Not Accomplished Galileo Timing of Cell Frames	The SRNC cannot deliver the requested positioning measurement due to UE positioning error reported by the UE with error reason "Not Accomplished Galileo Timing of Cell Frames"
UE Positioning Error: Assistance Data Missing	The SRNC cannot deliver the requested positioning measurement due to UE positioning error reported by the UE with error reason "Assistance Data Missing"
Position calculation error: invalid GLONASS measured results	The SAS cannot calculate position due to invalid GLONASS measured results
Position calculation error: invalid GANSS measured results	The SAS cannot calculate position due to invalid GANSS measured results

Position calculation error: A-GANSS positioning method not supported	The SAS cannot calculate position because it does not support any A-GANSS positioning method
UE Positioning Error: Not enough GANSS Satellites	The SRNC cannot deliver the requested positioning measurement due to UE positioning error reported by the UE with error reason "Not Enough GANSS Satellites".
UE Positioning Error: Not Accomplished GANSS Timing of Cell Frames	The SRNC cannot deliver the requested positioning measurement due to UE positioning error reported by the UE with error reason "Not Accomplished GANSS Timing of Cell Frames"

Table 22

Transport Network Layer cause	Meaning
Transport resource unavailable	The required transport resources are not available
Unspecified	Sent when none of the above cause values applies but still the cause is Transport Network Layer related

Table 23

Protocol cause	Meaning
Abstract Syntax Error (Reject)	The received message included an abstract syntax error and the concerning criticality indicated "reject" (see clause 10.3)
Abstract Syntax Error (Ignore and Notify)	The received message included an abstract syntax error and the concerning criticality indicated "ignore and notify" (see clause 10.3)
Abstract syntax error (falsely constructed message)	The received message contained IEs or IE groups in wrong order or with too many occurrences (see clause 10.3)
Message not Compatible with Receiver State	The received message was not compatible with the receiver state (see clause 10.4)
Semantic Error	The received message included a semantic error (see clause 10.4)
Transfer Syntax Error	The received message included a transfer syntax error (see clause 10.2)
Unspecified	Sent when none of the above cause values applies but still the cause is Protocol related

Table 24

Miscellaneous cause	Meaning
Processing Overload	RNC/SAS processing overload
Hardware Failure	RNC/SAS hardware failure
O&M Intervention	Operation and Maintenance intervention related to RNC/SAS equipment
Unspecified	Sent when none of the above cause values applies and the cause is not related to any of the categories Radio Network Layer, Transport Network Layer or Protocol

9.2.2.4 Criticality Diagnostics

The *Criticality Diagnostics* IE is sent by the RNC or the SAS when parts of a received message have not been comprehended or are missing. It contains information about which IE was not comprehended or is missing.

For further details on how to use the *Criticality Diagnostics* IE, see annex A.

Table 25

IE/Group Name	Presence	Range	IE type and reference	Semantics description
Procedure Code	O		INTEGER (0..255)	
Triggering Message	O		ENUMERATED (initiating message, successful outcome, unsuccessful outcome, outcome)	The Triggering Message is used only if the Criticality Diagnostics is part of Error Indication.
Procedure Criticality	O		ENUMERATED (reject, ignore, notify)	This Procedure Criticality is used for reporting the Criticality of the Triggering message (Procedure).
Transaction ID	O		9.2.2.28	
Information Element Criticality Diagnostics		0..<maxnoof errors>		
>IE Criticality	M		ENUMERATED (reject, ignore, notify)	The IE Criticality is used for reporting the criticality of the triggering IE. The value "Ignore" shall never be used.
>IE Id	M		INTEGER (0..65535)	The IE Id of the not understood or missing IE as defined in the ASN.1 part of the specification.
>Repetition Number	O		INTEGER (0..255)	<p>The <i>Repetition Number</i> IE gives</p> <ul style="list-style-type: none"> - in case of a not understood IE: The number of occurrences of the reported IE up to and including the not understood occurrence - in case of a missing IE: The number of occurrences up to but not including the missing occurrence. <p>Note: All the counted occurrences of the reported IE must have the same top-down hierarchical message structure of IEs with assigned criticality above them.</p>
>Message Structure	O		9.2.2.23	The <i>Message Structure</i> IE describes the structure where the not understood or missing IE was detected. This IE is included if the not understood IE is not the top level of the message.
>Type of Error	M		ENUMERATED(not understood, missing, ...)	

Table 26

Range bound	Explanation
maxnooferrors	Maximum number of IE errors allowed to be reported with a single message. The value for maxnooferrors is 256.

9.2.2.5 DGPS Corrections

This IE contains DGPS corrections, which may be employed to compensate for ranging errors due to atmospheric delay, orbital modelling, and satellite clock drift.

Table 27

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
GPS TOW sec	M		INTEGER (0..604799)	In seconds GPS time-of-week when the DGPS corrections were calculated
Status/Health	M		ENUMERATED (UDRE scale 1.0, UDRE scale 0.75, UDRE scale 0.5, UDRE scale 0.3, UDRE scale 0.2, UDRE scale 0.1, no data, invalid data)	
DGPS information	C-Status/Health	1..<maxSat>		
>SatID	M		INTEGER (0..63)	Identifies the satellite and is equal to (SV ID No - 1) where SV ID No is defined in [10].
>IODE	M		INTEGER (0..255)	
>UDRE	M		ENUMERATED (UDRE ≤ 1.0 m, 1.0m < UDRE ≤ 4.0m, 4.0m < UDRE ≤ 8.0m, 8.0m < UDRE)	The value in this field shall be multiplied by the UDRE Scale Factor in the IE Status/Health to determine the final UDRE estimate for the particular satellite.
>PRC	M		INTEGER (-2047..2047.)	Scaling factor 0.32 Meters
>Range Rate Correction	M		INTEGER (-127..127)	Scaling factor 0.032 meters/sec

Table 28

Condition	Explanation
Status/Health	This IE shall be present if the <i>Status/Health</i> IE is not equal to "no data" or "invalid data"

Table 29

Range bound	Explanation
maxSat	Maximum number of satellites for which data is included in this IE. The value of maxSat is 16.

9.2.2.6 Geographical Area

Geographical Area IE is used to identify an area using geographical coordinates. The reference system is the same as the one used in [11].

Table 30

IE/Group Name	Presence	Range	IE type and reference	Semantics description
CHOICE <i>Geographical Area</i>				
> <i>Point</i>				Ellipsoid point
>>Geographical Coordinates	M		9.2.2.7	
> <i>Point With Uncertainty</i>				Ellipsoid point with uncertainty circle
>>Geographical Coordinates	M		9.2.2.7	
>>Uncertainty Code	M		INTEGER (0..127)	The uncertainty "r" expressed in meters is derived from the "Uncertainty Code" k by $r = 10x(1.1^k - 1)$
> <i>Polygon</i>				List of Ellipsoid points
>> Polygon		1..<maxnoofPoints>		
>>>Geographical Coordinates	M		9.2.2.7	
> <i>Ellipsoid point with uncertainty Ellipse</i>				
>>Geographical Coordinates	M		9.2.2.7	
>>Uncertainty Ellipse	M		9.2.2.30	
>>Confidence	M		INTEGER (0..100)	In percentage
> <i>Ellipsoid point with altitude</i>				
>>Geographical Coordinates	M		9.2.2.7	
>>Altitude and direction	M		9.2.2.2	
> <i>Ellipsoid point with altitude and uncertainty Ellipsoid</i>				
>>Geographical Coordinates	M		9.2.2.7	
>>Altitude and direction	M		9.2.2.2	
>>Uncertainty Ellipse	M		9.2.2.30	
>>Uncertainty Altitude	M		INTEGER (0..127)	The uncertainty altitude "h" expressed in metres is derived from the "Uncertainty Altitude" k , by: $h=45x(1.025^k - 1)$
>>Confidence	M		INTEGER (0..100)	In percentage
> <i>Ellipsoid Arc</i>				
>>Geographical Coordinates	M		9.2.2.7	
>>Inner radius	M		INTEGER (0.. $2^{16}-1$)	The relation between the value (N) and the radius (r) in meters it describes is $5N \leq r < 5(N+1)$, except for $N=2^{16}-1$ for which the range is extended to include all greater values of (r).
>>Uncertainty radius	M		INTEGER (0..127)	The uncertainty "r" is derived from the "Uncertainty radius" k by $r = 10x(1.1^k - 1)$

IE/Group Name	Presence	Range	IE type and reference	Semantics description
>>Offset angle	M		INTEGER (0..179)	The relation between the value (N) and the angle (a) in degrees it describes is $2N \leq a < 2(N+1)$
>>Included angle	M		INTEGER (0..179)	The relation between the value (N) and the angle (a) in degrees it describes is $2N < a \leq 2(N+1)$
>>Confidence	M		INTEGER (0..100)	

Table 31

Range bound	Explanation
maxnoofPoints	Maximum no. of points in polygon. Value is 15.

9.2.2.7 Geographical Coordinates

This IE contains the geographical coordinates.

Table 32

IE/Group Name	Presence	Range	IE type and reference	Semantics description
Latitude Sign	M		ENUMERATED (North, South)	
Degrees Of Latitude	M		INTEGER (0.. 2^{23} -1)	The IE value (N) is derived by this formula: $N \leq 2^{23} X / 90 < N+1$ X being the latitude in degree (0°.. 90°)
Degrees Of Longitude	M		INTEGER (- 2^{23} .. 2^{23} -1)	The IE value (N) is derived by this formula: $N \leq 2^{24} X / 360 < N+1$ X being the longitude in degree (-180°..+180°)

9.2.2.8 GPS Acquisition Assistance

This IE contains parameters that enable fast acquisition of the GPS signals in UE-assisted GPS positioning.

Table 33

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description	Criticality	Assigned Criticality
GPS TOW msec	M		INTEGER (0..6.048*10 ⁸ -1)	GPS Time of Week in milliseconds (rounded down to the nearest millisecond unit).	—	
Satellite information		1..<maxSat>			—	
>SatID	M		INTEGER (0..63)	Identifies the satellite and is equal to (SV ID No - 1) where SV ID No is defined in [10].	—	
>Doppler (0 th order term)	M		INTEGER (-2048..2047)	Scaling factor 2.5Hz	—	
>Extra Doppler		0..1			—	
>>Doppler (1 st order term)	M		INTEGER (-42..21)	Scaling factor 1/42	—	
>>Doppler Uncertainty	M		ENUMERATED (12.5,25,50,100,200,...)	In Hz	—	
>Code Phase	M		INTEGER (0..1022)	In Chips, specifies the centre of the search window	—	
>Integer Code Phase	M		INTEGER (0..19)	Number of 1023 chip segments	—	
>GPS Bit number	M		INTEGER (0..3)	Specifies GPS bit number (20 1023 chip segments)	—	
>Code Phase Search Window	M		ENUMRATED (1023,1,2,3,4,6,8,12,16,24,32,48,64,96,128,192)	Specifies the width of the search window.	—	
>Azimuth and Elevation		0..1			—	
>>Azimuth	M		INTEGER (0..31)	Scaling factor 11.25 Degrees	—	
>>Elevation	M		INTEGER (0..7)	Scaling factor 11.25 Degrees	—	
UTRAN GPS Reference Time	O		9.2.2.103	This IE may only be present if SAS operates in SAS-centric mode.	YES	ignore
GPS Reference Time Uncertainty	O		9.2.2.132	This IE may only be present if SAS operates in SAS-centric mode.	YES	ignore

Table 34

Range bound	Explanation
mMaxSat	Maximum number of satellites for which data is included in this IE. The value of maxSat is 16.

9.2.2.9 GPS Almanac and Satellite Health

This IE contains a reduced-precision subset of the clock and ephemeris parameters.

Table 35

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
WN _a	M		BIT STRING (8)	
Satellite information		1..<maxSat Almanac>		
>DataID	M		BIT STRING (2)	See [10]
>SatID	M		INTEGER (0..63)	Identifies the satellite and is equal to (SV ID No - 1) where SV ID No is defined in [10].
>e	M		BIT STRING (16)	Eccentricity [10]
>t _{oa}	M		BIT STRING (8)	Reference Time of Almanac [10]
>δi	M		BIT STRING (16)	Correction to Inclination (semi-circles) [10]
>OMEGADOT	M		BIT STRING (16)	Rate of Right Ascension (semi-circles/sec) [10]
>SV Health	M		BIT STRING (8)	[10]
>A ^{1/2}	M		BIT STRING (24)	Semi-Major Axis (meters) ^{1/2} [10]
>OMEGA ₀	M		BIT STRING (24)	Longitude of Ascending Node of Orbit Plane at Weekly Epoch (semi-circles) [10]
>M ₀	M		BIT STRING (24)	Mean Anomaly at Reference Time (semi-circles) [10]
>ω	M		BIT STRING (24)	Argument of Perigee (semi-circles) [10]
>af ₀	M		BIT STRING (11)	apparent clock correction [10]
>af ₁	M		BIT STRING (11)	apparent clock correction [10]
SV Global Health	O		BIT STRING (364)	This enables GPS time recovery and possibly extended GPS correlation intervals

Table 36

Range bound	Explanation
maxSatAlmanac	Maximum number of satellites for which data is included in this IE. The value of maxSatAlmanac is 32.

9.2.2.10 GPS Clock and Ephemeris Parameters

The IE contains the GPS clock information and GPS Ephemeris.

Table 37

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
C/A or P on L2	M		BIT STRING (2)	Code(s) on L2 Channel [10]
URA Index	M		BIT STRING (4)	User Range Accuracy [10]
SV Health	M		BIT STRING (6)	[10]
IODC	M		BIT STRING (10)	Issue of Data, Clock [10]
L2 P Data Flag	M		BIT STRING (1)	[10]
SF 1 Reserved	M		BIT STRING (87)	[10]
T_{GD}	M		BIT STRING (8)	Estimated group delay differential [10]
t_{oc}	M		BIT STRING (16)	apparent clock correction [10]
af_2	M		BIT STRING (8)	apparent clock correction [10]
af_1	M		BIT STRING (16)	apparent clock correction [10]
af_0	M		BIT STRING (22)	apparent clock correction [10]
C_{rs}	M		BIT STRING (16)	Amplitude of the Sine Harmonic Correction Term to the Orbit Radius (meters) [10]
Δn	M		BIT STRING (16)	Mean Motion Difference From Computed Value (semi-circles/sec) [10]
M_0	M		BIT STRING (32)	Mean Anomaly at Reference Time (semi-circles) [10]
C_{uc}	M		BIT STRING (16)	Amplitude of the Cosine Harmonic Correction Term To The Argument Of Latitude (radians) [10]
e	M		BIT STRING (32)	Eccentricity [10]
C_{us}	M		BIT STRING (16)	Amplitude of the Sine Harmonic Correction Term To The Argument Of Latitude (radians) [10]
$(A)^{1/2}$	M		BIT STRING (32)	Semi-Major Axis (meters) ^{1/2} [10]
t_{oe}	M		BIT STRING (16)	Reference Time Ephemeris [10]
Fit Interval Flag	M		BIT STRING (1)	[10]
AODO	M		BIT STRING (5)	Age Of Data Offset [10]
C_{ic}	M		BIT STRING (16)	Amplitude of the Cosine Harmonic Correction Term To The Angle Of Inclination (radians) [10]
OMEGA_0	M		BIT STRING (32)	Longitude of Ascending Node of Orbit Plane at Weekly Epoch (semi-circles) [10]
C_{is}	M		BIT STRING (16)	Amplitude of the Sine Harmonic Correction Term To The Angle Of Inclination (radians) [10]
i_0	M		BIT STRING (32)	Inclination Angle at Reference Time (semi-circles) [10]
C_{rc}	M		BIT STRING (16)	Amplitude of the Cosine Harmonic Correction Term to the Orbit Radius (meters) [10]

ω	M		BIT STRING (32)	Argument of Perigee (semi-circles) [10]
OMEGAdot	M		BIT STRING (24)	Rate of Right Ascension (semi-circles/sec) [10]
Idot	M		BIT STRING (14)	Rate of Inclination Angle (semi-circles/sec) [10]

9.2.2.11 GPS Ionospheric Model

The IE contains fields needed to model the propagation delays of the GPS signals through the ionosphere.

Table 38

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
α_0	M		BIT STRING (8)	NOTE 1
α_1	M		BIT STRING (8)	NOTE 1
α_2	M		BIT STRING (8)	NOTE 1
α_3	M		BIT STRING (8)	NOTE 1
β_0	M		BIT STRING (8)	NOTE 2
β_1	M		BIT STRING (8)	NOTE 2
β_2	M		BIT STRING (8)	NOTE 2
β_3	M		BIT STRING (8)	NOTE 2

NOTE 1: The parameters α_n are the coefficients of a cubic equation representing the amplitude of the vertical delay [10].

NOTE 2: The parameters β_n are the coefficients of a cubic equation representing the period of the ionospheric model [10].

9.2.2.12 GPS Measured Results

The purpose of this information element is to provide reported GPS measurement information from the SRNC to the SAS.

Table 39

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description	Criticality	Assigned Criticality
GPS TOW msec	M		INTEGER (0..6.048*10 ⁸ -1)	GPS Time of Week in milliseconds (rounded down to the nearest millisecond unit). If the <i>UTRAN GPS reference time Result</i> is present, this IE shall be set to 0 by the transmitter and ignored by the receiver.	–	
Measurement Parameters		1..<maxSat>			–	
>Satellite ID	M		INTEGER (0..63)	Identifies the satellite and is equal to (SV ID No - 1) where SV ID No is defined in [10].	–	
>C/N ₀	M		INTEGER (0..63)	The estimate of the carrier-to-noise ratio of the received signal from the particular satellite used in the measurement. It is given in units of dB-Hz (Typical levels will be in the range of 20 – 50 dB-Hz).	–	
>Doppler	M		INTEGER (-32768..32768)	Hz, scale factor 0.2.	–	
>Whole GPS Chips	M		INTEGER (0..1022)	Unit in GPS chips	–	
>Fractional GPS Chips	M		INTEGER (0..(2 ¹⁰ -1))	Scale factor 2 ⁻¹⁰	–	
>Multipath Indicator	M		ENUMERATED (NM, low, medium, high)	See NOTE 1	–	
>Pseudorange RMS Error	M		INTEGER (0..63)	See NOTE 2	–	
UTRAN GPS Reference Time Result	O		9.2.2.104	This IE may only be present if SAS operates in SAS-centric mode.	YES	ignore
GPS Reference Time Uncertainty	O		9.2.2.132		YES	ignore

NOTE 1: Table 41 gives the mapping of the multipath indicator field.

NOTE 2: Table 42 gives the bitmapping of the Pseudorange RMS Error field.

Table 40

Range bound	Explanation
maxSat	Maximum number of satellites for which data is included in this IE. The value of maxSat is 16.

Table 41

Value	Multipath Indication
NM	Not measured
Low	MP error < 5m
Medium	5m < MP error < 43m
High	MP error > 43m

Table 42

Value	Mantissa	Exponent	Floating-Point value, x_i	Pseudorange value, P
0	000	000	0.5	$P < 0.5$
1	001	000	0.5625	$0.5 \leq P < 0.5625$
i	X	Y	$0.5 * (1 + x/8) * 2^y$	$x_{i-1} \leq P < x_i$
62	110	111	112	$104 \leq P < 112$
63	111	111	--	$112 \leq P$

9.2.2.13 GPS Navigation Model

This IE contain information required to manage the transfer of precise navigation data to the GPS-capable UE.

Table 43

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
Satellite information		$1..<\maxSat>$		
>SatID	M		INTEGER (0..63)	Identifies the satellite and is equal to (SV ID No - 1) where SV ID No is defined in [10].
>Satellite Status	M		ENUMERATED (NS_NN, ES_SN, ES_NN, REVD)	See NOTE
>GPS Clock and Ephemeris parameters	C-Satellite status		9.2.2.10	

NOTE: The UE shall interpret enumerated symbols as follows.

Table 44

Value	Indication
NS_NN	New satellite, new Navigation Model
ES_SN	Existing satellite, same Navigation Model
ES_NN	Existing satellite, new Navigation Model
REVD	Reserved

Table 45

Condition	Explanation
<i>Satellite status</i>	The IE shall be present if the <i>Satellite Status</i> IE is not set to ES_SN

Table 46

Range bound	Explanation
maxSat	Maximum number of satellites for which data is included in this IE. The value of maxSat is 16.

9.2.2.14 GPS Real Time Integrity

Table 47

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
CHOICE <i>Bad Satellites Presence</i>				
>Bad Satellites				
>> Satellite information		1..<maxNo Sat>		
>>>BadSatID	M		INTEGER (0..63)	Identifies the satellite and is equal to (SV ID No - 1) where SV ID No is defined in [10].
>No Bad Satellites			NULL	

Table 48

Range bound	Explanation
maxNoSat	Maximum number of satellites for which data is included in this IE. The value of maxNoSat is 16.

9.2.2.15 GPS Reference Time

Table 49

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description	Criticality	Assigned Criticality
GPS Week	M		INTEGER (0..1023)		–	
GPS TOW msec	M		INTEGER (0..6.048*10 ⁸ -1)	GPS Time of Week in milliseconds (rounded down to the nearest millisecond unit).	–	
GPS TOW Assist		0..<maxSat>			–	
>SatID	M		INTEGER (0..63)	Identifies the satellite and is equal to (SV ID No - 1) where SV ID No is defined in [10].	–	
>TLM Message	M		BIT STRING (14)		–	
>Anti-Spoof	M		BOOLEAN		–	
>Alert	M		BOOLEAN		–	
>TLM Reserved	M		BIT STRING (2)		–	
UTRAN GPS Reference Time	O		9.2.2.103	This IE may only be present if SAS operates in SAS-centric mode.	YES	ignore
SFN-TOW Uncertainty	O		GPS-UTRAN Time Relationship Uncertainty 9.2.2.18	This IE may only be present if SAS operates in SAS-centric mode.	YES	ignore
TUTRAN-GPS Drift Rate	O		9.2.2.105	This IE may only be present if SAS operates in SAS-centric mode.	YES	ignore
GPS Reference Time Uncertainty	O		9.2.2.132	This IE may only be present if SAS operates in SAS-centric mode.	YES	ignore

Table 50

Range bound	Explanation
maxSat	Maximum number of satellites for which data is included in this IE. The value of maxSat is 16.

9.2.2.16 GPS Transmission TOW

Table 51

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
GPS Transmission TOW			INTEGER (0..604799)	The GPS time-of-week in seconds

9.2.2.17 GPS UTC Model

The UTC Model field contains a set of parameters needed to relate GPS time to Universal Time Coordinate (UTC).

Table 52

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
A ₁	M		BIT STRING (24)	sec/sec [10]
A ₀	M		BIT STRING (32)	seconds [10]
t _{ot}	M		BIT STRING (8)	seconds [10]
Δt _{LS}	M		BIT STRING (8)	seconds [10]
WN _t	M		BIT STRING (8)	weeks [10]
WN _{LSF}	M		BIT STRING (8)	weeks [10]
DN	M		BIT STRING (8)	days [10]
Δt _{LSF}	M		BIT STRING (8)	seconds [10]

9.2.2.18 GPS-UTRAN Time Relationship Uncertainty

This IE contains the uncertainty of the GPS and UTRAN time relationship.

Table 53

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
GPS-UTRAN Time Relationship Uncertainty			ENUMERATED (50ns, 500ns, 1us, 10us, 1ms, 10ms, 100ms, unreliable,...)	RNC or SAS estimate of uncertainty in GPS-UTRAN time relationship

9.2.2.19 Information Exchange ID

The Information Exchange ID uniquely identifies any requested information per RNC-SAS pair.

Table 54

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
Information Exchange ID			INTEGER (0 .. 2 ²⁰⁻¹)	

9.2.2.20 Information Exchange Object Type

Void.

9.2.2.21 Information Report Characteristics

The information report characteristics define how the reporting shall be performed.

Table 56

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
Information Report Characteristics Type	M		ENUMERATED(On Demand, Periodic, On Modification, ...)	
CHOICE <i>Information Report Periodicity</i>	C-Periodic			Indicates the frequency with which the SAS shall send broadcast data reports.
>Min				
>>Minutes	M		INTEGER (1..60, ...)	
>Hour				
>>Hours	M		INTEGER (1..24, ...)	

Table 57

Condition	Explanation
Periodic	This IE shall be present if the <i>Information Report Characteristics Type</i> IE indicates 'periodic'

9.2.2.22 Information Type

The Information Type indicates which kind of information the SAS shall provide.

Table 58

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description	Criticality	Assigned Criticality
<i>CHOICE Information Type</i>					—	
>Implicit					—	
>>Method Type	M		9.2.2.25		—	
>Explicit					—	
>> Explicit Information		1..<max noofExp Info>			—	
>>> <i>CHOICE Explicit Information Item</i>	M				—	
>>>> <i>Almanac and Satellite Health</i>			NULL		—	
>>>> <i>UTC Model</i>					—	
>>>>> <i>Transmission TOW Indicator</i>	M		9.2.2.29		—	
>>>> <i>Ionospheric Model</i>					—	
>>>>> <i>Transmission TOW Indicator</i>	M		9.2.2.29		—	
>>>> <i>Navigation Model</i>					—	
>>>>> <i>Transmission TOW Indicator</i>	M		9.2.2.29		—	
>>>> Nav. Model Additional Data		0..1			—	
>>>>> <i>GPS Week</i>	M		INTEGER (0..1023)		—	
>>>>> <i>GPS_Toe</i>	M		INTEGER (0..167)	GPS time of ephemeris in hours of the latest ephemeris set	—	
>>>>> <i>T-Toe limit</i>	M		Integer (0..10)	ephemeris age tolerance in hours	—	
>>>> Satellite related data		0..<max Sat>			—	
>>>>> <i>SatID</i>	M		INTEGER (0..63)	Identifies the satellite and is equal to (SV ID No - 1) where SV ID No is defined in [10].	—	
>>>>> <i>IODE</i>	M		INTEGER (0..255)	Issue of Data Ephemeris for SatID	—	
>>>> <i>DGPS Corrections</i>			NULL		—	
>>>> <i>Reference Time</i>			NULL		—	
>>>> <i>Acquisition Assistance</i>			NULL		—	
>>>> <i>Real Time Integrity</i>			NULL		—	
>>>> <i>Almanac and Satellite Health SIB</i>					—	
>>>> <i>Transmission TOW Indicator</i>	M		9.2.2.29		—	
>>>> <i>Reference Location</i>			NULL	This IE may only be present if SAS operates in	—	

				SAS-centric mode.		
>>>> GANSS Common Data					–	
>>>> GANSS Reference Time	O		ENUMERATED(Requested, Not-Requested)		–	
>>>> GANSS Ionosphere Model	O		ENUMERATED(Requested, Not-Requested)		–	
>>>> GANSS Reference Location	O		ENUMERATED(Requested, Not-Requested)	This IE may only be present if SAS operates in SAS-centric mode.	–	
>>>> GANSS Additional Ionospheric Model	O		Data ID BIT STRING(2)	Presence means requested according to Data ID as defined in [4]. Absence means not requested.	YES	ignore
>>>> GANSS Earth Orientation Parameters	O		ENUMERATED(Requested, Not-Requested)		YES	ignore
>>>> GANSS Generic Data					–	
>>>> GANSS Generic Data Item		1..<max GANSS >			–	
>>>> GANSS ID	O		9.2.2.130	Absence of this IE means Galileo.	–	
>>>> GANSS Real Time Integrity		0..1			–	
>>>>> GANSS Time Indicator	O		9.2.2.127		–	
>>>> GANSS Data Bits		0..1			–	
>>>>> GANSS TOD	M		INTEGER(0..86399)	The GANSS TOD for which the data bits are requested.	–	
>>>>> Data Bit Assistance		1			–	
>>>>>> GANSS Signal ID	M		BIT STRING(8)	Coded as defined in [4]	–	
>>>>>> GANSS Data Bit Interval	M		INTEGER(0..15)	This field represents the time length for which the Data Bit Assistance is requested. The Data Bit Assistance shall be relative to the time interval (GANSS TOD, GANSS TOD + Data Bit	–	

				Interval). The Data Bit Interval r , expressed in seconds, is mapped to a binary number K with the following formula: $r = 0.1 * 2^K$ Value $K=15$ means that the time interval is not specified.		
>>>>>Satellite Information		0..<max GANSS Sat>			—	
>>>>>>Satellite ID	M		INTEGER (0..63)	Defined in [4].	—	
>>>>DGANSS Corrections		0..1			—	
>>>>GANSS Time Indicator	O		9.2.2.127		—	
>>>>DGANS Signal	M		BIT STRING(8)	Coded as defined in [4]	—	
>>>>GANSS Almanac and Satellite Health		0..1			—	
>>>>GANSS Time Indicator	O		9.2.2.127		—	
>>>>GANSS Reference Measurement Information		0..1			—	
>>>>GANSS Time Indicator	O		9.2.2.127		—	
>>>>GANSS UTC Model		0..1			—	
>>>>GANSS Time Indicator	O		9.2.2.127		—	
>>>>GANSS Time Model GNSS-GNSS		0..1			—	
>>>>GNSS-GNSS Time ext	M		BIT STRING(9)	Defines the time model required. Bit 1 is the MSB and bit 9 is the LSB (see clause 9.2.1). Bit 1 stands for GPS, Bit 2 stands for Galileo, Bit 3 stands for QZSS Bit 4 stands for GLONASS. Other bits are reserved.	—	
>>>>GANSS Time Indicator	O		9.2.2.127		—	
>>>>GANSS		0..1			—	

Navigation Model						
>>>>>GANSS Week	M		INTEGER(0..4095)		–	
>>>>>GANSS Toe	M		INTEGER(0..167)		–	
>>>>>GANSS T-Toe Limit	M		INTEGER(0..10)		–	
>>>>>Satellite Related Data		0..<max GANSS Sat>			–	
>>>>>Sat ID	M		INTEGER(0..63)	Defined in [4].	–	
>>>>>IOD	M		BIT STRING(10)		–	
>>>>>GANSS Additional Navigation Models		0..1			–	
>>>>>GANSS Week	M		INTEGER(0..4095)		–	
>>>>>GANSS Toe	M		INTEGER(0..167)		–	
>>>>>GANSS T-Toe Limit	M		INTEGER(0..10)		–	
>>>>>Satellite Related Data		0..<max GANSS Sat>			–	
>>>>>Sat ID	M		INTEGER(0..63)	Defined in [4].	–	
>>>>>IOD	M		BIT STRING(10)		–	
>>>>>GANSS Additional UTC Models		0..1			–	
>>>>>GANSS Time Indicator	O		9.2.2.127		–	
>>>>>GANSS Auxiliary Information		0..1			–	
>>>>>GANSS Time Indicator	O		9.2.2.127		–	
>>>>>SBAS ID	C-GANSS-ID		9.2.2.134		–	

Table 59

Range Bound	Explanation
maxnoofExplInfo	Maximum number of Explicit Information supported in one Information Exchange. The value of maxnoofExplInfo is 32.
maxSat	Maximum number of satellites for which data is included in this IE. The value of maxSat is 16.
maxGANSS	Maximum number of GANSS systems for which data is included in this IE. The value of maxGANSS is 8.
maxGANSSSat	Maximum number of satellites for which data is included in this IE. The value of maxGANSSSat is 64

Table 59A

Condition	Explanation
GANSS-ID	This IE shall be present if the GANSS /D IE indicates 'SBAS'.

9.2.2.23 Message Structure

The *Message Structure* IE gives information for each level with assigned criticality in an hierarchical message structure from top level down to the lowest level above the reported level for the occurred error (reported in the *Information Element Criticality Diagnostics* IE).

Table 60

IE/Group Name	Presence	Range	IE type and reference	Semantics description
Message structure		1..<maxnooflevels>		The first repetition of the <i>Message Structure</i> IE corresponds to the top level of the message. The last repetition of the <i>Message Structure</i> IE corresponds to the level above the reported level for the occurred error of the message.
>IE ID	M		INTEGER (0..65535)	The IE ID of this level's IE containing the not understood or missing IE.
>Repetition Number	O		INTEGER (1..256)	<p>The <i>Repetition Number</i> IE gives, if applicable, the number of occurrences of this level's reported IE up to and including the occurrence containing the not understood or missing IE.</p> <p>Note: All the counted occurrences of the reported IE must have the same top-down hierarchical message structure of IEs with assigned criticality above them.</p>

Table 61

Range bound	Explanation
maxnooflevels	Maximum no. of message levels to report. The value for maxnooflevels is 256.

9.2.2.24 Message Type

Message Type IE uniquely identifies the message being sent. It is mandatory for all messages.

Table 62

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
Procedure Code	M		INTEGER(0..255)	“1” = Position Calculation “2” = Information Exchange Initiation “3” = Information Reporting “4” = Information Exchange Termination, “5” = Information Exchange Failure “6” = Error Indication “7” = Private Message “8” = Position Parameter Modification “9” = Position Initiation “10” = Position Activation “11” = Abort “12” = Position Periodic Report “13” = Position Periodic Result “14” = Position Periodic Termination
Type of Message	M		ENUMERATED (Initiating Message, Successful Outcome, Unsuccessful Outcome, Outcome)	

9.2.2.25 Method Type

Table 63

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
Method Type			ENUMERATED (UE_Assisted, UE_Based)	

9.2.2.26 Requested Data Value

The Requested Data Value contains the relevant data concerning the ongoing information exchange, or positioning event.

Table 64

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description	Criticality	Assigned Criticality
GPS Almanac and Satellite Health	O		9.2.2.9		–	
GPS UTC Model	O		9.2.2.17		–	
GPS Ionospheric Model	O		9.2.2.11		–	
GPS Navigation Model	O		9.2.2.13		–	
DGPS Corrections	O		9.2.2.5		–	
GPS Reference Time	O		9.2.2.15		–	
GPS Acquisition Assistance	O		9.2.2.8		–	
GPS Real Time Integrity	O		9.2.2.14		–	
Almanac and Satellite Health SIB	O		9.2.2.1		–	
GPS Transmission TOW	O		9.2.2.16		–	
GPS Reference Location	O		Geo-graphical Area 9.2.2.6	This IE may only be present if SAS operates in SAS-centric mode.	YES	ignore
GANSS Common Assistance Data		0..1			YES	ignore
>GANSS Reference Time	O		9.2.2.124		–	
>GANSS Ionospheric Model	O		9.2.2.116		–	
>GANSS Reference Location	O		Geo-graphical Area 9.2.2.6	This IE may only be present if SAS operates in SAS-centric mode.	–	
>GANSS Additional Ionospheric Model	O		9.2.2.116A		YES	ignore
>GANSS Earth Orientation Parameters	O		9.2.2.133		YES	ignore
GANSS Generic Assistance Data		0..<max GANSS >			GLOBAL	ignore
>GANSS ID	O		9.2.2.130	Absence of this IE means Galileo.	–	
>GANSS Real Time Integrity	O		9.2.2.122		–	
>GANSS Data Bit Assistance	O		9.2.2.127A		–	
>DGANSS Corrections	O		9.2.2.113		–	
>GANSS Almanac and Satellite Health	O		9.2.2.114		–	
>GANSS Reference Measurement Information	O		9.2.2.123		–	
>GANSS UTC Model	O		9.2.2.126		–	
>GANSS Time Model	O		9.2.2.125		–	
>GANSS Navigation Model	O		9.2.2.118		–	
>GANSS Additional Time Models	O		9.2.2.125A		–	

>GANSS Additional Navigation Models	O		9.2.2.118A		–	
>GANSS Additional UTC Models	O		9.2.2.126A		–	
>GANSS Auxiliary Information	O		9.2.2.135		–	
>SBAS ID	C-GANSS-ID		9.2.2.134		–	

Table 64A

Range Bound	Explanation
maxGANSS	Maximum number of GANSS systems for which data is included in this IE. The value of maxGANSS is 8.

Table 64B

Condition	Explanation
GANSS-ID	This IE shall be present if the <i>GANSS ID</i> IE indicates 'SBAS'.

9.2.2.27 Requested Data Value Information

The *Requested Data Value Information* IE provides information on whether or not the Requested Data Value is available in the message and also the Requested Data Value itself if available.

In case of "Periodic" and "On Modification" reporting, "Information Not Available" shall be used when at least one part of the requested information was not available at the moment of initiating the Information Reporting procedure.

Table 65

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description	Criticality	Assigned Criticality
CHOICE <i>Information Availability Indicator</i>	M				–	
> Information Available					–	
>>Requested Data Value	M		9.2.2.26		–	
>Information not Available			NULL		–	

9.2.2.28 Transaction ID

The Transaction ID is used to associate all the messages belonging to the same procedure. Messages belonging to the same procedure shall use the same Transaction ID.

The Transaction ID is determined by the initiating peer of a procedure.

The Transaction ID shall uniquely identify a procedure among all ongoing parallel procedures using the same procedure code, and initiated by the same protocol peer.

Table 66

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
CHOICE <i>Transaction ID Length</i>				The Transaction ID shall be interpreted for its integer value, not for the type of encoding ("short" or "long").
>Short				
>>Transaction ID Value	M		INTEGER (0..127)	
>Long				
>>Transaction ID Value	M		INTEGER (0..32767)	

9.2.2.29 Transmission TOW Indicator

Table 67

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
Transmission TOW Indicator			ENUMERATE D (requested, not requested)	

9.2.2.30 Uncertainty Ellipse

This IE contains the uncertainty ellipse of a geographical area.

Table 68

IE/Group Name	Presence	Range	IE type and reference	Semantics description
Uncertainty semi-major	M		INTEGER (0..127)	The uncertainty "r" is derived from the "uncertainty code" k by $r = 10x(1.1^k-1)$
Uncertainty semi-minor	M		INTEGER (0..127)	The uncertainty "r" is derived from the "uncertainty code" k by $r = 10x(1.1^k-1)$
Orientation of major axis	M		INTEGER (0..89)	The relation between the IE value (N) and the angle (a) in degrees it describes is $2N \leq a < 2(N+1)$

9.2.2.31 Cell-ID Measured Results Info List

This IE contains the Cell-ID measurements of signals associated with one or more cells.

Table 69

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description	Criticality	Assigned Criticality
Cell-ID Measured Results Info		1..<maxNoOfMeasCells>			–	
>UC-ID	M		9.2.2.37	The identifier of the measured cell.	–	
>UTRAN Access Point Position with Altitude	M		9.2.2.36	Exact geographical position of the base station antenna. If the SAS operates in SAS-centric mode, the values of this IE shall be set to 0 by the transmitter and shall be ignored by the receiver.	–	
>Geographical Area	O		9.2.2.6	May only be present if the SAS operates in RNC-centric mode.	–	
>Round Trip Time Info		0..1		FDD only	–	
>>UE Rx-Tx Time Difference Type 2	M		INTEGER (0..8191)	According to mapping in [13].	–	
>>UE Positioning Measurement Quality	M		9.2.2.35	Quality of the UE Rx-Tx time difference measurement.	–	
>>Round Trip Time	M		INTEGER (0..32766)	According to mapping in [13].	–	
>>Extended Round Trip Time	O		INTEGER (32767..103041)	Continuation of intervals as mapped in [13]. Included only if the <i>Round Trip Time</i> IE above is included with its maximum value and if the actual value is outside the possible range for the <i>Round Trip Time</i> IE	YES	ignore
>Rx Timing Deviation Info		0..1		3.84Mcps TDD only	–	
>>Rx Timing Deviation	M		INTEGER (0..8191)	According to mapping in [14].	–	
>>Timing Advance	M		INTEGER (0..63)	According to [4].	–	
>Rx Timing Deviation LCR Info		0..1		1.28Mcps TDD only	–	
>>Rx Timing Deviation LCR	M		INTEGER (0..511)	According to mapping in [14].	–	
>>Timing Advance LCR	M		INTEGER (0..2047)	According to [4]. The content of	–	

				this IE shall be ignored if the <i>Extended Timing Advance LCR IE</i> is present		
>>Extended Timing Advance LCR	O		INTEGER (2048..8191)	According to [4].	YES	ignore
>Pathloss	O		INTEGER (46..158)	Unit: dB downlink pathloss as defined in [4] subclause 10.3.7.3	–	
>Rx Timing Deviation 768Info		0..1		7.68Mcps TDD only	YES	reject
>>Rx Timing Deviation 7.68Mcps	M		INTEGER (0.. 65535)	According to mapping in [14].	–	
>>Timing Advance 7.68Mcps	M		INTEGER (0.. 511)	According to [4].	–	
>Rx Timing Deviation 384ext Info		0..1		3.84Mcps TDD only	YES	reject
>>Rx Timing Deviation	M		INTEGER (0.. 32767)	According to mapping in [14].	–	
>>Timing Advance	M		INTEGER (0.. 255)	According to [4].	–	
>Round Trip Time Info With Type 1		0..1		FDD only	YES	ignore
>>UE Rx-Tx Time Difference Type 1	M		INTEGER (768..1280)	According to mapping in [13].	–	
>>Round Trip Time	M		INTEGER (0..32766)	According to mapping in [13].	–	
>>Extended Round Trip Time	O		INTEGER (32767..103041)	Continuation of intervals as mapped in [13]. Included only if the <i>Round Trip Time IE</i> above is included with its maximum value and if the actual value is outside the possible range for the <i>Round Trip Time IE</i>	–	
>Additional UE Measurement Info		0..1		FDD only	YES	ignore
>>CPICH RSCP	O		INTEGER (-5..91)	According to CPICH_RSCP in [13].	–	
>>CPICH Ec/N0	O		INTEGER (0..49)	According to CPICH_Ec/No in [13].	–	
>Angle Of Arrival LCR		0..1		1.28Mcps TDD only	YES	ignore
>>AOA LCR	M		INTEGER (0..719)	According to mapping in [14]	–	
>>AOA LCR Accuracy Class	M		ENUMERATED (A, B, C, D, E, F, G, H,...)	According to mapping in [14]	–	

Table 70

Range bound	Explanation
maxNoOfMeasNCell	Maximum number of neighbour cells on which information can be reported. The value of maxNoOfMeasNCell is 32.

9.2.2.32 OTDOA Measured Results Info List

This IE contains the OTDOA measurements of signals sent from the reference and neighbour cells.

Table 71

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description	Criticality	Assigned Criticality
OTDOA Measured Results Info		1..<Maxno ofMeasNCell>			–	
>UC-ID	M		9.2.2.37	The identifier of the neighbour cell.	–	
>UE SFN-SFN Observed Time Difference Type 2 Info		1			–	
>>SFN-SFN Observed Time Difference Type 2	M		INTEGER (0..40961)	Gives the observed timing of the neighbour cell relative to the reference cell.	–	
>>UE Positioning Measurement Quality	M		9.2.2.35	Quality of the observed time difference measurement.	–	
>>Measurement Delay	M		INTEGER (0..65535)	<p>The interval of time, in units of 10ms frames, spanning the following two events:</p> <p>1) Time of applicability of the SFN-SFN Value or TUTRAN-GPS/SFN relationship provided for the corresponding neighbour cell in 9.2.2.33 or TUTRAN-GANSS/SFN relationship provided for the corresponding neighbour cell in 9.2.2.33.</p> <p>2) The point in time when this corresponding SFN-SFN observed time difference measurement was captured by the UE.</p> <p>If the SAS operates in SAS-centric mode, 1) above shall be set to zero. I.e., in SAS-centric mode this IE</p>	–	

				indicates the SFN during which the corresponding SFN-SFN observed time difference measurement was captured by the UE.		
>Additional OTDOA Measured Results	O			This IE may only be present if SAS operates in SAS-centric mode.	YES	ignore
>>Primary CPICH Info	M		Primary Scrambling Code 9.2.2.46	The identifier of the neighbour cell.	—	

Table 72

Range bound	Explanation
MaxNoOfMeasNCell	Maximum number of neighbouring cells on which information can be reported. The value of MaxNoOfMeasNCell is 32.

9.2.2.33 OTDOA Neighbour Cell Info

Table 73

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
UC-ID	M		9.2.2.37	The identifier of the neighbour cell.
UTRAN Access Point Position with Altitude	M		9.2.2.36	Exact geographical position of the base station antenna.
CHOICE <i>Relative Timing Difference Info</i>	M			
>SFN-SFN Measurement Value Information				
>>SFN-SFN Value	M		INTEGER (0..614399)	
>>SFN-SFN Quality	O		INTEGER (0..255)	Indicates the standard deviation (std) of the SFN-SFN otd (observed time difference) measurements in 1/16 chip. SFN-SFN Quality = $\sqrt{E[(x-\mu)^2]}$ = std of reported SFN-SFN Value, where x is the reported SFN-SFN Value and $\mu = E[x]$ is the expectation value of x.
>>SFN-SFN Drift Rate	M		INTEGER (-100..+100)	Indicates the SFN-SFN drift rate in 1/256 chip per second. A positive value indicates that the Reference cell clock is running at a greater frequency than the measured neighbouring cell.
>>SFN-SFN Drift Rate Quality	O		INTEGER (0..100)	Indicates the standard deviation (std) of the SFN-SFN drift rate measurements in 1/256 chip per second. SFN-SFN Drift Rate Quality = $\sqrt{E[(x-\mu)^2]}$ = std of reported SFN-SFN Drift Rate, where x is the reported SFN-SFN Drift Rate and $\mu = E[x]$ is the expectation value of x.
>T _{UTRAN-GPS} Measurement Value Information				
>>SFN	M		INTEGER (0..4095)	SFN during which the T _{UTRAN-GPS} measurement was performed
>>T _{UTRAN-GPS}		1		Indicates the UTRAN GPS Timing of Cell Frame for LCS.
>>>MS	M		INTEGER (0..16383)	Most significant part
>>>LS	M		INTEGER (0..4294967295)	Least significant part
>>T _{UTRAN-GPS} Quality	O		INTEGER (0..255)	Indicates the standard deviation (std) of the T _{UTRAN-GPS} measurements in 1/16 chip. T _{UTRAN-GPS} Quality = $\sqrt{E[(x-\mu)^2]}$ = std of reported T _{UTRAN-GPS} Value, where x is the reported T _{UTRAN-GPS} Value and $\mu = E[x]$ is the expectation value of x.
>>T _{UTRAN-GPS} Drift Rate	M		INTEGER (-50..+50)	Indicates the T _{UTRAN-GPS} drift rate in 1/256 chip per second. A positive value indicates that

				the UTRAN clock is running at a lower frequency than GPS clock.
>>T _{UTRAN-GPS} Drift Rate Quality	O		INTEGER(0..50)	Indicates the standard deviation (std) of the T _{UTRAN-GPS} drift rate measurements in 1/256 chip per second. T _{UTRAN-GPS} Drift Rate Quality = $\sqrt{E[(x-\mu)^2]}$ = std of reported T _{UTRAN-GPS} Drift Rate, where x is the reported T _{UTRAN-GPS} Drift Rate and $\mu = E[x]$ is the expectation value of x.
>T _{UTRAN-GANSS} Measurement Value Information				
>>GANSS ID	O		9.2.2.130	Absence of this IE means Galileo.
>>SFN	M		INTEGER(0..4095)	SFN during which the T _{UTRAN-GANSS} measurement was performed
>>T _{UTRAN-GANSS}		1		Indicates the UTRAN GANSS Timing of Cell Frame for LCS.
>>>MS	M		INTEGER(0..16383)	Most significant part
>>>LS	M		INTEGER(0..4294967295)	Least significant part
>>T _{UTRAN-GANSS} Quality	O		INTEGER(0..255)	Indicates the standard deviation (std) of the T _{UTRAN-GANSS} measurements in 1/16 chip. T _{UTRAN-GANSS} Quality = $\sqrt{E[(x-\mu)^2]}$ = std of reported T _{UTRAN-GANSS} Value, where x is the reported T _{UTRAN-GANSS} Value and $\mu = E[x]$ is the expectation value of x.
>>T _{UTRAN-GANSS} Drift Rate	M		INTEGER(-50..50)	Indicates the T _{UTRAN-GANSS} drift rate in 1/256 chip per second. A positive value indicates that the UTRAN clock is running at a lower frequency than GANSS clock.
>>T _{UTRAN-GANSS} Drift Rate Quality	O		INTEGER(0..50)	Indicates the standard deviation (std) of the T _{UTRAN-GANSS} drift rate measurements in 1/256 chip per second. T _{UTRAN-GANSS} Drift Rate Quality = $\sqrt{E[(x-\mu)^2]}$ = std of reported T _{UTRAN-GANSS} Drift Rate, where x is the reported T _{UTRAN-GANSS} Drift Rate and $\mu = E[x]$ is the expectation value of x.

9.2.2.34 OTDOA Reference Cell Info

Table 74

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description	Criticality	Assigned Criticality
UC-ID	M		9.2.2.37	The identifier of the reference cell.	—	
UTRAN Access Point Position with Altitude	M		9.2.2.36	Exact geographical position of the base station antenna.	—	
TUTRAN-GPS Measurement Value Information		0..1			—	
>SFN	M		INTEGER (0..4095)	SFN during which the TUTRAN-GPS measurement was performed	—	
>T _{UTRAN-GPS}		1		Indicates the UTRAN GPS Timing of Cell Frame for LCS.	—	
>>MS	M		INTEGER (0..16383)	Most significant part	—	
>>LS	M		INTEGER (0..4294967295)	Least significant part	—	
>T _{UTRAN-GPS} Quality	O		INTEGER (0..255)	Indicates the standard deviation (std) of the T _{UTRAN-GPS} measurements in 1/16 chip. T _{UTRAN-GPS} Quality = $\sqrt{E[(x-\mu)^2]}$ = std of reported T _{UTRAN-GPS} Value, where x is the reported T _{UTRAN-GPS} Value and $\mu = E[x]$ is the expectation value of x.	—	
>T _{UTRAN-GPS} Drift Rate	M		INTEGER (-50..+50)	Indicates the T _{UTRAN-GPS} drift rate in 1/256 chip per second. A positive value indicates that the UTRAN clock is running at a lower frequency than GPS clock.	—	
>T _{UTRAN-GPS} Drift Rate Quality	O		INTEGER (0..50)	Indicates the standard deviation (std) of the T _{UTRAN-GPS} drift rate measurements in 1/256 chip per second. T _{UTRAN-GPS} Drift Rate Quality = $\sqrt{E[(x-\mu)^2]}$ = std of reported T _{UTRAN-GPS} Drift Rate, where x is the reported T _{UTRAN-GPS} Drift Rate and $\mu = E[x]$ is the expectation value of	—	

TUTRAN-GANSS Measurement Value Information		0..1		x.	GLOBAL	ignore
>GANSS ID	O		9.2.2.130	Absence of this IE means Galileo.	–	
>SFN	M		INTEGER (0..4095)	SFN during which the T _{UTRAN-GANSS} measurement was performed	–	
>T _{UTRAN-GANSS}		1		Indicates the UTRAN GANSS Timing of Cell Frame for LCS.	–	
>>MS	M		INTEGER(0..16383)	Most significant part	–	
>>LS	M		INTEGER(0..4294967295)	Least significant part	–	
>T _{UTRAN-GANSS} Quality	O		INTEGER(0..255)	Indicates the standard deviation (std) of the T _{UTRAN-GANSS} measurements in 1/16 chip. T _{UTRAN-GANSS} Quality = $\sqrt{E[(x-\mu)^2]}$ = std of reported T _{UTRAN-GANSS} Value, where x is the reported T _{UTRAN-GANSS} Value and $\mu = E[x]$ is the expectation value of x.	–	
>T _{UTRAN-GANSS} Drift Rate	M		INTEGER(-50..50)	Indicates the T _{UTRAN-GANSS} drift rate in 1/256 chip per second. A positive value indicates that the UTRAN clock is running at a lower frequency than GANSS clock.	–	
>T _{UTRAN-GANSS} Drift Rate Quality	O		INTEGER(0..50)	Indicates the standard deviation (std) of the T _{UTRAN-GANSS} drift rate measurements in 1/256 chip per second. T _{UTRAN-GANSS} Drift Rate Quality = $\sqrt{E[(x-\mu)^2]}$ = std of reported T _{UTRAN-GANSS} Drift Rate, where x is the reported T _{UTRAN-GANSS} Drift Rate and $\mu = E[x]$ is the expectation value of x.	–	
Additional Measurement Information LCR		0..1		1.28Mcps TDD only	YES	ignore
>Timing Advance LCR R7	M		INTEGER (0..8191)	According to [4].	–	
>Rx Timing Deviation LCR	M		INTEGER (0..511)	According to mapping in [14].	–	

>Angle Of Arrival LCR		0..1		1.28Mcps TDD only	–	
>>AOA LCR	M		INTEGER (0..719)	According to mapping in [14]	–	
>>AOA LCR Accuracy Class	M		ENUMERA TED (A, B, C, D, E, F, G, H,...)	According to mapping in [14]	–	

9.2.2.35 UE Positioning Measurement Quality

Table 75

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
Std Resolution	M		BIT STRING (2)	Std Resolution field includes the resolution used in Std of Measurements field. Encoding on two bits as follows: '00' 10 meters '01' 20 meters '10' 30 meters '11' Reserved
Number of Measurements	M		BIT STRING (3)	The 'Number of Measurements' field indicates how many measurements have been used in the UE to determine the sample standard deviation of the measurements. Following 3 bit encoding is used: '001' 5-9 '010' 10-14 '011' 15-24 '100' 25-34 '101' 35-44 '110' 45-54 '111' 55 or more Special case: '000': In this case the field 'Std of Measurements' contains the std of the reported measurement value = $\sqrt{E[(x-\mu)^2]}$, where x is the reported value and $\mu = E[x]$ is the expectation value (i.e. the true value) of x. This std can be used irrespective of the number of measurements and reporting of the number of measurements is not needed. Also other measurements such as Ec/No or Rx levels can be utilised in this case to evaluate the 'Std of Measurements' reported in this IE.
Std of Measurements	M		BIT STRING (5)	Std of Measurements field includes sample standard deviation of measurements (when number of measurements is reported in 'Number of Measurements' field) or standard deviation of the reported measurement value = $\sqrt{E[(x-\mu)^2]}$, where x is the reported value and $\mu = E[x]$ is the expectation value (i.e. the true value) of x (when '000' is given in 'Number of Measurements' field). Following linear 5 bit encoding is used: '00000' 0 - (R*1-1) meters '00001' R*1 - (R*2-1) meters '00010' R*2 - (R*3-1) meters ...

			'11111' R*31 meters or more where R is the resolution defined by Std Resolution field. E.g. R=20 m corresponds to 0-19 m, 20-39 m,...,620+ m.
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9.2.2.36 UTRAN Access Point Position with Altitude

The UTRAN Access Point Position with Altitude indicates the exact geographical position of the base station antenna. The altitude shall be included when available.

Table 76

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
Geographical Coordinates	M		9.2.2.7	
Altitude and direction	O		9.2.2.2	

9.2.2.37 UTRAN Cell Identifier (UC-ID)

The UC-ID (UTRAN Cell identifier) is the identifier of a cell in one UTRAN.

Table 77

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description	Criticality	Assigned Criticality
RNC-ID	M		INTEGER (0..4095)	The identifier of one RNC in UTRAN. If the <i>Extended RNC-ID</i> IE is included in the <i>UC-ID</i> IE, the <i>RNC-ID</i> IE shall be ignored.	—	—
C-ID	M		INTEGER (0..65535)	The identifier of a cell in one RNS.	—	—
Extended RNC-ID	O		9.2.2.37A	The <i>Extended RNC-ID</i> IE shall be used if the RNC identity has a value larger than 4095.	YES	reject

9.2.2.37A Extended RNC-ID

This is the identifier of one RNC in UTRAN.

Table 77A

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
Extended RNC-ID			INTEGER(4096 ..65535)	Note: Application of the <i>Extended RNC-ID</i> IE to very large networks is FFS.

9.2.2.38 Horizontal Accuracy Code

Table 78

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
Horizontal Accuracy Code	M		INTEGER(0..127)	The requested accuracy "r" is derived from the "Horizontal Accuracy Code" k by $r = 10x(1.1^k - 1)$

9.2.2.39 Vertical Accuracy Code

Table 79

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
Vertical Accuracy Code	M		INTEGER(0..127)	The requested accuracy "v" is derived from the "Vertical Accuracy Code" k by $v = 45x(1.025^k - 1)$.

9.2.2.40 Accuracy Fulfilment Indicator

This IE indicates whether the returned position estimate satisfies the requested accuracy or not.

Table 80

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
Accuracy Fulfilment Indicator	M		ENUMERATED (requested accuracy fulfilled, requested accuracy not fulfilled, ...)	

9.2.2.41 Uplink DPCH information

This IE indicates the Uplink DPCH information used in the U-TDOA positioning method.

Table 81

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
Choice mode	M			
>FDD				
>>Scrambling code type	M		ENUMERATED (short, long)	
>>Scrambling code number	M		INTEGER(0..16 777215)	
>>TFCI existence	M		BOOLEAN	TRUE means existence.
>>Number of FBI bits	M		INTEGER(0..2)	In bits.
>TDD				
>>Cell Parameter ID	M		9.2.2.81	
>>TFCI Coding	M		9.2.2.82	
>>Puncture Limit	M		9.2.2.76	
>>Repetition Period	M		9.2.2.84	
>>Repetition Length	M		9.2.2.83	
>>TDD DPCH Offset	M		9.2.2.85	
>>UL Timeslot Information	M		9.2.2.86	
>>Frame Offset	M		9.2.2.64	
>>Special Burst Scheduling	M		9.2.2.92	

9.2.2.42 Frequency information

This IE indicates the Frequency information used for the U-TDOA positioning method.

Table 82

IE/Group name	Presence	Range	IE Type and Reference	Semantics description
CHOICE mode	M			
>FDD				
>>UARFCN uplink (Nu)	O		INTEGER (0..16383)	If this IE is not present, the default duplex distance defined for the operating frequency band shall be used [20]
>>UARFCN downlink (Nd)	M		INTEGER (0 .. 16383)	[20]
>TDD				
>>UARFCN	M		INTEGER (0 .. 16383)	[21]

9.2.2.43 PRACH parameters

This IE indicates the PRACH parameter used for the U-TDOA positioning method.

Table 83

IE/Group name	Presence	Range	IE Type and Reference	Semantics description
PRACH parameters		1 .. <maxP RACH>		
>PRACH information	M		9.2.2.47	
>TFS	M		9.2.2.48	
>TFCS		1..<max TFC>		
>>CTFC	M		9.2.2.49	

Table 84

Range bound	Explanation
maxPRACH	Maximum number of PRACHs in a cell. The value is 16.
maxTFC	Maximum number of TFC. Value is 1024.

9.2.2.44 Compressed Mode Assistance Data

This IE provides the assistance data used for the U-TDOA positioning method when the UE is operating in the compressed mode.

Table 85

IE/Group name	Presence	Range	IE Type and Reference	Semantics description
Downlink information		1		
>Primary Scrambling Code	M		9.2.2.46	
>Chip Offset	M		9.2.2.63	
>Frame Offset	M		9.2.2.64	
Uplink information		1		
>Transmisson Gap Pattern Sequence Information	M		9.2.2.66	
>Active Pattern Sequence Information	M		9.2.2.67	
>CFN	M		9.2.2.68	

9.2.2.45 C-RNTI

The cell RNTI (C-RNTI) identifies a UE having a RRC connection within a cell that is used for the U-TDOA positioning method.

Table 86

IE/Group name	Presence	Range	IE Type and Reference	Semantics description
C-RNTI			BIT STRING(16)	

9.2.2.46 Primary Scrambling Code

This IE gives the DL scrambling code of a cell.

Table 87

IE/Group name	Presence	Range	IE Type and Reference	Semantics description
Primary Scrambling Code			INTEGER(0..511)	

9.2.2.47 PRACH information

This IE contains the PRACH information used for the U-TDOA positioning method.

Table 88

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
CHOICE mode	M			
>FDD				
>>Available Signature	M		BIT STRING (16)	Each bit indicates availability for a signature, where the signatures are numbered "signature 0" up to "signature 15". The value 1 of a bit indicates that the corresponding signature is available and the value 0 that it is not available.
>>Available SF	M		ENUMERATED (32,64,128,256, ...)	In chips per symbol Defines the minimum allowed SF (i.e. the maximum rate)
>>Preamble scrambling code number	M		INTEGER(0..15)	Identification of scrambling code see [17]
>>Puncturing Limit	M		9.2.2.76	
>>Available Sub Channel Number	M		BIT STRING (12)	Each bit indicates availability for a subchannel, where the subchannels are numbered "subchannel 0" to "subchannel 11". The value 1 of a bit indicates that the corresponding subchannel is available and the value 0 indicates that it is not available.
>TDD				
>>Time Slot	M		9.2.2.87	
>>TDD Channelisation Code	M		9.2.2.91	
>>Max PRACH Midamble Shifts	M		9.2.2.93	
>>PRACH Midamble	M		9.2.2.94	

9.2.2.48 TFS

This IE contains the TFS parameters used for the U-TDOA positioning method.

Table 89

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
Dynamic Transport Format Information		1.. <maxT F>		
>RLC Size	M		INTEGER(129..50 55)	Unit is bits
>Number of TBs and TTI List		1.. <maxT F>		Present for every valid number of TB's (and TTI) for this RLC Size.
>>Transmission time interval	C-dynamicTTI		ENUMERATED(10, 20, 40, 80, dynamic,...)	In ms. The value dynamic is only used in TDD mode.
>>Number of Transport blocks	M		INTEGER(0..512)	
Semi-static Transport Format Information	M		9.2.2.61	

Table 90

Range bound	Explanation
maxTF	Maximum number of Transport Formats. The value is 32.

Table 91

Condition	Explanation
dynamicTTI	This IE shall be present if TTI IE in Semi-static Transport Format Information IE is set to dynamic.

9.2.2.49 CTFC

This IE identifies the TFC used for the U-TDOA positioning method.

Table 92

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
CHOICE CTFC Size				
>2 bit CTFC				
>>CTFC information-2		1..<max TFC>		
>>>ctfc2Bit	M		INTEGER(0..3)	
>4 bit CTFC				
>>CTFC information-4		1..<max TFC>		
>>>ctfc4Bit	M		INTEGER(0..15)	
>6 bit CTFC				
>>CTFC information-6		1..<max TFC>		
>>>ctfc6Bit	M		INTEGER(0..63)	
>8 bit CTFC				
>>CTFC information-8		1..<max TFC>		
>>>ctfc8Bit	M		INTEGER(0..255)	
>12 bit CTFC				
>>CTFC information-12		1..<max TFC>		
>>>ctfc12Bit	M		INTEGER(0..4095)	
>16 bit CTFC				
>>CTFC information-16		1..<max TFC>		
>>>ctfc16Bit	M		INTEGER(0..65535)	
>24 bit CTFC				
>>CTFC information-24		1..<max TFC>		
>>>ctfc22Bit	M		INTEGER(0..16777215)	

Table 92A

Range bound	Explanation
maxTFC	Maximum number of TFC. Value is 1024.

9.2.2.50 Request Type

This IE contains the Request Type parameters used for SAS centric positioning method selection.

Table 93

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
Event	M		ENUMERATED(S top Change of service area, Direct, Change of service area, Stop Direct, ..., Periodic, Stop Periodic)	Requests related to service area reporting are not supported in the current version of this specification.
Report Area	M		ENUMERATED(S ervice Area, Geographical Area, ...)	
Horizontal Accuracy Code	O		INTEGER(0..127)	The requested accuracy "r" is derived from the "accuracy code" k by $r = 10 \times (1.1^k - 1)$.

9.2.2.51 UE Positioning Capability

This IE contains the UE Positioning Capability information used for SAS centric positioning method selection.

Table 94

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description	Criticality	Assigned Criticality
Standalone location method(s) supported	M		BOOLEAN	Defines if a UE can measure its location by some means unrelated to UTRAN. TRUE means supported	–	
UE based OTDOA supported	M		BOOLEAN	TRUE means supported	–	
Network Assisted GPS support	M		ENUMERATED (Network based, UE based, Both, None,...)	Defines if the UE supports network based or UE based GPS methods.	–	
Support for GPS timing of cell frames measurement	M		BOOLEAN	Defines if a UE has the capability to perform the UE GPS timing of cell frames measurement [4]. TRUE means capable	–	
Support for IPDL	M		BOOLEAN	Defines if a UE has the capability to use IPDL to enhance its 'SFN-SFN observed time difference –type 2' measurement. TRUE means supported	–	
Support for Rx-Tx time difference type2 measurement	M		BOOLEAN	TRUE means supported	–	
Support for UE assisted GPS measurement validity in CELL_PCH and URA_PCH states	M		BOOLEAN	TRUE means supported	–	
Support for SFN-SFN observed time difference type 2 measurement	M		BOOLEAN	TRUE means supported	–	
Network Assisted GANSS Support		0..<max GANSS>			GLOBAL	ignore
>GANSS ID	O		9.2.2.130	Absence of this IE means Galileo.	–	
>GANSS mode	M		ENUMERATED ('Network based', 'UE based', 'Both', 'None')	Defines if the UE supports network based or UE based GANSS methods	–	
>GANSS Signal ID	O		9.2.2.131	Absence of this field means the default value for the GANSS identified by	–	

>Support for GANSS timing of cell frames measurement	M		BOOLEAN	"GANSS ID" [4]. Defines if a UE has the capability to perform the UE GANSS timing of cell frames measurement [4]. TRUE means capable	–	
>Support for GANSS Carrier-Phase Measurement	O		BOOLEAN	Defines if a UE has the capability to perform the UE GANSS Carrier-Phase Measurement. TRUE means capable	–	
>SBAS IDs	C-GANSS-ID		BIT STRING(8)	Defines the specific SBAS(s) supported. Coded as defined in [4].	–	
>GANSS Signal IDs	O		BIT STRING(8)	Defines if a UE has the capability to perform measurements on more than one GANSS signal and which signals are supported. Coded as defined in [4].	–	
>Support for non-native assistance choices	O		ENUMERATED(true)	Defines if a UE supports assistance data choices in formats not defined in the ICD of a particular GANSS [4].	–	

Table 94A

Range Bound	Explanation
maxGANSS	Maximum number of GANSS systems for which data is included in this IE. The value of maxGANSS is 8.

Table 94B

Condition	Explanation
GANSS-ID	This IE shall be present if the GANSS ID IE indicates 'SBAS'.

9.2.2.52 Response Time

This IE contains the Response Time used for SAS centric mode.

Table 95

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
Response Time			ENUMERATED(Low Delay, Delay Tolerant,...)	The value refers to [15].

9.2.2.53 Positioning Priority

This IE contains the Positioning Priority used for SAS centric mode.

Table 96

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
Positioning Priority			ENUMERATED(High Priority, Normal Priority, ...)	The value refers to [15]

9.2.2.54 Client Type

This IE contains the Client Type used for SAS centric mode.

Table 97

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
Client Type			ENUMERATED(Emergency Services, Value Added Services, PLMN Operator Services, Lawful Intercept Services, PLMN Operator - broadcast services, PLMN Operator - O&M, PLMN Operator - anonymous statistics, PLMN Operator - Target MS service support, ...)	Identifies the type of client.

9.2.2.55 Positioning Method

This IE contains the Positioning Method used for SAS centric positioning method selection.

Table 98

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description	Criticality	Assigned Criticality
Additional Method Type	M		9.2.2.58		—	
Selected Position Method	M		ENUMERATE D(OTDOA, GPS, OTDOA or GPS, Cell ID, UTDOA, ..., GNSS, OTDOA or GNSS)		—	
GNSS Positioning Method	C-GNSS		BIT STRING(9)	<p>For each bit, if set to '1', indicates that respective GNSS is allowed.</p> <p>Bit 1 is the MSB and bit 9 is the LSB (see clause 9.2.1).</p> <p>bit 1: GPS bit 2: Galileo bit 3: SBAS (WAAS, EGNOS, MSAS, GAGAN) bit 4: Modernized GPS (L1C, L2C, L5) bit 5: QZSS bit 6: GLONASS</p> <p>bits 7-9: reserved for future GNSSes</p> <p>Note: Bit 1 cannot be the only one set to 1.</p>	YES	ignore

Table 98A

Condition	Explanation
GNSS	This IE shall be present if the <i>Selected Position Method</i> IE value is set to "GNSS" or "OTDOA or GNSS"

9.2.2.56 U-TDOA Bit Count

This IE contains the recommended number of pre-coded bits to be transmitted by the UE when the U-TDOA positioning method is selected.

Table 99

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
U-TDOA Bit Count			INTEGER (0..5000)	Number of bits to be transmitted by the target UE

9.2.2.57 U-TDOA Time Interval

This IE contains the recommended maximum time interval for transmission of the U-TDOA Bit Count number of bits for U-TDOA positioning.

Table 100

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
U-TDOA Time Interval			INTEGER (0..3000)	Time in ms in which the U-TDOA Bit Count is to be transmitted by the UE

9.2.2.58 Additional Method Type

This IE contains the selected positioning method type for SAS-centric mode.

Table 101

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
Additional Method Type			ENUMERATED (UE_Assisted, UE_Based, UE_Based is preferred but UE_assisted is allowed, UE_Assisted is preferred but UE_Based is allowed, ...)	

9.2.2.59 UE Positioning OTDOA Assistance Data

This IE contains the UE Positioning OTDOA Assistance Data used in the SAS centric mode.

Table 102

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description	Criticality	Assigned Criticality
UE Positioning OTDOA Reference Cell Info	O				–	
>SFN	O		INTEGER (0..4095)	Time stamp (SFN of Reference Cell) of the SFN-SFN relative time differences and SFN-SFN drift rates. Included if any SFN-SFN drift value is included in IE <i>UE positioning OTDOA neighbour cell info</i> .	–	
>CHOICE mode					–	
>>Fdd					–	
>>>Primary CPICH Information	M		Primary scrambling code 9.2.2.46		–	
>>Tdd					–	
>>>Cell Parameter ID	M		9.2.2.81		–	
>Frequency Info	O		9.2.2.42	Default value is the existing value of frequency information. This IE shall always be set to default value	–	
>CHOICE positioning mode					–	
>>UE Based					–	
>>> Cell position	O		Reference Cell Position 9.2.2.70	The position of the antenna that defines the cell.	–	
>>> Round Trip Time	O		INTEGER (0..32766)	According to mapping in [13].	–	
>>UE Assisted					–	
>UE positioning IPDL parameters	O		9.2.2.71	If this element is not included there are no idle periods present	–	
>Extended Round Trip Time	O		INTEGER (32767..103041)	According to mapping in [13]. Included only if the <i>Round Trip Time</i> IE above is included with its maximum value and if the actual value is outside the possible range for the the <i>Round Trip Time</i> IE.	YES	ignore
>Timing Advance LCR R7	O		INTEGER (0..8191)	1.28Mcps TDD only. According to [4].	–	
>Rx Timing Deviation LCR	O		INTEGER (0..511)	1.28Mcps TDD only . According to mapping in [14].	–	
>Angle Of Arrival LCR		0..1		1.28Mcps TDD only	–	
>>AOA LCR	M		INTEGER (0..719)	According to mapping in [14]	–	
>>AOA LCR Accuracy Class	M		ENUMERATE D (A, B, C, D, E, F, G, H,...)	According to mapping in [14]	–	

UE Positioning OTDOA Neighbour Cell List	O				—	
>UE positioning OTDOA Neighbour cell info		1..<maxCellM eas>			—	
>>CHOICE mode					—	
>>>FDD					—	
>>>Primary CPICH Information	M		Primary scrambling code 9.2.2.46		—	
>>>TDD					—	
>>>Cell Parameter ID	M		9.2.2.81		—	
>>Frequency Info	O		9.2.2.42	Default value is the existing value of frequency information	—	
>>UE positioning IPDL parameters	O		9.2.2.71		—	
>>SFN-SFN Relative Time difference	M		9.2.2.73		—	
>>SFN Offset Validity	O		ENUMERATE D (false)	Absence of this element means SFN offset is valid. False means SFN offset is not valid.	—	
>>SFN-SFN Drift	O		ENUMERATE D (0,1,2,3,4,5,8, 10,15,25,35,50 ,65,80,100,-1,- 2,-3,-4,-5,-8, - 10,-15,-25,- 35,-50,-65,- 80,-100,...)	Indicates the SFN-SFN drift rate in 1/256 chip per second.	—	
>>Search Window Size	M		ENUMERATE D (c20, c40, c80, c160, c320, c640, c1280, moreThan1280, ...)	In chips. If the value is X then the expected SFN-SFN observed time difference is in the range [RTD-X, RTD+X] where RTD is the value of the field SFN-SFN relative time difference.	—	
>>CHOICE positioning mode					—	
>>>UE Based					—	
>>>Relative North	O		INTEGER (-20000..20000)	Seconds of angle, scale factor 0.03. Relative position compared to reference cell.	—	
>>>Relative East	O		INTEGER (-20000..20000)	Seconds of angle, scale factor 0.03. Relative position compared to reference cell.	—	
>>>Relative Altitude	O		INTEGER (-4000..4000)	Relative altitude in meters compared to ref. cell.	—	
>>>Fine SFN-SFN	O		INTEGER (0..15)	Gives finer resolution	—	
>>>Round Trip Time	O		INTEGER (0..32766)	In chips. Included if cell is in active set	—	
>> UE assisted					—	

>>Extended Round Trip Time	O		INTEGER (32767..103041)	In chips. Included if cell is in active set. Included only if the <i>Round Trip Time</i> IE above is included with its maximum value and if the actual value is outside the possible range for the <i>Round Trip Time</i> IE.	YES	ignore
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Table 103

Range bound	Explanation
maxCellMeas	Maximum number of cells to measure. The value is 32.

9.2.2.60 UL TrCH information

This IE contains the UL TrCH information used for the U-TDOA positioning method.

Table 104

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
Uplink transport channel type	M		ENUMERATED (DCH,USCH,...)	USCH is TDD only
TFS	M		9.2.2.48	

9.2.2.61 Semi-static Transport Format Information

This IE contains the Semi-static Transport Format information used for the U-TDOA positioning method.

Table 105

IE/Group Name	Presence	Range	IE Type and Reference	Semantics description
Transmission time interval	M		ENUMERATED(5, 10, 20, 40, 80, dynamic, ...)	In ms. The value dynamic is only used in TDD mode
Type of channel coding	M		ENUMERATED(No coding, Convolutional, Turbo, ...)	The option "No coding" is only valid for TDD.
Coding Rate	C-Coding		ENUMERATED(1/2, 1/3, ...)	
Rate matching attribute	M		INTEGER(1..hiRM)	
CRC size	M		ENUMERATED(0, 8, 12, 16, 24, ...)	In bits

Table 106

Condition	Explanation
Coding	This IE shall be present if Type of channel coding IE is "Convolutional" or "Turbo".

Table 107

Constant	Explanation	Value
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Constant	Explanation	Value
hiRM	Maximum number that could be set as rate matching attribute for a transport channel	256

9.2.2.62 Environment Characterisation

This IE contains the Environment Characterisation information used for the SAS centric mode.

Table 108

IE/Group Name	Presence	Range	IE Type and Reference	Semantics description
Environment Characterisation			ENUMERATED(heavy multipath and NLOS conditions, no or light multipath and usually LOS conditions, not defined or mixed environment, ...)	

9.2.2.63 Chip Offset

This IE contains the Chip Offset information used for the U-TDOA positioning method.

The Chip Offset is defined as the radio timing offset inside a radio frame. The Chip offset is used as offset relative to the Primary CPICH timing for the DL DPCH or for the F-DPCH.

Table 109

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
Chip Offset			INTEGER(0..38399)	Unit: chips

9.2.2.64 Frame Offset

This IE contains the Frame Offset information used for the U-TDOA positioning method.

The Frame Offset is the required offset between the dedicated channel downlink transmission frames (CFN, Connection Frame Number) and the broadcast channel frame offset (Cell Frame Number). The Frame Offset is used in the translation between Connection Frame Number (CFN) on Iub/Iur and the least significant 8 bits of SFN (System Frame Number) on Uu. The Frame Offset is UE and cell specific

Table 110

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
Frame Offset			INTEGER(0..255)	Unit: Frames

9.2.2.65 Position Data

This IE provides data related to the positioning methods used and reported in the SAS centric mode.

Table 111

IE/Group Name	Presence	Range	IE type and reference	Semantics description	Criticality	Assigned Criticality
Position Data	M				—	
>Positioning Data Discriminator	M		BIT STRING (4)	<p>The positioning data discriminator defines the type of data provided for each positioning method:</p> <p>0000 indicates the presence of the <i>Positioning Data Set</i> IE (that reports the usage of each non-GANSS method that was successfully used to obtain the location estimate)</p> <p>0001 indicates the presence of the GANSS Positioning Data Set IE (that reports the usage of each GANSS method that was successfully used to obtain the location estimate) and the absence of the <i>Positioning Data Set</i> IE</p> <p>1 octet of data is provided for each positioning method included.</p> <p>All other values are reserved.</p>	—	
>Positioning Data Set	C- ifDiscriminator=0				—	

>>Positioning Method and Usage		1..<maxSet>	OCTET STRING (1)	<p>Coding of positioning method (bits 8-4):</p> <p>00000 Reserved 00001 Reserved 00010 Reserved 00011 Reserved 00100 Reserved 00101 Mobile Assisted GPS 00110 Mobile Based GPS 00111 Conventional GPS 01000 U-TDOA 01001 OTDOA 01010 IPDL 01011 RTT 01100 Cell ID 01101 to 01111 reserved for other location technologies 10000 to 11111 reserved for network specific positioning methods</p> <p>Coding of usage (bits 3-1):</p> <p>000 Attempted unsuccessfully due to failure or interruption - not used. 001 Attempted successfully: results not used to generate location - not used. 010 Attempted successfully: results used to verify but not generate location - not used. 011 Attempted successfully: results used to generate location 100 Attempted successfully: case where MS supports multiple mobile based positioning methods and the actual method or methods used by the MS cannot be determined.</p>	-	
>GANSS Positioning Data Set			0..1		YES	ignore
>>GANSS Positioning Method and Usage		1..<maxGANSSet>	OCTET STRING (1)	<p>Coding of Method (Bits 8-7) :</p> <p>00 : MS-Based 01 : MS-Assisted 10 : Conventional 11 : Reserved</p> <p>Coding of GANSS ID (Bits 6-4) :</p> <p>000 : Galileo 001 : SBAS 010 : Modernized GPS 011 : QZSS 100 : GLONASS</p>	-	

				other values reserved Coding of usage (bits 3-1): 011 Attempted successfully: results used to generate location 100 Attempted successfully: case where MS supports multiple mobile based positioning methods and the actual method or methods used by the MS cannot be determined.		
--	--	--	--	---	--	--

Table 112

Condition	Explanation
ifDiscriminator=0	This IE is present if the <i>Positioning Data Discriminator</i> IE is set to "0000"

Table 113

Range bound	Explanation
maxSet	Maximum size of the data set. Value is 9.
maxGANSSSet	Maximum size of the data. Value is 9.

9.2.2.66 Transmission Gap Pattern Sequence Information

This IE contains the Transmission Gap Pattern Sequence information used for the U-TDOA positioning method when the UE is operating in the compressed mode.

Table 114

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
Transmission Gap Pattern Sequence Information		1..<maxTGPS>		
>TGPS Identifier	M		INTEGER(1..maxTGPS)	Transmission Gap Pattern Sequence Identifier: Establish a reference to the compressed mode pattern sequence. Up to <maxTGPS> simultaneous compressed mode pattern sequences can be used.
>TGSN	M		INTEGER(0..14)	Transmission Gap Starting Slot Number: The slot number of the first transmission gap slot within the TGCFN.
>TGL1	M		INTEGER(1..14)	The length of the first Transmission Gap within the transmission gap pattern expressed in number of slots.
>TGL2	O		INTEGER(1..14)	The length of the second Transmission Gap within the transmission gap pattern. If omitted, then TGL2=TGL1.
>TGD	M		INTEGER(0,15..269)	Transmission Gap Distance: indicates the number of slots between the starting slots of two consecutive transmission gaps within a transmission gap pattern. If there is only one transmission gap in the transmission gap pattern, this parameter shall be set to "0" ("0" =undefined).
>TGPL1	M		INTEGER(1..144, ...)	The duration of transmission gap pattern 1 in frames.
>Uplink Compressed Mode Method	M		ENUMERATED(SF/2, Higher Layer Scheduling, ...)	Method for generating uplink compressed mode gap.

Table 115

Range bound	Explanation
maxTGPS	Maximum number of transmission gap pattern sequences. The value is 6.

9.2.2.67 Active Pattern Sequence Information

This IE contains the Active Pattern Sequence information used for the U-TDOA positioning method when the UE is operating in the compressed mode.

Table 116

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
CM Configuration Change CFN	M		CFN 9.2.2.68	
Transmission Gap Pattern Sequence Status		0..<maxTGPS>		
>TGPS Identifier	M		INTEGER(1..maxTGPS)	If the group is not present, none of the pattern sequences are activated. References an already defined sequence.
>TGPRC	M		INTEGER(0..511)	The number of transmission gap patterns within the Transmission Gap Pattern Sequence. "0"=Infinity
>TGCFN	M		CFN 9.2.2.68	Connection Frame Number of the first frame of the first pattern 1 within the Transmission Gap Pattern Sequence.

Table 117

Range bound	Explanation
maxTGPS	Maximum number of transmission gap pattern sequences. The value is 6.

9.2.2.68 CFN

This IE contains the CFN used for the U-TDOA positioning method when the UE is operating in the compressed mode.

Table 118

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
CFN			INTEGER(0..255)	

9.2.2.69 Positioning Response Time

This IE contains the Positioning Response Time information used for SAS centric mode.

Table 119

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
Positioning Response Time			ENUMERATED(250, 500, 1000, 2000, 3000, 4000, 6000, 8000, 12000, 16000, 20000, 24000, 28000, 32000, 64000, ...)	Unit: millisecond

9.2.2.70 Reference Cell Position

Reference Cell Position IE is used to identify the position of the reference cell using geographical coordinates. The reference system is the same as the one used in [11].

Table 120

IE/Group Name	Presence	Range	IE type and reference	Semantics description
CHOICE Geographical Area				
>Point				Ellipsoid point
>>Geographical Coordinates	M		9.2.2.7	
>>Ellipsoid point with altitude				
>>Geographical Coordinates	M		9.2.2.7	
>>Altitude and direction	M		9.2.2.2	

9.2.2.71 UE Positioning IPDL Parameters

The *UE Positioning IPDL Parameters* IE is used for OTDOA in the SAS centric mode.

Table 121

IE/Group Name	Presence	Range	IE type and reference	Semantics description
CHOICE mode				
>FDD				
>>IP Spacing	M		ENUMERATED(5,7,10,15,20,30,40,50,...)	See [4]
>>IP Length	M		ENUMERATED(5,10,...)	See [4]
>>IP Offset	M		INTEGER(0..9)	See [4]
>>Seed	M		INTEGER(0..63)	See [4]
>TDD				
Burst Mode Parameters	O		9.2.2.72	

9.2.2.72 Burst Mode Parameters

Burst Mode Parameters IE is used for OTDOA in the SAS centric mode.

Table 122

IE/Group Name	Presence	Range	IE type and reference	Semantics description
Burst Start	M		INTEGER(0..15)	
Burst Length	M		INTEGER(10..25)	
Burst Frequency	M		INTEGER(1..16)	

9.2.2.73 SFN-SFN Relative Time Difference

SFN-SFN Relative Time Difference IE is used for OTDOA in the SAS centric mode

Table 123

IE/Group Name	Presence	Range	IE type and reference	Semantics description
SFN Offset	M		INTEGER (0..4095)	
SFN-SFN-Relative Time Difference	M		INTEGER (0..38399)	

9.2.2.74 UTDOA Group

This IE contains information used for the U-TDOA positioning method.

Table 124

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
UTRAN Cell Identifier	M		9.2.2.37	
Frequency Information	M		9.2.2.42	
Choice <i>RRC State</i>	M			
> <i>CELL_DCH</i>				
>>Uplink DPCH Information	M		9.2.2.41	
>>Compressed Mode Assistance Data	O		9.2.2.44	FDD only
>> DCH Information		0..1		
>>> TFCS		1..<maxTFC>		
>>>> CTFC	M		9.2.2.49	
>>>> TrCH Information List		1..<maxTrCH>		
>>>>UL TrCH Information	M		9.2.2.60	
>> E-DPCCH Information		0..1		FDD only
>>>Maximum Set of E-DPDCHs	M		9.2.2.75	
>>>Puncture Limit	M		9.2.2.76	
>>>E-TFCS Information	M		9.2.2.77	
>>>E-TTI	M		9.2.2.79	
>>>E-DPCCH Power Offset	O		9.2.2.80	
> <i>CELL_FACH</i>				
>>PRACH Parameters	M		9.2.2.43	
>>C-RNTI	M		9.2.2.45	
>>USCH parameters	O		9.2.2.95	TDD only

Table 125

Range bound	Explanation
maxTFC	Maximum number of TFC. The value is 1024.
maxTrCH	Maximum number of Transport Channels. The value is 32.

9.2.2.75 Maximum Set of E-DPDCHs

The Maximum Set of E-DPDCHs parameter, as defined in [16], is used in UTDOA positioning method.

Table 126

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
Maximum Set of E-DPDCHs			ENUMERATED (vN64, vN32, vN16, vN8, vN4, v2xN4, v2xN2, v2xN2plus2xN4, ...)	

9.2.2.76 Puncture Limit

The Puncture Limit parameter is used in UTDOA positioning method indicating the limit in the amount of puncturing that can be applied in order to minimise the number of dedicated physical channels.

Table 127

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
Puncture Limit			INTEGER (0..15)	Unit: % Range: 40..100 % Step: 4 % 100% means no puncturing

9.2.2.77 E-DCH Transport Format Combination Set Information (E-TFCS Information)

This IE is used in UTDOA positioning method. Whereas the related Transport Block sizes are standardised in [ref is FFS] this IE gives details on the referenced Transport Block Size Table and the Reference E-TFCIs.

Table 128

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
E-DCH Transport Format Combination Set Index	M		INTEGER (1..4, ...)	Indicates which standardised E-TFCS Transport Block Size Table shall be used. The related tables are specified in [ref FFS].
Reference E-TFCI Information		0..<maxnoofRefETFCIs>		
>Reference E-TFCI	M		INTEGER (0..127)	
>Reference E-TFCI Power Offset	M		9.2.2.78	

Table 129

Range Bound	Explanation
maxnoofRefETFCIs	Maximum number of signalled reference E-TFCIs

9.2.2.78 Reference E-TFCI Power Offset

The Reference E-TFCI Power Offset is used in UTDOA positioning method indicating how to calculate the reference E-TFCI gain factor.

Table 130

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
Reference E-TFCI Power Offset			INTEGER (0..8)	According to mapping in ref. [17] subclause 4.2.1.3

9.2.2.79 E-TTI

The E-TTI parameter is used in UTDOA positioning method indicating the Transmission Time Interval for E-DPCH operation.

Table 131

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
E-TTI			ENUMERATED (2ms, 10ms, ...)	

9.2.2.80 E-DPCCH Power Offset

The E-DPCCH Power Offset is used in UTDOA positioning method indicating how to calculate the E-DPCCH gain factor.

Table 132

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
E-DPCCH Power Offset			INTEGER (0..8)	According to mapping in ref. [17] subclause 4.2.1.3.

9.2.2.81 Cell Parameter ID

The Cell Parameter ID identifies unambiguously the Code Groups, Scrambling Codes, Midambles and Toffset (see ref. [18]).

Table 133

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
Cell Parameter ID			INTEGER (0..127,...)	

9.2.2.82 TFCI Coding

The TFCI Coding describes the way how the TFCI bits are coded. By default 1 TFCI bit is coded with 4 bits, 2 TFCI bits are coded with 8 bits, 3-5 TFCI bits are coded with 16 bits and 6-10 TFCI bits are coded with 32 bits.

Table 134

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
TFCI Coding			ENUMERATED (4, 8, 16, 32,...)	

9.2.2.83 Repetition Length

The Repetition Length represents the number of consecutive Radio Frames inside a Repetition Period in which the same Time Slot is assigned to the same Physical Channel see ref. [4].

Table 135

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
Repetition Length			INTEGER (1..63)	

9.2.2.84 Repetition Period

The Repetition Period represents the number of consecutive Radio Frames after which the same assignment scheme of Time Slots to a Physical Channel is repeated. This means that if the Time Slot K is assigned to a physical channel in the Radio Frame J , it is assigned to the same physical channel also in all the Radio Frames $J+n^*Repetition\ Period$ (where n is an integer) see ref. [4].

Table 136

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
Repetition Period			ENUMERATED (1, 2, 4, 8, 16, 32, 64,...)	

9.2.2.85 TDD DPCH Offset

The Offset represents the phase information for the allocation of a group of dedicated physical channels. The first range is used when a starting offset is not required and the TDD Physical channel offset for each DPCH in the CCTrCH shall be directly determined from the TDD DPCH Offset. The second range is used when a starting offset is required. The TDD DPCH Offset shall map to the CFN and the TDD Physical Channel Offset for each DPCH in this CCTrCH shall be calculated by TDD DPCH Offset mod Repetition period, see ref. [4].

Table 137

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
CHOICE Offset Type				
>Initial Offset				
>>TDD DPCH Offset Value	M		INTEGER (0..255)	
>No Initial Offset				
>>TDD DPCH Offset Value	M		INTEGER (0..63)	

9.2.2.86 UL Timeslot Information

The *UL Timeslot Information* IE provides information on the time slot allocation for an UL DPCH.

Table 138

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
UL Timeslot Information		$1..<\maxno\\nofULts>$		
>Time Slot	M		9.2.2.87	
>Midamble Shift And Burst Type	M		9.2.2.88	
>TFCI Presence	M		9.2.2.89	
>UL Code Information	M		9.2.2.90	

9.2.2.87 Time Slot

The Time Slot represents the minimum time interval inside a Radio Frame that can be assigned to a Physical Channel.

Table 139

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
Time Slot			INTEGER (0..14)	

9.2.2.88 Midamble Shift And Burst Type

This information element indicates burst type and midamble allocation.

The 256 chip midamble supports 3 different time shifts, the 512 chips midamble may support 8 or even 16 time shifts.

Three different midamble allocation schemes exist:

Default midamble: the midamble shift is selected by layer 1 depending on the associated channelisation code (DL and UL)

Common midamble: the midamble shift is chosen by layer 1 depending on the number of channelisation codes (possible in DL only)

UE specific midamble: a UE specific midamble is explicitly assigned (DL and UL)

Table 140

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
CHOICE Burst Type				
>Type1				
>>Midamble Configuration Burst Type 1 And 3	M		INTEGER (4, 8, 16)	As defined in [19]
>>CHOICE Midamble Allocation Mode	M			
>>>Default Midamble			NULL	
>>>Common Midamble			NULL	
>>>UE Specific Midamble				
>>Midamble Shift Long	M		INTEGER (0..15)	
>Type2				
>>Midamble Configuration Burst Type 2	M		INTEGER (3,6)	As defined in [19]
>>CHOICE Midamble Allocation Mode	M			
>>>Default Midamble			NULL	
>>>Common Midamble			NULL	
>>>UE Specific Midamble				
>>Midamble Shift Short	M		INTEGER (0..5)	
>Type3				UL only
>>Midamble Configuration Burst Type 1 And 3	M		INTEGER (4, 8, 16)	As defined in [19]
>>CHOICE Midamble Allocation Mode	M			
>>>Default Midamble			NULL	
>>>UE Specific Midamble				
>>Midamble Shift Long	M		INTEGER (0..15)	

9.2.2.89 TFCI Presence

The TFCI Presence parameter indicates whether the TFCI shall be included. [TDD - If it is present in the timeslot, it will be mapped to the channelisation code defined by [19].]

Table 141

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
TFCI presence			ENUMERATED (Present, Not Present)	

9.2.2.90 TDD UL Code Information

The *TDD UL Code Information* IE provides information for UL Codes that have been established.

Table 142

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
TDD UL Code Information		$1..<\maxno_{ofDPCHs}>$		
>TDD Channelisation Code	M		9.2.2.91	

Table 143

Range Bound	Explanation
$\maxno_{ofDPCHs}$	Maximum number of DPCHs in one CCTrCH

9.2.2.91 TDD Channelisation Code

The Channelisation Code Number indicates which Channelisation Code is used for a given Physical Channel. In TDD the Channelisation Code is an Orthogonal Variable Spreading Factor code, that can have a spreading factor of 1, 2, 4, 8 or 16.

Table 144

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
TDD Channelisation Code			ENUMERATED (1/1), (2/1), (2/2), (4/1), .. (4/4), (8/1), .. (8/8), (16/1), .. (16/16),...)	

9.2.2.92 Special Burst Scheduling

This information element expresses the number of frames between special burst transmissions during DTX.

Table 145

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
Special Burst Scheduling			INTEGER (1..256)	Number of frames between special burst transmission during DTX

9.2.2.93 Max PRACH Midamble Shift

Indicates the maximum number of Midamble shifts to be used in a cell.

Table 146

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
Max PRACH Midamble Shift			ENUMERATED (4, 8,...)	

9.2.2.94 PRACH Midamble

The PRACH Midamble indicates if only the Basic Midamble Sequence or also the time-inverted Midamble Sequence is used.

Table 147

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
PRACH Midamble			ENUMERATED (Inverted, Direct, ...)	

9.2.2.95 USCH Parameters

In Cell-FACH state, when the UE supports the USCH, and the CRNC is equal to the SRNC, the UE may be given periodic allocations on the uplink shared channel. Furthermore, the UE may also be configured to generate special bursts instead of uplink shared channel transmissions. This information element defines the uplink shared channel transmissions.

Table 148

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
Cell Parameter ID	M		9.2.2.81	
TFCI Coding	M		9.2.2.82	
Puncture Limit	M		9.2.2.76	
Repetition Period	M		9.2.2.84	This is the scheduling interval on the USCH.
USCH Scheduling Offset	M		9.2.2.96	
UL Timeslot Information	M		9.2.2.86	
TFCS		1..<maxTF C>		
>CTFC	M		9.2.2.49	
TrCH Information List		1..<maxTr CH>		
>UL TrCH Information	M		9.2.2.60	

Table 149

Range bound	Explanation
maxTFC	Maximum number of TFC. The value is 1024.
maxTrCH	Maximum number of Transport Channels. The value is 32.

9.2.2.96 USCH Scheduling Offset

This information element indicates the offset relative to CFN=0 that the transmission on the uplink shared channel shall take place.

Table 150

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
USCH scheduling offset			INTEGER(0..255)	

9.2.2.97 Include Velocity

This element indicates that the UE's velocity is requested.

Table 151

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
Include Velocity	M		ENUMERATED (requested)	

9.2.2.98 Velocity Estimate

The *Velocity Estimate* IE is used to describe the UE's velocity. The reference system is the same as used in [11].

Table 152

IE/Group Name	Presence	Range	IE type and reference	Semantics description
Choice <i>Velocity Estimate</i>				
>Horizontal Velocity				Horizontal speed and bearing (the direction of travel).
>>Horizontal Speed and Bearing	M		9.2.2.99	
>Horizontal with Vertical Velocity				Horizontal speed and bearing (the direction of travel) as well as vertical speed and the direction (upward or downward)
>>Horizontal Speed and Bearing	M		9.2.2.99	
>>Vertical Velocity	M		9.2.2.100	
>Horizontal Velocity with Uncertainty				Horizontal speed, bearing (the direction of travel), and the uncertainty of the reported speed.
>>Horizontal Speed and Bearing	M		9.2.2.99	
>>Uncertainty Speed	M		INTEGER (0..255)	Uncertainty speed is encoded in increments of 1 kilometer per hour using an 8 bit binary coded number (N). The value of N gives the uncertainty speed except for N=255 which indicates that the uncertainty is not specified
>Horizontal with Vertical Velocity and Uncertainty				Horizontal speed and bearing (the direction of travel) as well as vertical speed and the direction (upward or downward) and the uncertainty of the reported speed.
>>Horizontal Speed and Bearing	M		9.2.2.99	
>>Vertical Velocity	M		9.2.2.100	
>>Horizontal Uncertainty Speed	M		INTEGER (0..255)	Horizontal Uncertainty Speed is encoded in increments of 1 kilometer per hour using an 8 bit binary coded number (N). The value of N gives the uncertainty speed except for N=255 which indicates that the uncertainty is not specified
>>Vertical Uncertainty Speed	M		INTEGER (0..255)	Vertical Uncertainty Speed is encoded in increments of 1 kilometer per hour using an 8 bit binary coded number (N). The value of N gives the uncertainty speed except for N=255 which indicates that the uncertainty is not specified

9.2.2.99 Horizontal Speed and Bearing

This IE contains the two components of horizontal velocity: speed and bearing

Table 153

IE/Group Name	Presence	Range	IE type and reference	Semantics description
Bearing	M		INTEGER (0..359)	The direction of movement is given in degrees where '0' represents North, '90' represents East, etc.
Horizontal Speed	M		INTEGER (0..<2 ¹¹ -1)	The relationship between (N) and the horizontal speed (h) in kilometers per hour it describes is: $N \leq h < N + 0.5$ (N=0) $N - 0.5 \leq h < N + 0.5$ (0<N<2 ¹¹ -1) $N - 0.5 \leq h$ (N = 2 ¹¹ -1)

9.2.2.100 Vertical Velocity

This IE contains the two components of vertical velocity: speed and direction

Table 154

IE/Group Name	Presence	Range	IE type and reference	Semantics description
Vertical Speed	M		INTEGER (0..2 ⁸ -1)	The relationship between (N) and the vertical speed (v) in kilometers per hour it describes is: $N \leq v < N + 0.5$ (N = 0) $N - 0.5 \leq v < N + 0.5$ (0 < N < 2 ⁸ -1) $N - 0.5 \leq v$ (N = 2 ⁸ -1)
Vertical Speed Direction			ENUMERATED (upward, downward)	

9.2.2.101 GPS Positioning Instructions

This information element contains positioning instructions for GPS positioning method in SAS-centric mode.

Table 155

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description	Criticality	Assigned Criticality
Horizontal Accuracy Code	O		9.2.2.38		–	
Vertical Accuracy Code	O		9.2.2.39		–	
GPS Timing of Cell Wanted	M		BOOLEAN	This IE is set to TRUE if the UE is requested to report SFN-GPS timing of the reference cell.	–	
Additional Assistance Data Request	M		BOOLEAN	TRUE indicates that the UE is requested to send an additional assistance data request if the provided assistance data are not sufficient.	–	
Measurement Validity	O		ENUMERATED(CELL_DCH, all states except CELL_DCH, all states, ...)		YES	ignore

9.2.2.102 UE Position Estimate Info

The UE Position Estimate Info is used in UE-based positioning methods providing the UE position estimate from the RNC to the SAS in SAS-centric mode.

Table 156

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description	Criticality	Assigned Criticality
CHOICE Reference Time	M				—	
>UTRAN GPS reference time Result			9.2.2.104		—	
>GPS reference time only					—	
>>GPS TOW msec	M		INTEGER (0..6.048*10 ⁸ -1, ...)	GPS Time of Week in milliseconds.	—	
>Cell timing					—	
>>SFN	M		INTEGER (0..4095)	SFN during which the position was calculated.	—	
>>UC-ID	M		UTRAN Cell Identifier 9.2.2.37	Identifies the reference cell for SFN.	—	
>UTRAN GANSS reference time result			9.2.2.136		—	
>GANSS reference time only					—	
>>GANSS TOD msec	M		INTEGER(0..35 99999)	GANSS Time of Day in milliseconds.	—	
>>GANSS time ID	O		GANSS ID 9.2.2.130	Absence of this IE means Galileo system time. The value '0' ('SBAS') shall not be used for GANSS Time ID.	—	
UE Position Estimate	M		Geographical Area 9.2.2.6		—	
GPS Reference Time Uncertainty	O		9.2.2.132		YES	ignore
Position Data	O		Bit String(16)	For each bit, if set to '1' indicates that respective GNSS or position system was used for position calculation. Coded as defined in [4].	YES	ignore

9.2.2.103 UTRAN-GPS Reference Time

Table 157

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
UTRAN GPS timing of cell frames	M		INTEGER (0..2322431999999, ...)	GPS timing of cell frames in steps of 1 chip.
UC-ID	O		UTRAN Cell Identifier 9.2.2.37	Identifies the reference cell for the GPS TOW-SFN relationship.
SFN	M		INTEGER (0..4095)	The SFN which the UTRAN GPS timing of cell frames time stamps.

9.2.2.104 UTRAN-GPS Reference Time Result

Table 158

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
UE GPS timing of cell frames	M		INTEGER(0..37158911999999, ...)	GPS Time of Week in units of 1/16 th UMTS chips according to [13].
UC-ID	M		UTRAN Cell Identifier 9.2.2.37	Identifies the reference cell for the GPS TOW-SFN relationship
SFN	M		INTEGER(0..4095)	This IE indicates the SFN at which the UE timing of cell frame is captured.

9.2.2.105 $T_{\text{UTRAN-GPS}}$ Drift Rate

Table 159

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
$T_{\text{UTRAN-GPS}}$ Drift Rate	O		ENUMERATED (0, 1, 2, 5, 10, 15, 25, 50, -1, -2, -5, -10, -15, -25, -50, ...)	In 1/256 chips per sec.

9.2.2.106 Periodic Position Calculation Info

The Periodic Position Calculation Info contains information required for periodic location in RNC-centric mode.

Table 160

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
Reference Number	M		INTEGER(0..32767, ...)	This IE is used to uniquely associate all periodic Position Calculation procedures belonging to the location of the same target UE for periodic location. Position Calculation procedures belonging to the same target UE for periodic location shall use the same Reference Number.
Amount of Outstanding Requests	M		INTEGER(1..8639999,...)	This IE indicates the amount of outstanding periodic requests. This IE shall be set to the total number of periodic requests in the first Position Calculation Request message, and decrement by 1 for each new Position Calculation Request for periodic location. When the number reaches 1, the SAS will know that the periodic location is complete.
Reporting Interval	M		INTEGER(1..8639999,...)	This IE indicates the reporting interval in seconds when the SAS can expect a next Position Calculation Request associated to the same target UE in periodic location.

9.2.2.107 Periodic Location Info

The Periodic Location Info contains the periodic reporting interval and reporting amount for periodic location.

Table 161

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
Reporting Amount	M		INTEGER(1..8639999,...)	This IE indicates the amount of periodic reports.
Reporting Interval	M		INTEGER(1..8639999,...)	This IE indicates the reporting interval in seconds.

9.2.2.108 Amount of Reporting

The Amount of Reporting together with the *RNC Response Time IE* in a POSITION ACTIVATION REQUEST message defines the periodical reporting criteria.

Table 162

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
Amount of Reporting	M		ENUMERATED(2, 4, 8, 16, 32, 64, Infinity, ...)	Amount of reporting for a periodic location procedure.

9.2.2.109 Measurement Instructions Used

This information element contains measurement instructions used by the SRNC upon reception of a POSITION ACTIVATION REQUEST message.

Table 163

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
Measurement Validity	M		ENUMERATED(CELL_DCH, all states except CELL_DCH, all states, ...)	

9.2.2.110 RRC State Change

Table 164

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
New RRC State	M		ENUMERATED(CELL_DCH, CELL_FACH, CELL_PCH, URA_PCH, ...)	

9.2.2.111 Periodic Position Termination Cause

The Position Periodic Termination Cause element indicates the reason for termination of a periodic reporting procedure in SAS-centric mode.

Table 165

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
Periodic Position Termination Cause	M		ENUMERATED(RRC State Transition, Cancelled by SRNC, Cancelled by SAS, Undefined, ...)	

9.2.2.112 Requested Cell-ID Measurements

This information element contains a list of requested measurements for Cell-ID positioning method in SAS-centric mode.

Table 166

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
Choice mode	M			
>FDD				
>>Round Trip Time Info	M		BOOLEAN	If set to TRUE, the RNC is requested to include the <i>Round Trip Time Info</i> IE in the Cell-ID Measured Results Info List.
>>Pathloss	M		BOOLEAN	If set to TRUE, the RNC is requested to include the <i>Pathloss</i> IE in the Cell-ID Measured Results Info List.
>>Round Trip Time Info With Type 1	M		BOOLEAN	If set to TRUE, the RNC is requested to include the <i>Round Trip Time Info With Type 1</i> IE in the Cell-ID Measured Results Info List.
>>CPICH RSCP	M		BOOLEAN	If set to TRUE, the RNC is requested to include the <i>CPICH RSCP</i> IE in the Cell-ID Measured Results Info List.
>>CPICH Ec/N0	M		BOOLEAN	If set to TRUE, the RNC is requested to include the <i>CPICH Ec/N0</i> IE in the Cell-ID Measured Results Info List.
>TDD				
>>Rx Timing Deviation Info	M		BOOLEAN	If set to TRUE, the RNC is requested to include the <i>Rx Timing Deviation Info</i> IE in the Cell-ID Measured Results Info List.
>>Pathloss	M		BOOLEAN	If set to TRUE, the RNC is requested to include the <i>Pathloss</i> IE in the Cell-ID Measured Results Info List.
>>Rx Timing Deviation LCR Info	M		BOOLEAN	If set to TRUE, the RNC is requested to include the <i>Rx Timing Deviation LCR Info</i> IE in the Cell-ID Measured Results Info List.
>>Rx Timing Deviation 768Info	M		BOOLEAN	If set to TRUE, the RNC is requested to include the <i>Rx Timing Deviation 768Info</i> IE in the Cell-ID Measured Results Info List.
>>Rx Timing Deviation 384ext Info	M		BOOLEAN	If set to TRUE, the RNC is requested to include the <i>Rx Timing Deviation 384ext Info</i> IE in the Cell-ID Measured Results Info List.
>>Angle Of Arrival LCR	M		BOOLEAN	If set to TRUE, the RNC is requested to include the <i>Angle Of Arrival LCR</i> IE in the Cell-ID Measured Results Info List.
>>Timing Advance LCR	M		BOOLEAN	If set to TRUE, the RNC is requested to include the <i>Timing Advance LCR</i> IE (or the <i>Extended Timing Advance LCR</i> IE) in the Cell-ID Measured Results Info List.

9.2.2.113 DGANSS Corrections

This IE contains DGANSS corrections to be used by the UE.

Table 167

IE/Group name	Presence	Range	IE Type and Reference	Semantics description

IE/Group name	Presence	Range	IE Type and Reference	Semantics description
DGANSS Reference Time	M		INTEGER(0..3570 by step of 30)	Seconds. Time in GNSS system time (modulo 3600 s) when the DGANSS corrections were calculated
DGANSS Information		1..<maxSgnType>		
>GANSS Signal ID	O		9.2.2.131	Absence of this field means the default value for the GANSS identified by "GANSS ID" [4].
>Status/Health	M		ENUMERATED(UDRE scale 1.0, UDRE scale 0.75, UDRE scale 0.5, UDRE scale 0.3, UDRE scale 0.2, UDRE scale 0.1, no data, invalid data)	
>DGANSS Signal Information	C-Status/Health	1..<maxGANSSat>		
>>Sat ID	M		INTEGER(0..63)	Defined in [4].
>>IOD	M		BIT STRING(10)	
>>UDRE	M		ENUMERATED(UDRE ≤ 1.0 m, 1.0m < UDRE ≤ 4.0m, 4.0m < UDRE ≤ 8.0m, 8.0m < UDRE)	The value in this field shall be multiplied by the UDRE Scale Factor in the IE Status/Health to determine the final UDRE estimate for the particular satellite.
>>PRC	M		INTEGER(-2047..2047)	Scaling factor 0.32 meters
>>RRC	M		INTEGER(-127..127)	Scaling factor 0.032 meters/sec

Table 167A

Range bound	Explanation
maxSgnType	Maximum number of signals for which data is included in this IE. The value of maxSgnType is 8
maxGANSSat	Maximum number of satellites for which data is included in this IE. The value of maxGANSSat is 64

Table 167B

Condition	Explanation
Status/Health	This IE shall be present if the Status/Health IE value is not equal to "no data" or "invalid data".

9.2.2.114 GANSS Almanac and Satellite Health

This IE contains a reduced-precision subset of the ephemeris and clock correction parameters.

Table 168

IE/Group name	Presence	Range	IE Type and Reference	Semantics description

IE/Group name	Presence	Range	IE Type and Reference	Semantics description
Week Number	M		INTEGER(0..255)	Almanac reference week , number of weeks since the beginning of GANSS specific system time (mod 256)
<i>CHOICE Almanac Model</i>	M			
<i>>Keplerian Parameters</i>				Model 1
>>T _{oa}	M		INTEGER(0..255)	Scaling factor 2 ¹² s Reference time of almanac within week in GANSS TOD time base
>>IOD _a	M		INTEGER(0..3)	Issue-Of –Data, common to all satellites
>>Satellite Information KP		1..<maxGANSSSatAlm anac>		Almanacs are in the order of the SV IDs, the smallest ID first.
>>>Sat ID	M		INTEGER(0..63)	Defined in [4].
>>>e	M		BIT STRING(11)	Eccentricity, dimensionless [22]
>>>δi	M		BIT STRING(11)	semi-circles [22]
>>>OMEGADOT	M		BIT STRING(11)	Longitude of Ascending Node of Orbit Plane at Weekly Epoch (semi-circles/sec) [22]
>>>SV Health KP	M		BIT STRING(4)	dimensionless
>>>delta A ^{1/2}	M		BIT STRING(17)	Semi-Major Axis delta (meters) ^{1/2} [22]
>>>OMEGA ₀	M		BIT STRING(16)	Longitude of Ascending Node of Orbit Plane at Weekly Epoch (semi-circles) [22]
>>>M ₀	M		BIT STRING(16)	Mean Anomaly at Reference Time (semi-circles) [22]
>>>ω	M		BIT STRING(16)	Argument of Perigee (semi-circles) [22]
>>>af ₀	M		BIT STRING(14)	Seconds [22]
>>>af ₁	M		BIT STRING(11)	sec/sec [22]
<i>>NAV Keplerian Parameters</i>				Model 2
>>T _{oa}	M		INTEGER(0..255)	Scaling factor 2 ¹² s Reference time of almanac within week in GANSS TOD time base
>>Satellite information NAV-KP		1..<maxGANSSSatAlm anac>		
>>>Sat ID	M		INTEGER(0..63)	Defined in [4].
>>>e	M		BIT STRING(16)	Eccentricity, dimensionless [27]
>>>δi	M		BIT STRING(16)	Correction to inclination, semi-circles [27]
>>>OMEGADOT	M		BIT STRING(16)	Rate of right ascension, semi-circles/sec [27]
>>>SV Health	M		BIT STRING(8)	Satellite health [27]
>>>A ^{1/2}	M		BIT STRING(24)	Square root of the semi-major axis, meters ^{1/2} [27]
>>>OMEGA ₀	M		BIT STRING(24)	Longitude of ascending node of orbit plane at weekly epoch, semi-circles [27]

IE/Group name	Presence	Range	IE Type and Reference	Semantics description
>>> ω	M		BIT STRING (24)	Argument of perigee semi-circles [27]
>>> M_0	M		BIT STRING (24)	Mean anomaly at reference time semi-circles [27]
>>> a_{f0}	M		BIT STRING (11)	Apparent satellite clock correction seconds [27]
>>> a_{f1}	M		BIT STRING (11)	Apparent satellite clock correction sec/sec [27]
>Reduced Keplerian Parameters				Model 3
>> T_{oa}	M		INTEGER(0..255)	Scaling factor 2^{12} s Reference time of almanac within week in GANSS TOD time base
>>Satellite information RED-KP		1..<maxGAN SSSatAlm anac>		
>>>Sat ID	M		INTEGER (0..63)	Defined in [4].
>>> δ_A	M		BIT STRING(8)	meters [23,24,25,27]
>>> Ω_0	M		BIT STRING (7)	semi-circles [23,24,25,27]
>>> Φ_0	M		BIT STRING (7)	semi-circles [23,24,25,27]
>>>L1 Health	M		BIT STRING (1)	dimensionless [23,24,25,27]
>>>L2 Health	M		BIT STRING (1)	dimensionless [23,24,25,27]
>>>L5 Health	M		BIT STRING (1)	dimensionless [23,24,25,27]
>Midi Keplerian Parameters				Model 4
>> T_{oa}	M		INTEGER(0..255)	Scaling factor 2^{12} s Reference time of almanac within week in GANSS TOD time base
>>Satellite information MIDI-KP		1..<maxGAN SSSatAlm anac>		
>>>Sat ID	M		INTEGER (0..63)	Defined in [4].
>>> e	M		BIT STRING(11)	dimensionless [23,24,25,27]
>>> δ_i	M		BIT STRING (11)	semi-circles [23,24,25,27]
>>> Ω_{dot}	M		BIT STRING (11)	semi-circles/sec [23,24,25,27]
>>> \sqrt{A}	M		BIT STRING (17)	meters $^{1/2}$ [23,24,25,27]
>>> Ω_0	M		BIT STRING (16)	semi-circles [23,24,25,27]
>>> ω	M		BIT STRING (16)	semi-circles [23,24,25,27]
>>> M_0	M		BIT STRING (16)	semi-circles [23,24,25,27]
>>> a_{f0}	M		BIT STRING (11)	seconds [23,24,25,27]
>>> a_{f1}	M		BIT STRING (10)	sec/sec [23,24,25,27]
>>>L1 Health	M		BIT STRING	Dimensionless [23,24,25,27]

IE/Group name	Presence	Range	IE Type and Reference	Semantics description
			(1)	
>>>L2 Health	M		BIT STRING (1)	dimensionless [23,24,25,27]
>>>L5 Health	M		BIT STRING (1)	dimensionless [23,24,25,27]
>GLONASS Keplerian Parameters				Model 5
>>Satellite information GLO-KP		1.. <maxGAN SSSatAlm anac>		
>>>N ^A	M		BIT STRING(11)	days [28]
>>>n ^A	M		BIT STRING (5)	dimensionless [28]
>>>H _n ^A	M		BIT STRING (5)	dimensionless [28]
>>>λ _n ^A	M		BIT STRING (21)	semi-circles [28]
>>>t _{λn} ^A	M		BIT STRING (21)	seconds [28]
>>>Δi _n ^A	M		BIT STRING (18)	semi-circles [28]
>>>ΔT _n ^A	M		BIT STRING (22)	sec/orbit period [28]
>>>ΔT_DOT _n ^A	M		BIT STRING (7)	sec/orbit period ² [28]
>>>ε _n ^A	M		BIT STRING (15)	dimensionless [28]
>>>ω _n ^A	M		BIT STRING (16)	semi-circles [28]
>>>τ _n ^A	M		BIT STRING (10)	seconds [28]
>>>C _n ^A	M		BIT STRING (1)	dimensionless [28]
>>>M _n ^A	O		BIT STRING (2)	dimensionless [28]
>SBAS ECEF Parameters				Model 6
>>Satellite information SBAS-ECEF		1.. <maxGAN SSSatAlm anac>		
>>>Data ID	M		BIT STRING(2)	Dimensionless [26]
>>>SV ID	M		INTEGER (0..63)	Defined in [4].
>>>Health	M		BIT STRING (8)	Dimensionless [26]
>>>X _G	M		BIT STRING (15)	meters [26]
>>>Y _G	M		BIT STRING (15)	meters [26]
>>>Z _G	M		BIT STRING (9)	meters [26]
>>>X _G Rate-of-Change	M		BIT STRING (3)	meters/sec [26]
>>>Y _G Rate-of-Change	M		BIT STRING (3)	meters/sec [26]
>>>Z _G Rate-of-Change	M		BIT STRING (4)	meters/sec [26]
>>>t ₀	M		BIT STRING (11)	seconds [26]

Table 168A

Range bound	Explanation
maxGANSSSatAlmanac	Maximum number of satellites for which data is included in this IE. The value of maxGANSSSat is 36

9.2.2.115 GANSS Clock Model

The IE contains fields needed to model the GANSS clock parameters.

Table 169

IE/Group name	Presence	Range	IE Type and Reference	Semantics description
Satellite Clock Model		1..<maxGANSSClockMod>		Model-1. There may be more than one clock model included if defined in SIS ICD (e.g. two for Galileo)
>t _{oc}	M		BIT STRING(14)	defined in [22]
>a _{i2}	M		BIT STRING(12)	defined in [22]
>a _{i1}	M		BIT STRING(18)	defined in [22]
>a _{i0}	M		BIT STRING(28)	defined in [22]
>T _{GD}	O		BIT STRING(10)	defined in [22]
>Model ID	O		INTEGER(0..3)	Coded as defined in Table 169B.

Table 169A

Range bound	Explanation
maxGANSSClockMod	Maximum number of satellite clock models for which data is included in this IE. The value of maxGANSSClockMod is 4

Table 169B

GANSS Id	Model ID Value	Explanation
Galileo	0	I/NAV
	1	F/NAV
	2	Reserved
	3	Reserved

9.2.2.115A GANSS Additional Clock Models

The IE contains fields needed to model the GANSS clock parameters.

Table 169C

IE/Group name	Presence	Range	IE Type and Reference	Semantics description

IE/Group name	Presence	Range	IE Type and Reference	Semantics description
CHOICE Additional Clock Models				
>NAV-Clock Model				Model-2
>> t_{oc}	M		BIT STRING(16)	Time of clock (seconds) [27]
>> a_{f2}	M		BIT STRING(8)	Clock correction polynomial coefficient (sec/sec ²) [27]
>> a_{f1}	M		BIT STRING(16)	Clock correction polynomial coefficient (sec/sec) [27]
>> a_{f0}	M		BIT STRING(22)	Clock correction polynomial coefficient (seconds) [27]
>> T_{GD}	M		BIT STRING(8)	Group delay (seconds) [27]
>CNAV/CNAV-2 Clock Model				Model-3
>> t_{oc}	M		BIT STRING(11)	Clock data reference time of week (seconds) [23, 24, 25, 27]
>> t_{op}	M		BIT STRING(11)	Clock data predict time of week (seconds) [23, 24, 25, 27]
>>URA _{oc} Index	M		BIT STRING(5)	SV clock accuracy index (dimensionless) [23, 24, 25, 27]
>>URA _{oc1} Index	M		BIT STRING(3)	SV clock accuracy change index (dimensionless) [23, 24, 25, 27]
>>URA _{oc2} Index	M		BIT STRING(3)	SV clock accuracy change rate index (dimensionless) [23, 24, 25, 27]
>> a_{f2-n}	M		BIT STRING(10)	SV clock drift rate correction coefficient (sec/sec ²) [23, 24, 25, 27]
>> a_{f1-n}	M		BIT STRING(20)	SV clock drift correction coefficient (sec/sec) [23, 24, 25, 27]
>> a_{f0-n}	M		BIT STRING(26)	SV clock bias correction coefficient (seconds) [23, 24, 25, 27]
>> T_{GD}	M		BIT STRING(13)	Group delay correction (seconds) [23, 24, 25, 27]
>>ISC _{L1CP}	O		BIT STRING(13)	Inter signal group delay correction (seconds) [25, 27]
>>ISC _{L1CD}	O		BIT STRING(13)	Inter signal group delay correction (seconds) [25, 27]
>>ISC _{L1C/A}	O		BIT STRING(13)	Inter signal group delay correction (seconds) [23, 24, 27]
>>ISC _{L2C}	O		BIT STRING(13)	Inter signal group delay correction (seconds) [23, 24, 27]
>>ISC _{L515}	O		BIT STRING(13)	Inter signal group delay correction (seconds) [24, 27]
>>ISC _{L5Q5}	O		BIT STRING(13)	Inter signal group delay correction (seconds) [24, 27]
>GLONASS Satellite Clock Model				Model-4

IE/Group name	Presence	Range	IE Type and Reference	Semantics description
$>\tau_n(t_b)$	M		BIT STRING (22)	Satellite clock offset (seconds) [28]
$>\gamma_n(t_b)$	M		BIT STRING (11)	Relative frequency offset from nominal value (dimensionless) [28]
$>\Delta\tau_n$	O		BIT STRING (5)	Time difference between transmission in G2 and G1 (seconds) [28]
<i>>SBAS Satellite Clock Model</i>				Model-5
$>t_0$	M		BIT STRING (13)	(seconds) [26]
$>a_{Gf0}$	M		BIT STRING (12)	(seconds) [26]
$>a_{Gf1}$	M		BIT STRING (8)	(sec/sec) [26]

9.2.2.116 GANSS Ionospheric Model

The IE contains fields needed to model the propagation delays of the GANSS signals through the ionosphere.

Table 170

IE/Group name	Presence	Range	IE Type and Reference	Semantics description
a_{i0}	M		BIT STRING(12)	This parameter is used as defined in [22]
a_{i1}	M		BIT STRING(12)	This parameter is used as defined in [22]
a_{i2}	M		BIT STRING(12)	This parameter is used as defined in [22]
GANSS Ionosphere Regional Storm Flags		0..1		
>Storm Flag 1	M		BOOLEAN	This parameter is used as defined in [22]
>Storm Flag 2	M		BOOLEAN	This parameter is used as defined in [22]
>Storm Flag 3	M		BOOLEAN	This parameter is used as defined in [22]
>Storm Flag 4	M		BOOLEAN	This parameter is used as defined in [22]
>Storm Flag 5	M		BOOLEAN	This parameter is used as defined in [22]

9.2.2.116A GANSS Additional Ionospheric Model

The IE contains fields needed to model the propagation delays of the GANSS signals through the ionosphere.

Table 170A

IE/Group name	Presence	Range	IE Type and Reference	Semantics description

IE/Group name	Presence	Range	IE Type and Reference	Semantics description
Data ID	M		BIT STRING(2)	Coded as defined in [4]
α_0	M		BIT STRING(8)	seconds [27]
α_1	M		BIT STRING(8)	sec/semi-circle [27]
α_2	M		BIT STRING(8)	sec/(semi-circle) ² [27]
α_3	M		BIT STRING(8)	sec/(semi-circle) ³ [27]
β_0	M		BIT STRING(8)	seconds [27]
β_1	M		BIT STRING(8)	sec/semi-circle [27]
β_2	M		BIT STRING(8)	sec/(semi-circle) ² [27]
β_3	M		BIT STRING(8)	sec/(semi-circle) ³ [27]

9.2.2.117 GANSS Measured Results

Table 171

IE/Group name	Presence	Range	IE Type and Reference	Semantics description	Criticality	Assigned Criticality
CHOICE Reference Time	M				–	
>UTRAN Reference Time				This choice may only be present if SAS operates in SAS-centric mode.	–	
>>UE GANSS Timing of Cell Frames	M		INTEGER(0.86399999999750 by step of 250)	GANSS Time of Day (TOD) in ns	–	
>>GANSS Time ID	O		GANSS ID 9.2.2.130	Absence of this IE means Galileo system time. The value '0' ('SBAS') shall not be used for GANS Time ID.	–	
>>GANSS TOD Uncertainty	O		INTEGER(0.127)	Provides the accuracy of the relation between GANSS TOD and UTRAN time. Its coding is defined in [4].	–	
>>UC-ID	M		UTRAN Cell Identifier 9.2.2.37	Identifies the reference cell for the GANSS TOD-SFN relationship.	–	
>>Reference SFN	M		INTEGER(0.4095)	The SFN for which the location is valid. This IE indicates the SFN at which the UE timing of cell frames is captured.	–	

IE/Group name	Presence	Range	IE Type and Reference	Semantics description	Criticality	Assigned Criticality
>GANSS Reference Time Only					–	
>>GANSS TOD msec	M		INTEGER(0..3599999)	GANSS Time of Day (modulo 1 hour) in milliseconds (rounded down to the nearest millisecond unit).	–	
>>GANSS Time ID	O		GANSS ID 9.2.2.130	Absence of this IE means Galileo system time. The value '0' ('SBAS') shall not be used for GANSS Time ID.	–	
>>GANSS TOD Uncertainty	O		INTEGER(0..127)	Provides the accuracy of the GANSS TOD. Its coding is defined in [4].	–	
GANSS Generic Measurement Information		1..<max GANSS >			–	
>GANSS ID	O		9.2.2.130	Absence of this IE means Galileo.	–	
>GANSS Signal Measurement Information	M	1..<max SgnTyp e>			–	
>>GANSS Signal ID	O		9.2.2.131	Absence of this field means the default value for the GANSS identified by "GANSS ID" [4]..	–	
>>GANSS Code Phase Ambiguity	O		INTEGER(0..31)	In milliseconds. Defined in [4].	–	
>>GANSS Code Phase Ambiguity Extension	O		INTEGER(32..127)	In milliseconds. Defined in [4].	GLOBAL	ignore
>>GANSS Measurement Parameters	M	1..<maxGANSS at>			–	
>>>Sat ID	M		INTEGER(0..63)	Defined in [4].	–	
>>>C/N ₀	M		INTEGER(0..63)	the estimate of the carrier-to-noise ratio of the received signal from the particular satellite used in the measurement. It is given in units of dB-Hz (typical levels will be in the range of 20 – 50 dB-Hz).	–	
>>>Multipath Indicator	M		ENUMERATED(NM, low, medium, high)	Coding as in 9.2.2.12	–	
>>>Carrier Quality Indicaton	O		BIT STRING(2)	Coded as defined in [4].	–	
>>>GANSS Code Phase	M		INTEGER(0..63)	Defined in [4].	–	

IE/Group name	Presence	Range	IE Type and Reference	Semantics description	Criticality	Assigned Criticality
			$2^{21}-1$)			
>>>GANSS Integer Code Phase	O		INTEGER(0..63)	Defined in [4].	-	
>>>GANSS Integer Code Phase Extension	O		INTEGER (64..127)	Defined in [4].	GLOBAL	ignore
>>>Code Phase RMS Error	M		INTEGER (0..63)	Coding as Pseudorange RMS Error in section 9.2.2.12	-	
>>>Doppler	M		INTEGER(-32768..32767)	m/s, scale factor 0.04. Doppler measured by the UE for the particular satellite signal	-	
>>>ADR	O		INTEGER(0..33554431)	Meters, scale factor 2^{-10} ADR measurement measured by the UE for the particular satellite signal.	-	

Table 171A

Range bound	Explanation
maxGANSS	Maximum number of GANSS. The value of maxGANSS is 8.
maxSgnType	Maximum number of signals for which data is included in this IE. The value of maxSgnType is 8.
maxGANSSSat	Maximum number of satellites for which data is included in this IE. The value of maxGANSSSat is 64

9.2.2.118 GANSS Navigation Model

This IE contains information required to manage the transfer of precise navigation data to the GANSS-capable UE.

Table 172

IE/Group name	Presence	Range	IE Type and Reference	Semantics description
Non-Broadcast Indication	O		ENUMERATED(true)	If this IE is present, GANSS navigation model is not derived from satellite broadcast. See NOTE 1
Satellite Information		1..<maxGANSSSat>		
>Sat ID	M		INTEGER(0..63)	Defined in [4]
>SV Health	M		BIT STRING(5)	Coded as defined in [4].
>IOD	M		BIT STRING(10)	
>GANSS Clock Model	M		GANSS clock model 9.2.2.115	
>GANSS Orbit Model	M		GANSS orbit model 9.2.2.119	

Table 172A

Range bound	Explanation
maxGANSSat	Maximum number of satellites for which data is included in this IE. The value of maxGANSSat is 64

NOTE 1 : The Non-Broadcast Indication allows to inform that the navigation model is not bit-to-bit the one broadcast by the satellite. If it is set to 1, the UE is informed that techniques such as data wiping off applied to the navigation model may not work for instance.

9.2.2.118A GANSS Additional Navigation Models

This IE contains information required to manage the transfer of precise navigation data to the GANSS-capable UE.

Table 172B

IE/Group name	Presence	Range	IE Type and Reference	Semantics description
Non-Broadcast Indication	O		ENUMERATED(true)	If this IE is present, GANSS navigation model is not derived from satellite broadcast. See NOTE 1 in 9.2.2.118.
Satellite Information		1..<maxGANSSat>		
>Sat ID	M		INTEGER(0..63)	Defined in [4].
>SV Health	M		BIT STRING(6)	Coded as defined in [4].
>IOD	M		BIT STRING(11)	Coded as defined in [4].
>GANSS Additional Clock Models	M		GANSS additional clock models 9.2.2.115A	
>GANSS Additional Orbit Models	M		GANSS additional orbit models 9.2.2.119A	

Table 172C

Range bound	Explanation
maxGANSSat	Maximum number of satellites for which data is included in this IE. The value of maxGANSSat is 64

9.2.2.119 GANSS Orbit Model

This IE contains information for GANSS orbit model parameters.

Table 173

IE/Group name	Presence	Range	IE Type and Reference	Semantics description
CHOICE Orbit Model	M			
>Keplerian Parameters				Model-1
>>t _{oe}	M		BIT STRING(14)	Time-of-Ephemeris in seconds, scale factor 60 [22]
>>ω	M		BIT STRING(32)	Argument of Perigee (semi-circles) [22]

IE/Group name	Presence	Range	IE Type and Reference	Semantics description
>>Δn	M		BIT STRING(16)	Mean Motion Difference From Computed Value (semi-circles/sec) [22]
>>M ₀	M		BIT STRING(32)	Mean Anomaly at Reference Time (semi-circles) [22]
>>OMEGAdot	M		BIT STRING(24)	Longitude of Ascending Node of Orbit Plane at Weekly Epoch (semi-circles/sec) [22]
>>e	M		BIT STRING(32)	Eccentricity, scale factor 2 ⁻³³ [22]
>>Idot	M		BIT STRING(14)	Rate of Inclination Angle (semi-circles/sec) [22]
>>sqrtA	M		BIT STRING(32)	Semi-Major Axis in (meters) ^{1/2} , scale factor 2 ⁻¹⁹ [22]
>>i ₀	M		BIT STRING(32)	Inclination Angle at Reference Time (semi-circles) [22]
>>OMEGA ₀	M		BIT STRING(32)	Longitude of Ascending Node of Orbit Plane at Weekly Epoch (semi-circles) [22]
>>C _{rs}	M		BIT STRING(16)	Amplitude of the Sine Harmonic Correction Term to the Orbit Radius (meters) [22]
>>C _{is}	M		BIT STRING(16)	Amplitude of the Sine Harmonic Correction Term To The Angle Of Inclination (radians) [22]
>>C _{us}	M		BIT STRING(16)	Amplitude of the Sine Harmonic Correction Term To The Argument Of Latitude (radians) [22]
>>C _{rc}	M		BIT STRING(16)	Amplitude of the Cosine Harmonic Correction Term to the Orbit Radius (meters) [22]
>>C _{ic}	M		BIT STRING(16)	Amplitude of the Cosine Harmonic Correction Term To The Angle Of Inclination (radians) [22]
>>C _{uc}	M		BIT STRING(16)	Amplitude of the Cosine Harmonic Correction Term To The Argument Of Latitude (radians) [22]

9.2.2.119A GANSS Additional Orbit Models

This IE contains information for GANSS orbit model parameters.

Table 173A

IE/Group name	Presence	Range	IE Type and Reference	Semantics description
CHOICE Additional Orbit Models				
>>NAV-Keplerian Parameters				Model-2
>>URA Index	M		BIT STRING(4)	SV accuracy (dimensionless) [27]
>>Fit Interval Flag	M		BIT STRING(1)	Fit interval indication (dimensionless) [27]
>>t _{oe}	M		BIT STRING(16)	Time of ephemeris (seconds) [27]
>>ω	M		BIT STRING(32)	Argument of perigee (semi-circles) [27]

IE/Group name	Presence	Range	IE Type and Reference	Semantics description
>>Δn	M		BIT STRING (16)	Mean motion difference from computed value (semi-circles/sec) [27]
>>M ₀	M		BIT STRING (32)	Mean anomaly at reference time (semi-circles) [27]
>>OMEGAdot	M		BIT STRING (24)	Rate of right ascension (semi-circles/sec) [27]
>>e	M		BIT STRING (32)	Eccentricity (dimensionless) [27]
>>Idot	M		BIT STRING (14)	Rate of inclination angle (semi-circles/sec) [27]
>>sqrtA	M		BIT STRING (32)	Square root of semi-major axis (meters ^{1/2}) [27]
>>i ₀	M		BIT STRING (32)	Inclination angle at reference time (semi-circles) [27]
>>OMEGA ₀	M		BIT STRING (32)	Longitude of ascending node of orbit plane at weekly epoch (semi-circles) [27]
>>C _{rs}	M		BIT STRING (16)	Amplitude of sine harmonic correction term to the orbit radius (meters) [27]
>>C _{is}	M		BIT STRING (16)	Amplitude of sine harmonic correction term to the angle of inclination (radians) [27]
>>C _{us}	M		BIT STRING (16)	Amplitude of sine harmonic correction term to the argument of latitude (radians) [27]
>>C _{rc}	M		BIT STRING (16)	Amplitude of cosine harmonic correction term to the orbit radius (meters) [27]
>>C _{ic}	M		BIT STRING (16)	Amplitude of cosine harmonic correction term to the angle of inclination (radians) [27]
>>C _{uc}	M		BIT STRING (16)	Amplitude of cosine harmonic correction term to the argument of latitude (radians) [27]

IE/Group name	Presence	Range	IE Type and Reference	Semantics description
>CNAV/CNAV-2 Keplerian Parameters				Model-3
>> t_{op}	M		BIT STRING (11)	Data predict time of week (seconds) [23,24,25,27]
>>URA _{oe} Index	M		BIT STRING (5)	SV accuracy (dimensionless) [23,24,25,27]
>> ΔA	M		BIT STRING (26)	Semi-major axis difference at reference time (meters) [23,24,25,27]
>> A_{dot}	M		BIT STRING (25)	Chane rate in semi-major axis (meters/sec) [23,24,25,27]
>> Δn_0	M		BIT STRING (17)	Mean motion difference from computed value at reference time (semi-circles/sec) [23,24,25,27]
>> Δn_0_{dot}	M		BIT STRING (23)	Rate of mean motion difference from computed value (semi-circles/sec ²) [23,24,25,27]
>> M_{0-n}	M		Bit String(33)	Mean anomaly at reference time (semi-circles) [23,24,25,27]
>> e_n	M		BIT STRING (33)	Eccentricity (dimensionless) [23,24,25,27]
>> ω_n	M		Bit String(33)	Argument of perigee (semi-circles) [23,24,25,27]
>> Ω_{0-n}	M		BIT STRING (33)	Reference right ascension angle (semi-circles) [23,24,25,27]
>> $\Delta\Omega_{\text{dot}}$	M		BIT STRING (17)	Rate of right ascension difference (semi-circles/sec) [23,24,25,27]
>> i_{0-n}	M		BIT STRING (33)	Inclination angle at reference time (semi-circles) [23,24,25,27]
>> i_{0-n}_{dot}	M		BIT STRING (15)	Rate of inclination angle (semi-circles/sec) [23,24,25,27]
>> C_{is-n}	M		BIT STRING (16)	Amplitude of sine harmonic correction term to the angle of inclination (radians) [23,24,25,27]
>> C_{ic-n}	M		BIT STRING (16)	Amplitude of cosine harmonic correction term to the angle of inclination (radians) [23,24,25,27]
>> C_{rs-n}	M		BIT STRING (24)	Amplitude of sine harmonic correction term to the orbit radius (meters) [23,24,25,27]
>> C_{rc-n}	M		BIT STRING (24)	Amplitude of cosine harmonic correction term to the orbit radius (meters) [23,24,25,27]
>> C_{us-n}	M		BIT STRING (21)	Amplitude of sine harmonic correction term to the argument of latitude (radians) [23,24,25,27]
>> C_{uc-n}	M		BIT STRING (21)	Amplitude of cosine harmonic correction term to the argument of latitude (radians) [23,24,25,27]

IE/Group name	Presence	Range	IE Type and Reference	Semantics description
>GLONASS Earth-Centered, Earth-fixed Parameters				Model-4
>>E _n	M		BIT STRING (5)	Age of data (days) [28]
>>P1	M		BIT STRING (2)	Time interval between two adjacent values of t _b (minutes) [28]
>>P2	M		BIT STRING (1)	Change of t _b flag (dimensionless) [28]
>>M	O		BIT STRING (2)	Type of satellite (dimensionless) [28]
>>x _n (t _b)	M		BIT STRING (27)	x-coordinate of satellite at time t _b (kilometers) [28]
>>dot{x}_n(t_b)	M		BIT STRING (24)	x-coordinate of satellite velocity at time t _b (kilometers/sec) [28]
>>ddot{x}_n(t_b)	M		BIT STRING (5)	x-coordinate of satellite acceleration at time t _b (kilometers/sec ²) [28]
>>y _n (t _b)	M		BIT STRING (27)	y-coordinate of satellite at time t _b (kilometers) [28]
>>dot{y}_n(t_b)	M		BIT STRING (24)	y-coordinate of satellite velocity at time t _b (kilometers/sec) [28]
>>ddot{y}_n(t_b)	M		BIT STRING (5)	y-coordinate of satellite acceleration at time t _b (kilometers/sec ²) [28]
>>z _n (t _b)	M		BIT STRING (27)	z-coordinate of satellite at time t _b (kilometers) [28]
>>dot{z}_n(t_b)	M		BIT STRING (24)	z-coordinate of satellite velocity at time t _b (kilometers/sec) [28]
>>ddot{z}_n(t_b)	M		BIT STRING (5)	z-coordinate of satellite acceleration at time t _b (kilometers/sec ²) [28]
>SBAS Earth-Centered, Earth-fixed Parameters				Model-5
>>t ₀	C-ClockModel		BIT STRING (13)	Time of applicability (seconds) [26]
>>Accuracy	M		BIT STRING (4)	(dimensionless) [26]
>>X _G	M		BIT STRING (30)	(meters) [26]
>>Y _G	M		BIT STRING (30)	(meters) [26]
>>Z _G	M		BIT STRING (25)	(meters) [26]
>>X _G Rate-of-Change	M		BIT STRING (17)	(meters/sec) [26]
>>Y _G Rate-of-Change	M		BIT STRING (17)	(meters/sec) [26]
>>Z _G Rate-of-Change	M		BIT STRING (18)	(meters/sec) [26]
>>X _G Acceleration	M		BIT STRING (10)	(meters/sec ²) [26]
>>Y _G Acceleration	M		BIT STRING (10)	meters/sec ²) [26]
>>Z _G Acceleration	M		BIT STRING (10)	meters/sec ²) [26]

Table 173B

Condition	Explanation
<i>ClockModel</i>	This IE shall be present if "SBAS Satellite Clock Model" (Model-5) in IE <i>GANSS Additional Clock Models</i> is not included in <i>GANSS Additional Navigation Models</i> IE.

9.2.2.120 GANSS Positioning Instructions

This information element contains positioning instructions for GANSS positioning method in SAS-centric mode.

Table 174

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description	Criticality	Assigned Criticality
Horizontal Accuracy Code	O		9.2.2.38		–	
Vertical Accuracy Code	O		9.2.2.39		–	
GANSS Timing of Cell Wanted	M		BIT STRING(8)	For each bit, if set to '1', indicates that for respective GANSS the GANSS Timing of Cell is wanted. Bit 1 is the MSB and bit 8 is the LSB (see clause 9.2.1). bit 1: Galileo bit 2: Modernized GPS bit 3: QZSS bit 4: GLONASS bits 5-8: reserved for future GANSS.	–	
Additional Assistance Data Request	M		BIT STRING(8)	For each bit, if set to '1', indicates that the UE is requested to send an additional assistance data request for the respective GANSS. Bit 1 is the MSB and bit 8 is the LSB (see clause 9.2.1). bit 1: Galileo bit 2: SBAS bit 3: Modernized GPS bit 4: QZSS bit 5: GLONASS bits 6-8: reserved for future GANSS.	–	
Measurement Validity	O		ENUMERATED (CELL_DCH, all states except CELL_DCH, all states, ...)		–	
GANSS Carrier-Phase Measurement Requested	O		BIT STRING(8)	For each bit, if set to '1', indicates that the UE is requested to report carrier phase measurements for the respective GANSS. Bit 1 is the MSB and bit 8 is the LSB (see clause 9.2.1). bit 1: Galileo bit 2: SBAS bit 3: Modernized GPS bit 4: QZSS bit 5: GLONASS bits 6-8: reserved for future GANSS.	YES	ignore
GANSS Multi-frequency Measurement Requested	O		BIT STRING(8)	For each bit, if set to '1', indicates that the UE is requested to report measurements	YES	ignore

				for multiple GANSS signals for the respective GANSS. Bit 1 is the MSB and bit 8 is the LSB (see clause 9.2.1). bit 1: Galileo bit 2: SBAS bit 3: Modernized GPS bit 4: QZSS bit 5: GLONASS bits 6-8: reserved for future GANSS.		
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9.2.2.121 GANSS-UTRAN Time Relationship Uncertainty

This IE contains the uncertainty of the GANSS and UTRAN time relationship.

Table 175

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
GANSS-UTRAN Time Relationship Uncertainty	M		ENUMERATED (50ns, 500ns, 1us, 10us, 1ms, 10ms, 100ms, unreliable,...)	RNC estimate of uncertainty in GANSS-UTRAN time relationship
GANSS ID	O		9.2.2.130	Absence of this IE means Galileo.

9.2.2.122 GANSS Real Time Integrity

This IE contains parameters that describe the real-time status of the GANSS constellation.

Table 176

IE/Group name	Presence	Range	IE Type and Reference	Semantics description
Satellite Information		1..<maxGANSSat>		
>Bad GANSS Sat ID	M		INTEGER(0..63)	Defined in [4]
>Bad GANSS Signal ID	O		BIT STRING(8)	Coded as defined in [4].

Table 176A

Range bound	Explanation
maxGANSSat	Maximum number of satellites for which data is included in this IE. The value of maxGANSSat is 64

9.2.2.123 GANSS Reference Measurement Information

This IE contains parameters that enable fast acquisition of the GANSS signals in UE-assisted GANSS positioning.

Table 177

IE/Group name	Presence	Range	IE Type and Reference	Semantics description
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IE/Group name	Presence	Range	IE Type and Reference	Semantics description
GANSS Signal ID	O		9.2.2.131	Absence of this field means the default value for the GANSS identified by "GANSS ID" [4].
Satellite Information		1..<maxGANSSat>		
>Sat ID	M		INTEGER (0..63)	Defined in [4].
>Doppler (0 th order term)	M		INTEGER(-2048..2047)	Scaling factor 0.5 m/s Conversion between m/s and Hz shall be made by using the <i>nominal</i> wavelength of the assisted signal.
>Extra Doppler		0..1		
>>Doppler (1 st order term)	M		INTEGER (-42..21)	Scaling factor 1/210 m/s ²
>>Doppler Uncertainty	M		ENUMERATED (40,20,10,5,2.5)	m/s. The Doppler experienced by a stationary UE is in the range "Doppler – Doppler Uncertainty" to "Doppler + Doppler Uncertainty".
>Code Phase	M		INTEGER(0..1023)	ms, scaling factor 2 ⁻¹⁰ <i>Nominal</i> chipping rate of the GNSS signal shall be used in conversion. Increasing binary values of the field signify increasing predicted pseudoranges.
>Integer Code Phase	M		INTEGER(0..127)	ms. Integer code phase (expressed modulo 128 ms) currently being transmitted at the GANSS Reference Time, as seen by a receiver at the Reference Location
>Code Phase Search Window	M		INTEGER(0..31)	Expected code-phase is in the range "Code Phase – Code Phase Search Window" to "Code Phase + Code Phase Search Window". Coded as defined in [4].
>Azimuth and Elevation		0..1		
>>Azimuth	M		INTEGER(0..31)	Scaling factor 11.25 Degrees An angle of x degrees means the satellite azimuth a is in the range x ≤ a < x+11.25 degrees.
>>Elevation	M		INTEGER(0..7)	Scaling factor 11.25 Degrees An angle of y degrees means the satellite elevation e is in the range y ≤ e < y+11.25 degrees except for y=78.75 where the range is extended to include 90 degrees.

Table 177A

Range bound	Explanation
maxGANSSat	Maximum number of satellites for which data is included in this IE. The value of maxGANSSat is 64

9.2.2.124 GANSS Reference Time

Table 178

IE/Group name	Presence	Range	IE Type and Reference	Semantics description
GANSS Day	O		INTEGER(0..8191)	The number of days from the beginning of GNSS system time (mod 8192)
GANSS TOD	M		INTEGER(0..86399)	GANSS Time of Day in seconds
GANSS TOD Uncertainty	O		INTEGER(0..127)	Provides the accuracy of the relation between GANSS TOD and UTRAN time if UTRAN GANSS timing of cell frames is provided. Its coding is defined in [4]. This IE may only be present if SAS operates in SAS-centric mode.
GANSS Time ID	O		GANSS ID 9.2.2.130	Absence of this IE means Galileo system time. The value '0' ('SBAS') shall not be used for GANSS Time ID.
UTRAN GANSS Reference Time		0..1		This IE may only be present if SAS operates in SAS-centric mode.
>UTRAN GANSS Timing of Cell Frames	M		INTEGER(0..999999750 by step of 250)	UTRAN GANSS timing of cell frames in steps of 250 ns. Indicates sub-second part of GANSS TOD IE. See [4]
>UC-ID	O		UTRAN Cell Identifier 9.2.2.37	Identifies the reference cell for the GANSS TOD-SFN relationship.
>SFN	M		Integer(0..4095)	The SFN which the UTRAN GANSS timing of cell frames time stamps.
UTRAN-GANSS Drift Rate	O		ENUMERATED (0, 1, 2, 5, 10, 15, 25, 50, -1, -2, -5, -10, -15, -25, -50,...)	in 1/256 chips per sec.

9.2.2.125 GANSS Time Model

The *GANSS Time Model* IE contains a set of parameters needed to relate GANSS time to selected time reference indicated by GNSS_TO_ID.

Table 179

IE/Group name	Presence	Range	IE Type and Reference	Semantics description
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IE/Group name	Presence	Range	IE Type and Reference	Semantics description
GANSS Time Model Reference Time	M		INTEGER(0..37799)	GANSS reference time (modulo 1 week) in seconds. Scale Factor 2^4
T_{A0}	M		INTEGER(-2147483648..2147483647)	Seconds, scale factor 2^{-35}
T_{A1}	O		INTEGER(-8388608..8388607)	sec/sec, scale factor 2^{-51}
T_{A2}	O		INTEGER(-64..63)	sec/sec ² , scale factor 2^{-68}
GNSS_TO_ID	M		ENUMERATED(GPS,..., Galileo, QZSS, GLONASS)	
Week Number	O		INTEGER(0..8191)	Reference week of GANSS Time Model

9.2.2.125A GANSS Additional Time Models

The *GANSS Additional Time Models* IE contains a set of parameters needed to relate GANSS time to selected time references.

Table 179A

IE/Group name	Presence	Range	IE Type and Reference	Semantics description
GNSS-GNSS Time Model		1..<maxGANSS-1>		
>GANSS Time Model			9.2.2.125	

Table 179B

Range Bound	Explanation
maxGANSS-1	Maximum number of GANSS systems for which data is included in this IE. The value of maxGANSS-1 is 7.

9.2.2.126 GANSS UTC Model

The *GANSS UTC Model* IE contains a set of parameters needed to relate GANSS time to Universal Time Coordinate (UTC).

Table 180

IE/Group name	Presence	Range	IE Type and Reference	Semantics description

IE/Group name	Presence	Range	IE Type and Reference	Semantics description
A ₁	M		BIT STRING(24)	sec/sec [22]
A ₀	M		BIT STRING(32)	seconds [22]
t _{ot}	M		BIT STRING(8)	seconds [22]
WN _t	M		BIT STRING(8)	weeks [22]
Δt _{LS}	M		BIT STRING(8)	seconds [22]
WN _{LSF}	M		BIT STRING(8)	weeks [22]
DN	M		BIT STRING(8)	days [22]
Δt _{LSF}	M		BIT STRING(8)	seconds [22]

9.2.2.126A GANSS Additional UTC Models

The *GANSS Additional UTC Models* IE contains several sets of parameters needed to relate GANSS time to Universal Time Coordinate (UTC), as defined in [23,24,25,26,27,28].

Table 180A

IE/Group name	Presence	Range	IE Type and Reference	Semantics description

IE/Group name	Presence	Range	IE Type and Reference	Semantics description
CHOICE Additional UTC Models				
>Model Set 1				
>A _{0-n}	M		BIT STRING(16)	Bias coefficient of GNSS time scale relative to UTC time scale (seconds) [23,24,25,27]
>A _{1-n}	M		BIT STRING(13)	Drift coefficient of GNSS time scale relative to UTC time scale (sec/sec) [23,24,25,27]
>A _{2-n}	M		BIT STRING(7)	Drift rate correction coefficient of GNSS time scale relative to UTC time scale (sec/sec ²) [23,24,25,27]
>Δt _{LS}	M		BIT STRING(8)	Current or past leap second count (seconds) [23,24,25,27]
>t _{ot}	M		BIT STRING(16)	Time data reference time of week (seconds) [23,24,25,27]
>WN _{ot}	M		BIT STRING(13)	Time data reference week number (weeks) [23,24,25,27]
>WN _{LSF}	M		BIT STRING(8)	Leap second reference week number (weeks) [23,24,25,27]
>DN	M		BIT STRING(4)	Leap second reference day number (days) [23,24,25,27]
>Δt _{LSF}	M		BIT STRING(8)	Current or future leap second count (seconds) [23,24,25,27]
>Model Set 2				
>N ^A	M		BIT STRING(11)	Callendar day number within four-year period beginning since the leap year (days) [28]
>τ _c	M		BIT STRING(32)	GLONASS time scale correction to UTC(SU) (seconds) [28]
>Delta UT1	O			
>>B1	M		BIT STRING(11)	Coefficient to determine ΔUT1 (seconds) [28]
>>B2	M		BIT STRING(10)	Coefficient to determine ΔUT1 (seconds/msd) [28]
>KP	O		BIT STRING(2)	Notification of expected leap second correction (dimensionless) [28]
>Model Set 3				
>A _{1WN}	M		BIT STRING(24)	sec/sec ([26], Message Type 12)
>A _{0WN}	M		BIT STRING(32)	seconds ([26], Message Type 12)
>t _{ot}	M		BIT STRING(8)	seconds ([26], Message Type 12)
>WN _t	M		BIT STRING(8)	weeks ([26], Message Type 12)
>Δt _{LS}	M		BIT STRING(8)	seconds ([26], Message Type 12)
>WN _{LSF}	M		BIT STRING(8)	weeks ([26], Message Type 12)
>DN	M		BIT STRING(8)	days ([26], Message Type 12)
>Δt _{LSF}	M		BIT STRING(8)	seconds ([26], Message Type 12)

IE/Group name	Presence	Range	IE Type and Reference	Semantics description
>UTC Standard ID	M		BIT STRING (3)	dimensionless Coded as defined in [4]

9.2.2.127 GANSS Time Indicator

Table 181

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
GANSS Time Indicator			ENUMERATE D (requested, not requested)	

9.2.2.127A GANSS Data Bit Assistance

Table 181A

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
GANSS TOD	M		INTEGER(0..59,...)	Reference time (modulo 1 minute) of the first bit of the data in <i>Data Bits</i> IE, in seconds.
Data Bit Assistance List		1..<maxGANSSat>		
>Sat ID	M		INTEGER(0..63)	Defined in [4].
>Data Bit Assistance Sgn List		1..<maxSgnType>		
>>GANSS Signal ID	M		9.2.2.131	
>>Data Bits	M		BIT STRING(1..1024)	Raw data bits as transmitted from a specific satellite at the time indicated by GANSS_TOD. See [4].

Table 181B

Range bound	Explanation
maxSgnType	Maximum number of signals for which data is included in this IE. The value of maxSgnType is 8.
maxGANSSat	Maximum number of GANSS satellites for which data is included in the IE. The value of maxGANSSat is 64.

9.2.2.128 Additional GPS Assistance Data Required

This IE lists the GPS assistance data types required by the UE.

Table 182

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
Almanac	M		BOOLEAN	TRUE means requested
UTC Model	M		BOOLEAN	TRUE means requested
Ionospheric Model	M		BOOLEAN	TRUE means requested
Navigation Model	M		BOOLEAN	TRUE means requested
DGPS Corrections	M		BOOLEAN	TRUE means requested
Reference Location	M		BOOLEAN	TRUE means requested
Reference Time	M		BOOLEAN	TRUE means requested
Acquisition Assistance	M		BOOLEAN	TRUE means requested
Real-Time Integrity	M		BOOLEAN	TRUE means requested
Nav. Model Additional Data		0..1		
>GPS Week	M		INTEGER (0..1023)	GPS week number
>GPS_Toe	M		INTEGER (0..167)	GPS time of ephemeris in hours of the latest ephemeris set
>T-Toe limit	M		Integer (0..10)	ephemeris age tolerance in hours
>Satellites related data		0..<maxSat>		
>>SatID	M		INTEGER (0..63)	Identifies the satellite and is equal to (SV ID No - 1) where SV ID No is defined in [10].
>>IODE	M		INTEGER (0..255)	Issue of Data Ephemeris for SatID

Table 183

Range Bound	Explanation
maxSat	Maximum number of satellites for which data is included in this IE. The value of maxSat is 16.

9.2.2.129 Additional GANSS Assistance Data Required

This IE lists the GANSS assistance data types required by the UE.

Table 184

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description	Criticality	Assigned Criticality
GANSS Reference Time	M		BOOLEAN	TRUE means requested	–	
GANSS Reference Location	M		BOOLEAN	TRUE means requested	–	
GANSS Ionospheric model	M		BOOLEAN	TRUE means requested	–	
GANSS Additional Ionospheric Model	O		BIT STRING(2)	Coded as defined in [4].	YES	ignore
GANSS Earth Orientation Parameters	O		ENUMERATED(true)		YES	ignore
GANSS Requested Generic Assistance Data		1..<maxGANSs>			–	
>GANSS ID	O		9.2.2.130	Absence of this IE means Galileo	–	
>GANSS Real-Time Integrity	O		BOOLEAN	TRUE means requested	–	
>GANSS Differential Corrections		0..1			–	
>>DGANSS Signal	M		BIT STRING (8)	Coded as defined in [4].	–	
>GANSS Almanac	O		BOOLEAN	TRUE means requested	–	
>GANSS Navigation Model	O		BOOLEAN	TRUE means requested	–	
>GANSS Time Model GNSS-GNSS	O		BIT STRING (9)	Defines the time model. Bit 1 is the MSB and bit 9 is the LSB (see clause 9.2.1). Bit 1 is set for GPS, Bit 2 is set for Galileo. Bit 3 is set for QZSS Bit 4 is set for GLONASS Other bits are reserved.	–	
>GANSS Reference Measurement Information	O		BOOLEAN	TRUE means requested	–	
>GANSS Data Bits		0..1			–	
>>GANSS TOD	M		INTEGER (0..86399)	The GANSS TOD for which the data bits are requested.	–	
>>Data Bit Assistance		1			–	
>>>GANSS Signal ID	M		BIT STRING(8)	Coded as defined in [4]	–	
>>>GANSS Data Bit Interval	M		INTEGER(0..15)	This field represents the time length for which the Data Bit Assistance is requested. The	–	

				Data Bit Assistance shall be relative to the time interval (GANSS TOD, GANSS TOD + Data Bit Interval). The Data Bit Interval r , expressed in seconds, is mapped to a binary number K with the following formula: $r = 0.1 * 2^K$ Value $K=15$ means that the time interval is not specified.		
>>>Satellite Information		0..<maxGANSSSat>			—	
>>>>Satellite ID	M		INTEGER(0..63)	Defined in [4].	—	
>GANSS UTC model	O		BOOLEAN	TRUE means requested	—	
>GANSS Navigation Model Additional data		0..1			—	
>>GANSS Week	M		INTEGER(0..4095)		—	
>>GANSS_Toe	M		INTEGER(0..167)	GANSS time of ephemeris in hours of the latest ephemeris set contained by the UE.	—	
>>T-Toe limit	M		INTEGER(0..10)	ephemeris age tolerance of the UE to UTRAN in hours. Five spare values needed.	—	
>>Satellites list related data	M	1..<maxGANSSat>			—	
>>>Sat ID	M		INTEGER(0..63)	Defined in [4].	—	
>>>IOD	M		BIT STRING(10)	Issue of Data for Sat ID	—	
>GANSS Additional Navigation Model	O		ENUMERATED(TED(true))		GLOBAL	ignore
>GANSS Additional UTC Models	O		ENUMERATED(TED(true))		GLOBAL	ignore
>GANSS Auxiliary Information	O		ENUMERATED(TED(true))		GLOBAL	ignore

Table 185

Range Bound	Explanation
maxGANSS	Maximum number of GANSS for which data is included in this IE. The value of maxGANSS is 8.
maxGANSSSat	Maximum number of GANSS satellites for which data is included in this IE. The value of maxGANSSSat is 64.

9.2.2.130 GANSS ID

This IE defines a particular GANSS.

Table 186

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
GANSS ID	M		INTEGER(0..7)	Defines the GANSS and is coded as defined in [4].

9.2.2.131 GANSS Signal ID

This IE defines a specific signal within a particular GANSS.

Table 187

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
GANSS Signal ID	M		INTEGER(0..3,...,4..7)	Defines the GANSS signal and is coded as defined in [4].

9.2.2.132 GPS Reference Time Uncertainty

Table 188

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
GPS Reference Time Uncertainty	M		Integer (0..127)	<p>This element provides the accuracy of the provided GPS time, or alternatively the accuracy of the provided relation between GPS and UTRAN time. If "GPS TOW" is the provided GPS time, or alternatively the GPS time corresponding to the UTRAN time provided, then the true GPS time lies in the interval ["GPS TOW" - "GPS Reference Time Uncertainty", "GPS TOW" + "GPS Reference Time Uncertainty"].</p> <p>The uncertainty r, expressed in microseconds, is mapped to a number K with the following formula:</p> $r = C * (((1+x)K)-1)$ <p>with $C = 0.0022$ and $x = 0.18$.</p> <p>To encode any higher value of the uncertainty than that corresponding to $K=127$ in the formula above, or to indicate an undefined value of the "GPS TOW", the same value, $K=127$, shall be used.</p>

9.2.2.133 GANSS Earth Orientation Parameters

Table 189

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
t_{EOP}	M		BIT STRING(16)	EOP data reference time (seconds) [23]
PM_X	M		BIT STRING (21)	X-axis polar motion value at reference time (arc-seconds) [23]
PM_X_dot	M		BIT STRING (15)	X-axis polar motion drift at reference time (arc-seconds/day) [23]
PM_Y	M		BIT STRING (21)	Y-axis polar motion value at reference time (arc-seconds) [23]
PM_Y_dot	M		BIT STRING (15)	Y-axis polar motion drift at reference time (arc-seconds/day) [23]
Δ UT1	M		BIT STRING (31)	UT1-UTC difference at reference time (seconds) [23]
Δ UT1_dot	M		BIT STRING (19)	Rate of UT1-UTC difference at reference time (seconds/day) [23]

9.2.2.134 SBAS ID

This IE defines a specific SBAS.

Table 190

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
SBAS ID	M		ENUMERATED(WAAS, EGNOS, MSAS, GAGAN, ...)	

9.2.2.135 GANSS Auxiliary Information

Table 191

IE/Group name	Presence	Range	IE Type and Reference	Semantics description
CHOICE_GANSS-ID				
>GANSS-ID-1				This choice may only be present if GANSS ID indicated "Modernized GPS"
>>Aux Info List		1 .. <maxGANSSat>		
>>>Sat ID	M		INTEGER(0..63)	Defined in [4].
>>>Signals Available	M		BIT STRING(8)	Coded as defined in [4].
>GANSS-ID-3				This choice may be present if GANSS ID indicated "GLONASS"
>>Aux Info List		1 .. <maxGANSSat>		
>>>Sat ID	M		INTEGER(0..63)	Defined in [4].
>>>Signals Available	M		BIT STRING(8)	Coded as defined in [4].
>>>Channel Number	M		INTEGER (-7..13)	This field indicates the GLONASS carrier frequency number of the satellite identified by <i>Sat ID</i> , as defined in [28].

Table 192

Range Bound	Explanation
maxGANSSat	Maximum number of GANSS satellites for which data is included in this IE. The value of maxGANSSat is 64.

9.2.2.136 UTRAN-GANSS Reference Time Result

Table 193

IE/Group Name	Presence	Range	IE Type and Reference	Semantics Description
UE GANSS timing of cell frames	M		INTEGER(0..3455999999,...)	GANSS Time of Day in steps of 250 ns [4].
GANSS time ID	O		GANSS ID 9.2.2.130	Absence of this IE means Galileo system time. The value '0' ('SBAS') shall not be used for GANSS Time ID.
GANSS TOD Uncertainty	O		INTEGER(0..127)	Coded as defined in [4].
UC-ID	M		UTRAN Cell Identifier 9.2.2.37	Identifies the reference cell for the GANSS TOD-SFN relationship.
SFN	M		INTEGER(0..4095)	This IE indicates the SFN at which the UE timing of cell frame is captured.

9.3 Message and Information Element Abstract Syntax (with ASN.1)

9.3.0 General

PCAP ASN.1 definition conforms with [7], [8], and [9].

The ASN.1 definition specifies the structure and content of PCAP messages. PCAP messages can contain any IEs specified in the object set definitions for that message without the order or number of occurrence being restricted by ASN.1. However, for this version of the standard, a sending entity shall construct a PCAP message according to the PDU definitions module and with the following additional rules (Note that in the following IE means an IE in the object set with an explicit id. If one IE needed to appear more than once in one object set, then the different occurrences have different IE ids):

- IEs shall be ordered (in an IE container) in the order they appear in object set definitions.
- Object set definitions specify how many times IEs may appear. An IE shall appear exactly once if the presence field in an object has value "mandatory". An IE may appear at most once if the presence field in an object has value "optional" or "conditional". If in a tabular format there is multiplicity specified for an IE (i.e. an IE list) then in the corresponding ASN.1 definition the list definition is separated into two parts. The first part defines an IE container list where the list elements reside. The second part defines list elements. The IE container list appears as an IE of its own. For this version of the standard an IE container list may contain only one kind of list elements.

If a PCAP message that is not constructed as defined above is received, this shall be considered as Abstract Syntax Error, and the message shall be handled as defined for Abstract Syntax Error in clause 10.3.6.

Clause 9.3 presents the Abstract Syntax of PCAP protocol with ASN.1. In case there is contradiction between the ASN.1 definition in this clause and the tabular format in clauses 9.1 and 9.2, the ASN.1 shall take precedence, except for the definition of conditions for the presence of conditional elements, where the tabular format shall take precedence.

9.3.1 Usage of private message mechanism for non-standard use

The private message mechanism for non-standard use may be used:

- for special operator- (and/or vendor) specific features considered not to be part of the basic functionality, i.e. the functionality required for a complete and high-quality specification in order to guarantee multivendor interoperability;
- by vendors for research purposes, e.g. to implement and evaluate new algorithms/features before such features are proposed for standardisation.

The private message mechanism shall not be used for basic functionality. Such functionality shall be standardised.

9.3.2 Elementary Procedure Definitions

```
-- ****
-- Elementary Procedure definitions
```

```

-- ****
PCAP-PDU-Descriptions {
  itu-t (0) identified-organization (4) etsi (0) mobileDomain (0)
  umts-Access (20) modules (3) pcap(4) version1 (1) pcap-PDU-Descriptions (0)
}

DEFINITIONS AUTOMATIC TAGS ::=

BEGIN

-- ****
-- IE parameter types from other modules.
-- ****

IMPORTS
  Criticality,
  ProcedureCode,
  TransactionID
FROM PCAP-CommonDataTypes

  PositionCalculationRequest,
  PositionCalculationResponse,
  PositionCalculationFailure,
  InformationExchangeInitiationRequest,
  InformationExchangeInitiationResponse,
  InformationExchangeInitiationFailure,
  InformationReport,
  InformationExchangeTerminationRequest,
  InformationExchangeFailureIndication,
  ErrorIndication,
  PrivateMessage,
  PositionInitiationRequest,
  PositionInitiationResponse,
  PositionInitiationFailure,
  PositionActivationRequest,
  PositionActivationResponse,
  PositionActivationFailure,
  PositionParameterModification,
  Abort,
  PositionPeriodicReport,
  PositionPeriodicResult,
  PositionPeriodicTermination

FROM PCAP-PDU-Contents

  id-PositionCalculation,
  id-InformationExchangeInitiation,
  id-InformationReporting,
  id-InformationExchangeTermination,
  id-InformationExchangeFailure,
  id-ErrorIndication,

```

```

id-privateMessage,
id-PositionInitiation,
id-PositionActivation,
id-PositionParameterModification,
id-Abort,
id-PositionPeriodicReport,
id-PositionPeriodicResult,
id-PositionPeriodicTermination

FROM PCAP-Constants;

-- ****
-- 
-- Interface Elementary Procedure Class
-- 
-- ****

PCAP-ELEMENTARY-PROCEDURE ::= CLASS {
  &InitiatingMessage           ,
  &SuccessfulOutcome          OPTIONAL,
  &UnsuccessfulOutcome        OPTIONAL,
  &Outcome                     OPTIONAL,
  &procedureCode               ProcedureCode UNIQUE,
  &criticality                Criticality    DEFAULT ignore
}

WITH SYNTAX {
  INITIATING MESSAGE      &InitiatingMessage
  [SUCCESSFUL OUTCOME]    &SuccessfulOutcome
  [UNSUCCESSFUL OUTCOME]  &UnsuccessfulOutcome
  [OUTCOME]                &Outcome
  PROCEDURE CODE           &procedureCode
  [CRITICALITY]            &criticality
}

-- ****
-- 
-- Interface PDU definitions
-- 
-- ****

PCAP-PDU ::= CHOICE {
  initiatingMessage        InitiatingMessage,
  successfulOutcome         SuccessfulOutcome,
  unsuccessfulOutcome       UnsuccessfulOutcome,
  outcome                   Outcome,
  ...
}

InitiatingMessage ::= SEQUENCE {
  procedureCode   PCAP-ELEMENTARY-PROCEDURE.&procedureCode
  criticality     PCAP-ELEMENTARY-PROCEDURE.&criticality
  transactionID   TransactionID,
  ((PCAP-ELEMENTARY-PROCEDURES)),
  ((PCAP-ELEMENTARY-PROCEDURES){@procedureCode}),
}

```

```

value          PCAP-ELEMENTARY-PROCEDURE.&InitiatingMessage    ({ PCAP-ELEMENTARY-PROCEDURES }{@procedureCode})
}

SuccessfulOutcome ::= SEQUENCE {
  procedureCode  PCAP-ELEMENTARY-PROCEDURE.&procedureCode    ({ PCAP-ELEMENTARY-PROCEDURES }),
  criticality    PCAP-ELEMENTARY-PROCEDURE.&criticality      ({ PCAP-ELEMENTARY-PROCEDURES }{@procedureCode}),
  transactionID TransactionID,                                ({ PCAP-ELEMENTARY-PROCEDURES }{@procedureCode}),
  value          PCAP-ELEMENTARY-PROCEDURE.&SuccessfulOutcome  ({ PCAP-ELEMENTARY-PROCEDURES }{@procedureCode})
}

UnsuccessfulOutcome ::= SEQUENCE {
  procedureCode  PCAP-ELEMENTARY-PROCEDURE.&procedureCode    ({ PCAP-ELEMENTARY-PROCEDURES }),
  criticality    PCAP-ELEMENTARY-PROCEDURE.&criticality      ({ PCAP-ELEMENTARY-PROCEDURES }{@procedureCode}),
  transactionID TransactionID,                                ({ PCAP-ELEMENTARY-PROCEDURES }{@procedureCode}),
  value          PCAP-ELEMENTARY-PROCEDURE.&UnsuccessfulOutcome ({ PCAP-ELEMENTARY-PROCEDURES }{@procedureCode})
}

Outcome ::= SEQUENCE {
  procedureCode  PCAP-ELEMENTARY-PROCEDURE.&procedureCode    ({ PCAP-ELEMENTARY-PROCEDURES }),
  criticality    PCAP-ELEMENTARY-PROCEDURE.&criticality      ({ PCAP-ELEMENTARY-PROCEDURES }{@procedureCode}),
  transactionID TransactionID,                                ({ PCAP-ELEMENTARY-PROCEDURES }{@procedureCode}),
  value          PCAP-ELEMENTARY-PROCEDURE.&Outcome            ({ PCAP-ELEMENTARY-PROCEDURES }{@procedureCode})
}

-- ****
-- 
-- Interface Elementary Procedure List
-- 
-- ****

PCAP-ELEMENTARY-PROCEDURES PCAP-ELEMENTARY-PROCEDURE ::= {
  PCAP-ELEMENTARY-PROCEDURES-CLASS-1  |
  PCAP-ELEMENTARY-PROCEDURES-CLASS-2  ,
  ...
}

PCAP-ELEMENTARY-PROCEDURES-CLASS-1 PCAP-ELEMENTARY-PROCEDURE ::= {
  positionCalculation           |
  informationExchangeInitiation,
  ...,
  positionInitiation            |
  positionActivation
}

PCAP-ELEMENTARY-PROCEDURES-CLASS-2 PCAP-ELEMENTARY-PROCEDURE ::= {
  informationReporting          |
  informationExchangeTermination |
  informationExchangeFailure    |
  errorIndication               |
  privateMessage,
  ...,
  positionParameterModification |
}

```

```

abort
positionPeriodicReport
positionPeriodicResult
positionPeriodicTermination
}

-- ****
-- Interface Elementary Procedures
-- ****

positionCalculation PCAP-ELEMENTARY-PROCEDURE ::= {
  INITIATING MESSAGE      PositionCalculationRequest
  SUCCESSFUL OUTCOME      PositionCalculationResponse
  UNSUCCESSFUL OUTCOME    PositionCalculationFailure
  PROCEDURE CODE           id-PositionCalculation
  CRITICALITY              reject
}

informationExchangeInitiation PCAP-ELEMENTARY-PROCEDURE ::= {
  INITIATING MESSAGE      InformationExchangeInitiationRequest
  SUCCESSFUL OUTCOME      InformationExchangeInitiationResponse
  UNSUCCESSFUL OUTCOME    InformationExchangeInitiationFailure
  PROCEDURE CODE           id-InformationExchangeInitiation
  CRITICALITY              reject
}

positionInitiation PCAP-ELEMENTARY-PROCEDURE ::= {
  INITIATING MESSAGE      PositionInitiationRequest
  SUCCESSFUL OUTCOME      PositionInitiationResponse
  UNSUCCESSFUL OUTCOME    PositionInitiationFailure
  PROCEDURE CODE           id-PositionInitiation
  CRITICALITY              reject
}

positionActivation PCAP-ELEMENTARY-PROCEDURE ::= {
  INITIATING MESSAGE      PositionActivationRequest
  SUCCESSFUL OUTCOME      PositionActivationResponse
  UNSUCCESSFUL OUTCOME    PositionActivationFailure
  PROCEDURE CODE           id-PositionActivation
  CRITICALITY              reject
}

informationReporting PCAP-ELEMENTARY-PROCEDURE ::= {
  INITIATING MESSAGE      InformationReport
  PROCEDURE CODE           id-InformationReporting
  CRITICALITY              ignore
}

informationExchangeTermination PCAP-ELEMENTARY-PROCEDURE ::= {
}

```

```

INITIATING MESSAGE      InformationExchangeTerminationRequest
PROCEDURE CODE          id-InformationExchangeTermination
CRITICALITY             ignore
}

informationExchangeFailure PCAP-ELEMENTARY-PROCEDURE ::= {
  INITIATING MESSAGE      InformationExchangeFailureIndication
  PROCEDURE CODE          id-InformationExchangeFailure
  CRITICALITY             ignore
}

errorIndication PCAP-ELEMENTARY-PROCEDURE ::= {
  INITIATING MESSAGE      ErrorIndication
  PROCEDURE CODE          id-ErrorIndication
  CRITICALITY             ignore
}

privateMessage PCAP-ELEMENTARY-PROCEDURE ::= {
  INITIATING MESSAGE      PrivateMessage
  PROCEDURE CODE          id-privateMessage
  CRITICALITY             ignore
}

positionParameterModification PCAP-ELEMENTARY-PROCEDURE ::= {
  INITIATING MESSAGE      PositionParameterModification
  PROCEDURE CODE          id-PositionParameterModification
  CRITICALITY             ignore
}

abort PCAP-ELEMENTARY-PROCEDURE ::= {
  INITIATING MESSAGE      Abort
  PROCEDURE CODE          id-Abort
  CRITICALITY             ignore
}

positionPeriodicReport PCAP-ELEMENTARY-PROCEDURE ::= {
  INITIATING MESSAGE      PositionPeriodicReport
  PROCEDURE CODE          id-PositionPeriodicReport
  CRITICALITY             ignore
}

positionPeriodicResult PCAP-ELEMENTARY-PROCEDURE ::= {
  INITIATING MESSAGE      PositionPeriodicResult
  PROCEDURE CODE          id-PositionPeriodicResult
  CRITICALITY             ignore
}

positionPeriodicTermination PCAP-ELEMENTARY-PROCEDURE ::= {
  INITIATING MESSAGE      PositionPeriodicTermination
  PROCEDURE CODE          id-PositionPeriodicTermination
  CRITICALITY             ignore
}

```

```
}
```

```
END
```

9.3.3 PDU Definitions

```
-- ****
-- PDU definitions for PCAP.
--
-- ****

PCAP-PDU-Contents {
  itu-t (0) identified-organization (4) etsi (0) mobileDomain (0)
  umts-Access (20) modules (3) pcap(4) version1 (1) pcap-PDU-Contents (1) }

DEFINITIONS AUTOMATIC TAGS ::=

BEGIN

-- ****
-- IE parameter types from other modules.
--
-- ****

IMPORTS
  Cause,
  CriticalityDiagnostics,
  GPS-UTRAN-TRU,
  InformationExchangeID,
  InformationReportCharacteristics,
  InformationType,
  MeasuredResultsList,
  RequestedDataValue,
  RequestedDataValueInformation,
  UE-PositionEstimate,
  CellId-MeasuredResultsSets,
  OTDOA-MeasurementGroup,
  AccuracyFulfilmentIndicator,
  HorizontalAccuracyCode,
  VerticalAccuracyCode,
  RequestType,
  UE-PositioningCapability,
  UC-ID,
  ResponseTime,
  PositioningPriority,
  ClientType,
  PositioningMethod,
  UTDOAPositioning,
  GPSPositioning,
  OTDOAAssistanceData,
  UTDOA-Group,
```

```

Positioning-ResponseTime,
EnvironmentCharacterisation,
PositionData,
IncludeVelocity,
VelocityEstimate,
UE-PositionEstimateInfo,
OTDOA-MeasuredResultsSets,
PeriodicPosCalcInfo,
PeriodicLocationInfo,
AmountOfReporting,
MeasInstructionsUsed,
RRCstateChange,
PeriodicTerminationCause,
CellIDPositioning,
GANSS-MeasuredResultsList,
GANSSPositioning,
GANSS-UTRAN-TRU,
AdditionalGPSAssistDataRequired,
AdditionalGanssAssistDataRequired

```

FROM PCAP-IEs

```

    TransactionID
FROM PCAP-CommonDataTypes

```

```

ProtocolExtensionContainer{},
ProtocolIE-ContainerList{},
ProtocolIE-Container{},
ProtocolIE-Single-Container{},
PrivateIE-Container{},
PCAP-PRIVATE-IES,
PCAP-PROTOCOL-EXTENSION,
PCAP-PROTOCOL-IES

```

FROM PCAP-Containers

```

id-Cause,
id-CriticalityDiagnostics,
id-GPS-UTRAN-TRU,
id-InformationExchangeID,
id-InformationExchangeObjectType-InfEx-Rprt,
id-InformationExchangeObjectType-InfEx-Rqst,
id-InformationExchangeObjectType-InfEx-Rsp,
id-InformationReportCharacteristics,
id-InformationType,
id-GPS-MeasuredResultsList,
id-RequestedDataValue,
id-RequestedDataValueInformation,
id-TransactionID,
id-UE-PositionEstimate,
id-CellId-MeasuredResultsSets,
id-OTDOA-MeasurementGroup,
id-AccuracyFulfilmentIndicator,
id-HorizontalAccuracyCode,
id-VerticalAccuracyCode,

```

```

id-RequestType,
id-UE-PositioningCapability,
id-UC-id,
id-ResponseTime,
id-PositioningPriority,
id-ClientType,
id-PositioningMethod,
id-UTDOAPositioning,
id-GPSPositioning,
id-OTDOAAssistanceData,
id-UTDOA-Group,
id-Positioning-ResponseTime,
id-EnvironmentCharacterisation,
id-PositionData,
id-IncludeVelocity,
id-VelocityEstimate,
id-UE-PositionEstimateInfo,
id-UC-ID-InfEx-Rqst,
id-OTDOA-MeasuredResultsSets,
id-PeriodicPosCalcInfo,
id-PeriodicLocationInfo,
id-AmountOfReporting,
id-MeasInstructionsUsed,
id-RRCstateChange,
id-PeriodicTerminationCause,
id-CellIDPositioning,
id-GANSS-MeasuredResultsList,
id-GANSSPositioning,
id-GANSS-UTRAN-TRU,
id-AdditionalGPSAssistDataRequired,
id-AdditionalGanssAssistDataRequired

FROM PCAP-Constants;

-- ****
-- POSITION CALCULATION REQUEST
-- ****

PositionCalculationRequest ::= SEQUENCE {
    protocolIEs      ProtocolIE-Container      { {PositionCalculationRequestIEs} },
    protocolExtensions  ProtocolExtensionContainer { {PositionCalculationRequestExtensions} }   OPTIONAL,
    ...
}

PositionCalculationRequestIEs PCAP-PROTOCOL-IES ::= {
    { ID id-UE-PositionEstimate      CRITICALITY reject  TYPE UE-PositionEstimate
    { ID id-GPS-MeasuredResultsList    CRITICALITY reject  TYPE MeasuredResultsList
    ...
}

PositionCalculationRequestExtensions PCAP-PROTOCOL-EXTENSION ::= {
    ...
}

```

```

{ ID id-CellId-MeasuredResultsSets   CRITICALITY reject EXTENSION CellId-MeasuredResultsSets  PRESENCE optional } |
{ ID id-OTDOA-MeasurementGroup      CRITICALITY reject EXTENSION OTDOA-MeasurementGroup  PRESENCE optional } |
{ ID id-HorizontalAccuracyCode     CRITICALITY ignore EXTENSION HorizontalAccuracyCode  PRESENCE optional } |
{ ID id-VerticalAccuracyCode       CRITICALITY ignore EXTENSION VerticalAccuracyCode   PRESENCE optional } |
{ ID id-UTDOA-Group                CRITICALITY reject EXTENSION UTDOA-Group        PRESENCE optional } |
{ ID id-Positioning-ResponseTime   CRITICALITY ignore EXTENSION Positioning-ResponseTime PRESENCE optional } |
{ ID id-IncludeVelocity           CRITICALITY ignore EXTENSION IncludeVelocity      PRESENCE optional } |
{ ID id-PeriodicPosCalcInfo       CRITICALITY ignore EXTENSION PeriodicPosCalcInfo  PRESENCE optional } |
{ ID id-GNSS-MeasuredResultsList  CRITICALITY reject EXTENSION GANSS-MeasuredResultsList PRESENCE optional } |
...
}

-- ****
-- POSITION CALCULATION RESPONSE
--
-- ****

PositionCalculationResponse ::= SEQUENCE {
  protocolIEs      ProtocolIE-Container { {PositionCalculationResponseIEs} },
  protocolExtensions ProtocolExtensionContainer { {PositionCalculationResponseExtensions} } OPTIONAL,
  ...
}

PositionCalculationResponseIEs PCAP-PROTOCOL-IES ::= {
  { ID id-UE-PositionEstimate      CRITICALITY ignore  TYPE UE-PositionEstimate      PRESENCE mandatory } |
  { ID id-CriticalityDiagnostics  CRITICALITY ignore  TYPE CriticalityDiagnostics  PRESENCE optional },
  ...
}

PositionCalculationResponseExtensions PCAP-PROTOCOL-EXTENSION ::= {
  { ID id-AccuracyFulfilmentIndicator CRITICALITY ignore  EXTENSION AccuracyFulfilmentIndicator  PRESENCE optional } |
  { ID id-VelocityEstimate          CRITICALITY ignore  EXTENSION VelocityEstimate        PRESENCE optional },
  ...
}

-- ****
-- POSITION CALCULATION FAILURE
--
-- ****

PositionCalculationFailure ::= SEQUENCE {
  protocolIEs      ProtocolIE-Container { {PositionCalculationFailureIEs} },
  protocolExtensions ProtocolExtensionContainer { {PositionCalculationFailureExtensions} } OPTIONAL,
  ...
}

PositionCalculationFailureIEs PCAP-PROTOCOL-IES ::= {
  { ID id-Cause                  CRITICALITY ignore  TYPE Cause      PRESENCE mandatory } |
  { ID id-CriticalityDiagnostics CRITICALITY ignore  TYPE CriticalityDiagnostics  PRESENCE optional },
  ...
}

```

```

PositionCalculationFailureExtensions PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

-- ****
-- INFORMATION EXCHANGE INITIATION REQUEST
-- ****

InformationExchangeInitiationRequest ::= SEQUENCE {
  protocolIEs          ProtocolIE-Container {{InformationExchangeInitiationRequest-IEs}},
  protocolExtensions   ProtocolExtensionContainer {{InformationExchangeInitiationRequest-Extensions}}      OPTIONAL,
  ...
}

InformationExchangeInitiationRequest-IEs PCAP-PROTOCOL-IES ::= {
  { ID id-InformationExchangeID           CRITICALITY reject TYPE InformationExchangeID           PRESENCE mandatory }|
  { ID id-InformationExchangeObjectType-InfEx-Rqst   CRITICALITY reject TYPE InformationExchangeObjectType-InfEx-Rqst   PRESENCE mandatory }|
  -- This IE represents both the Information Exchange Object Type IE and the choice based on the Information Exchange Object Type
  -- as described in the tabular message format in clause 9.1.
  { ID id-InformationType                 CRITICALITY reject TYPE InformationType                 PRESENCE mandatory }|
  { ID id-InformationReportCharacteristics CRITICALITY reject TYPE InformationReportCharacteristics PRESENCE mandatory }|
  { ID id-GPS-UTRAN-TRU                  CRITICALITY reject TYPE GPS-UTRAN-TRU                  PRESENCE conditional },
  -- This IE shall be present if the information requested in the Information Type IE contains GPS-related data
  ...
}

InformationExchangeInitiationRequest-Extensions PCAP-PROTOCOL-EXTENSION ::= {
  { ID id-GANSS-UTRAN-TRU                CRITICALITY reject EXTENSION GANSS-UTRAN-TRU                PRESENCE conditional },
  -- This IE shall be present if the information requested in the Information Type IE contains GANSS-related data
  ...
}

InformationExchangeObjectType-InfEx-Rqst ::= CHOICE {
  referencePosition                  RefPosition-InfEx-Rqst,
  ...
  extension-InformationExchangeObjectType-InfEx-Rqst   Extension-InformationExchangeObjectType-InfEx-Rqst
}

RefPosition-InfEx-Rqst ::= SEQUENCE {
  referencePositionEstimate          UE-PositionEstimate,
  iE-Extensions                     ProtocolExtensionContainer { { RefPositionItem-InfEx-Rqst-ExtIEs } }      OPTIONAL,
  ...
}

RefPositionItem-InfEx-Rqst-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

Extension-InformationExchangeObjectType-InfEx-Rqst ::= ProtocolIE-Single-Container {{ Extension-InformationExchangeObjectType-InfEx-RqstIE }}
```

```
Extension-InformationExchangeObjectType-InfEx-RqstIE PCAP-PROTOCOL-IES ::= {
```

```

{ ID id-UC-ID-InfEx-Rqst          CRITICALITY reject  TYPE UC-ID-InfEx-Rqst          PRESENCE mandatory } |
{ ID id-CellId-MeasuredResultsSets CRITICALITY ignore  TYPE CellId-MeasuredResultsSets PRESENCE optional }

}

UC-ID-InfEx-Rqst ::= SEQUENCE {
  referenceUC-ID
  UC-ID,
  iE-Extensions
  ProtocolExtensionContainer { { UCIDItem-InfEx-Rqst-ExtIES} } OPTIONAL,
  ...
}

UCIDItem-InfEx-Rqst-ExtIES PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

-- ****
-- 
-- INFORMATION EXCHANGE INITIATION RESPONSE
-- 
-- ****

InformationExchangeInitiationResponse ::= SEQUENCE {
  protocolIES
  ProtocolIE-Container { { InformationExchangeInitiationResponse-IEs} },
  protocolExtensions
  ProtocolExtensionContainer { { InformationExchangeInitiationResponse-Extensions} } OPTIONAL,
  ...
}

InformationExchangeInitiationResponse-IEs PCAP-PROTOCOL-IES ::= {
  { ID id-InformationExchangeID
    CRITICALITY ignore  TYPE InformationExchangeID
  } |
  { ID id-InformationExchangeObjectType-InfEx-Rsp
    CRITICALITY ignore  TYPE InformationExchangeObjectType-InfEx-Rsp
  } |
  { ID id-CriticalityDiagnostics
    CRITICALITY ignore  TYPE CriticalityDiagnostics
  } |
  ...
}

InformationExchangeInitiationResponse-Extensions PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

InformationExchangeObjectType-InfEx-Rsp ::= CHOICE {
  referencePosition
  RefPosition-InfEx-Rsp,
  ...
}

RefPosition-InfEx-Rsp ::= SEQUENCE {
  requestedDataValue
  RequestedDataValue,
  iE-Extensions
  ProtocolExtensionContainer { { RefPositionItem-InfEx-Rsp-ExtIES} } OPTIONAL,
  ...
}

RefPositionItem-InfEx-Rsp-ExtIES PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

```

```

-- ****
-- INFORMATION EXCHANGE INITIATION FAILURE
-- ****

InformationExchangeInitiationFailure ::= SEQUENCE {
  protocolIEs          ProtocolIE-Container {{InformationExchangeInitiationFailure-IEs}},
  protocolExtensions   ProtocolExtensionContainer {{InformationExchangeInitiationFailure-Extensions}} OPTIONAL,
  ...
}

InformationExchangeInitiationFailure-IEs PCAP-PROTOCOL-IES ::= {
  { ID id-InformationExchangeID      CRITICALITY ignore  TYPE InformationExchangeID      PRESENCE mandatory }|
  { ID id-Cause                     CRITICALITY ignore  TYPE Cause                      PRESENCE mandatory }|
  { ID id-CriticalityDiagnostics   CRITICALITY ignore  TYPE CriticalityDiagnostics  PRESENCE optional },
  ...
}

InformationExchangeInitiationFailure-Extensions PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

-- ****
-- POSITION INITIATION REQUEST
-- ****

PositionInitiationRequest ::= SEQUENCE {
  protocolIEs          ProtocolIE-Container {{PositionInitiationRequestIEs}} ,
  protocolExtensions   ProtocolExtensionContainer {{PositionInitiationRequestExtensions}} OPTIONAL,
  ...
}

PositionInitiationRequestIEs PCAP-PROTOCOL-IES ::= {
  { ID id-RequestType            CRITICALITY reject   TYPE RequestType            PRESENCE mandatory }|
  { ID id-UE-PositioningCapability CRITICALITY reject  TYPE UE-PositioningCapability PRESENCE mandatory }|
  { ID id-UC-id                  CRITICALITY reject   TYPE UC-ID                  PRESENCE mandatory }|
  { ID id-VerticalAccuracyCode   CRITICALITY ignore   TYPE VerticalAccuracyCode  PRESENCE optional }|
  { ID id-ResponseTime           CRITICALITY ignore   TYPE ResponseTime           PRESENCE optional }|
  { ID id-PositioningPriority   CRITICALITY ignore   TYPE PositioningPriority  PRESENCE optional }|
  { ID id-ClientType             CRITICALITY ignore   TYPE ClientType             PRESENCE optional },
  ...
}

PositionInitiationRequestExtensions PCAP-PROTOCOL-EXTENSION ::= {
  { ID id-IncludeVelocity        CRITICALITY ignore   EXTENSION IncludeVelocity  PRESENCE optional }|
  { ID id-PeriodicLocationInfo   CRITICALITY ignore   EXTENSION PeriodicLocationInfo PRESENCE optional },
  ...
}

-- ****

```

```

-- POSITION INITIATION RESPONSE
-- ****
PositionInitiationResponse ::= SEQUENCE {
    protocolIEs      ProtocolIE-Container    { {PositionInitiationResponseIEs} },
    protocolExtensions  ProtocolExtensionContainer { {PositionInitiationResponseExtensions} }    OPTIONAL,
    ...
}

PositionInitiationResponseIEs PCAP-PROTOCOL-IES ::= {
    { ID id-UE-PositionEstimate      CRITICALITY reject    TYPE UE-PositionEstimate      PRESENCE mandatory } |
    { ID id-PositionData            CRITICALITY ignore     TYPE PositionData            PRESENCE mandatory } |
    { ID id-AccuracyFulfilmentIndicator CRITICALITY ignore    TYPE AccuracyFulfilmentIndicator PRESENCE optional },
    ...
}

PositionInitiationResponseExtensions PCAP-PROTOCOL-EXTENSION ::= {
    { ID id-VelocityEstimate          CRITICALITY ignore    EXTENSION VelocityEstimate    PRESENCE optional },
    ...
}

-- ****
-- POSITION INITIATION FAILURE
-- ****
PositionInitiationFailure ::= SEQUENCE {
    protocolIEs      ProtocolIE-Container    { {PositionInitiationFailureIEs} },
    protocolExtensions  ProtocolExtensionContainer { {PositionInitiationFailureExtensions} }    OPTIONAL,
    ...
}

PositionInitiationFailureIEs PCAP-PROTOCOL-IES ::= {
    { ID id-Cause          CRITICALITY ignore    TYPE Cause      PRESENCE mandatory } |
    { ID id-CriticalityDiagnostics  CRITICALITY ignore    TYPE CriticalityDiagnostics  PRESENCE optional },
    ...
}

PositionInitiationFailureExtensions PCAP-PROTOCOL-EXTENSION ::= {
    ...
}

-- ****
-- POSITION ACTIVATION REQUEST
-- ****
PositionActivationRequest ::= SEQUENCE {

```

```

protocolIEs      ProtocolIE-Container      { {PositionActivationRequestIEs} },
protocolExtensions  ProtocolExtensionContainer { {PositionActivationRequestExtensions} } OPTIONAL,
...
}

PositionActivationRequestIEs PCAP-PROTOCOL-IES ::= {
{ ID id-PositioningMethod          CRITICALITY reject  TYPE PositioningMethod          PRESENCE mandatory } |
{ ID id-Positioning-ResponseTime   CRITICALITY ignore   TYPE Positioning-ResponseTime   PRESENCE mandatory } |
{ ID id-PositioningPriority       CRITICALITY ignore   TYPE PositioningPriority       PRESENCE optional } |
{ ID id-EnvironmentCharacterisation CRITICALITY ignore   TYPE EnvironmentCharacterisation PRESENCE optional } |
{ ID id-UTDOAPositioning          CRITICALITY reject  TYPE UTDOAPositioning          PRESENCE optional } |
{ ID id-GPSPositioning           CRITICALITY reject  TYPE GPSPositioning           PRESENCE optional } |
{ ID id-OTDOAAssistanceData      CRITICALITY reject  TYPE OTDOAAssistanceData      PRESENCE optional } ,
...
}

PositionActivationRequestExtensions PCAP-PROTOCOL-EXTENSION ::= {
{ ID id-IncludeVelocity          CRITICALITY ignore   EXTENSION IncludeVelocity          PRESENCE optional } |
{ ID id-AmountOfReporting        CRITICALITY ignore   EXTENSION AmountOfReporting        PRESENCE optional } |
{ ID id-CellIDPositioning        CRITICALITY ignore   EXTENSION CellIDPositioning        PRESENCE optional } |
{ ID id-GANSSPositioning         CRITICALITY reject  EXTENSION GANSSPositioning         PRESENCE optional } ,
...
}

-- ****
-- POSITION ACTIVATION RESPONSE
-- ****

PositionActivationResponse ::= SEQUENCE {
  protocolIEs      ProtocolIE-Container      { {PositionActivationResponseIEs} },
  protocolExtensions  ProtocolExtensionContainer { {PositionActivationResponseExtensions} } OPTIONAL,
...
}

PositionActivationResponseIEs PCAP-PROTOCOL-IES ::= {
{ ID id-UE-PositionEstimateInfo   CRITICALITY ignore   TYPE UE-PositionEstimateInfo   PRESENCE optional } |
{ ID id-GPS-MeasuredResultsList   CRITICALITY reject  TYPE MeasuredResultsList   PRESENCE optional } |
{ ID id-CellId-MeasuredResultsSets CRITICALITY reject  TYPE CellId-MeasuredResultsSets PRESENCE optional } |
{ ID id-OTDOA-MeasuredResultsSets CRITICALITY reject  TYPE OTDOA-MeasuredResultsSets PRESENCE optional } |
{ ID id-UTDOA-Group               CRITICALITY reject  TYPE UTDOA-Group               PRESENCE optional } ,
...
}

PositionActivationResponseExtensions PCAP-PROTOCOL-EXTENSION ::= {
{ ID id-VelocityEstimate          CRITICALITY ignore   EXTENSION VelocityEstimate          PRESENCE optional } |
{ ID id-MeasInstructionsUsed      CRITICALITY ignore   EXTENSION MeasInstructionsUsed      PRESENCE optional } |
{ ID id-GANSS-MeasuredResultsList   CRITICALITY reject  EXTENSION GANSS-MeasuredResultsList   PRESENCE optional } |
{ ID id-AdditionalGPSAssistDataRequired CRITICALITY ignore   EXTENSION AdditionalGPSAssistDataRequired PRESENCE optional } |
{ ID id-AdditionalGanssAssistDataRequired CRITICALITY ignore   EXTENSION AdditionalGanssAssistDataRequired PRESENCE optional } ,
...
}

```

```

-- ****
-- POSITION ACTIVATION FAILURE
-- ****

PositionActivationFailure ::= SEQUENCE {
    protocolIEs      ProtocolIE-Container      { {PositionActivationFailureIEs} },
    protocolExtensions  ProtocolExtensionContainer { {PositionActivationFailureExtensions} }      OPTIONAL,
    ...
}

PositionActivationFailureIEs PCAP-PROTOCOL-IES ::= {
    { ID id-Cause                  CRITICALITY ignore  TYPE Cause                  PRESENCE mandatory } |
    { ID id-CriticalityDiagnostics  CRITICALITY ignore  TYPE CriticalityDiagnostics  PRESENCE optional },
    ...
}

PositionActivationFailureExtensions PCAP-PROTOCOL-EXTENSION ::= {
    ...
}

-- ****
-- INFORMATION REPORT
-- ****

InformationReport ::= SEQUENCE {
    protocolIEs      ProtocolIE-Container      { {InformationReport-IEs} },
    protocolExtensions  ProtocolExtensionContainer { {InformationReport-Extensions} }      OPTIONAL,
    ...
}

InformationReport-IEs PCAP-PROTOCOL-IES ::= {
    { ID id-InformationExchangeID          CRITICALITY ignore  TYPE InformationExchangeID      PRESENCE mandatory
} |
    { ID id-InformationExchangeObjectType-InfEx-Rprt  CRITICALITY ignore  TYPE InformationExchangeObjectType-InfEx-Rprt  PRESENCE mandatory
},
    ...
}

InformationReport-Extensions PCAP-PROTOCOL-EXTENSION ::= {
    ...
}

InformationExchangeObjectType-InfEx-Rprt ::= CHOICE {
    referencePosition      RefPosition-InfEx-Rprt,
    ...
}

```

```

RefPosition-InfEx-Rprt ::= SEQUENCE {
  requestedDataValueInformation  RequestedDataValueInformation,
  iE-Extensions                  ProtocolExtensionContainer {{ RefPositionItem-InfEx-Rprt-ExtIEs }} OPTIONAL,
  ...
}

RefPositionItem-InfEx-Rprt-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

-- *****
-- 
-- INFORMATION EXCHANGE TERMINATION REQUEST
-- 
-- *****

InformationExchangeTerminationRequest ::= SEQUENCE {
  protocolIEs          ProtocolIE-Container {{InformationExchangeTerminationRequest-IEs}},
  protocolExtensions   ProtocolExtensionContainer {{InformationExchangeTerminationRequest-Extensions}} OPTIONAL,
  ...
}

InformationExchangeTerminationRequest-IEs PCAP-PROTOCOL-IES ::= {
  { ID      id-InformationExchangeID      CRITICALITY ignore      TYPE InformationExchangeID      PRESENCE mandatory},
  ...
}

InformationExchangeTerminationRequest-Extensions PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

-- *****
-- 
-- INFORMATION EXCHANGE FAILURE INDICATION
-- 
-- *****

InformationExchangeFailureIndication ::= SEQUENCE {
  protocolIEs          ProtocolIE-Container {{InformationExchangeFailureIndication-IEs}},
  protocolExtensions   ProtocolExtensionContainer {{InformationExchangeFailureIndication-Extensions}} OPTIONAL,
  ...
}

InformationExchangeFailureIndication-IEs PCAP-PROTOCOL-IES ::= {
  { ID      id-InformationExchangeID      CRITICALITY ignore      TYPE InformationExchangeID      PRESENCE mandatory } |
  { ID      id-Cause                      CRITICALITY ignore      TYPE Cause                  PRESENCE mandatory },
  ...
}

InformationExchangeFailureIndication-Extensions PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

```

```

}

-- ****
-- 
-- ERROR INDICATION
-- 
-- ****

ErrorIndication ::= SEQUENCE {
  protocolIEs      ProtocolIE-Container    { {ErrorIndicationIEs} },
  protocolExtensions  ProtocolExtensionContainer { {ErrorIndicationExtensions} }  OPTIONAL,
  ...
}

ErrorIndicationIEs PCAP-PROTOCOL-IES ::= {
  { ID id-Cause          CRITICALITY ignore  TYPE Cause          PRESENCE optional } |
  { ID id-CriticalityDiagnostics  CRITICALITY ignore  TYPE CriticalityDiagnostics  PRESENCE optional },
  ...
}

ErrorIndicationExtensions PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

-- ****
-- 
-- POSITION PARAMETER MODIFICATION
-- 
-- ****

PositionParameterModification ::= SEQUENCE {
  protocolIEs      ProtocolIE-Container    { {PositionParameterModificationIEs} },
  protocolExtensions  ProtocolExtensionContainer { {PositionParameterModificationExtensions} }  OPTIONAL,
  ...
}

PositionParameterModificationIEs PCAP-PROTOCOL-IES ::= {
  { ID id-UC-id          CRITICALITY reject  TYPE UC-ID          PRESENCE optional } |
  { ID id-UTDOA-Group      CRITICALITY reject  TYPE UTDOA-Group  PRESENCE optional },
  ...
}

PositionParameterModificationExtensions PCAP-PROTOCOL-EXTENSION ::= {
  { ID id-RRCstateChange    CRITICALITY ignore  EXTENSION RRCstateChange  PRESENCE optional },
  ...
}

-- ****
-- 
-- PRIVATE MESSAGE
-- 
-- ****

```

```

PrivateMessage ::= SEQUENCE {
  privateIEs      PrivateIE-Container {{PrivateMessage-IEs}},
  ...
}

PrivateMessage-IEs PCAP-PRIVATE-IES ::= {
  ...
}

-- ****
-- 
-- ABORT
-- 
-- ****

Abort ::= SEQUENCE {
  protocolIEs      ProtocolIE-Container { {AbortIEs} },
  protocolExtensions  ProtocolExtensionContainer { {AbortExtensions} }    OPTIONAL,
  ...
}

AbortIEs PCAP-PROTOCOL-IES ::= {
  { ID id-Cause      CRITICALITY ignore  TYPE Cause      PRESENCE mandatory },
  ...
}

AbortExtensions PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

-- ****
-- 
-- POSITION PERIODIC REPORT
-- 
-- ****

PositionPeriodicReport ::= SEQUENCE {
  protocolIEs      ProtocolIE-Container {{PositionPeriodicReport-IEs}},
  protocolExtensions  ProtocolExtensionContainer {{PositionPeriodicReport-Extensions}}    OPTIONAL,
  ...
}

PositionPeriodicReport-IEs PCAP-PROTOCOL-IES ::= {
  { ID id-UE-PositionEstimateInfo      CRITICALITY ignore  TYPE UE-PositionEstimateInfo      PRESENCE optional } |
  { ID id-VelocityEstimate      CRITICALITY ignore  TYPE VelocityEstimate      PRESENCE optional } |
  { ID id-GPS-MeasuredResultsList      CRITICALITY ignore  TYPE MeasuredResultsList      PRESENCE optional } |
  { ID id-CellId-MeasuredResultsSets      CRITICALITY ignore  TYPE CellId-MeasuredResultsSets      PRESENCE optional } |
  { ID id-OTDOA-MeasuredResultsSets      CRITICALITY ignore  TYPE OTDOA-MeasuredResultsSets      PRESENCE optional } |
  { ID id-Cause      CRITICALITY ignore  TYPE Cause      PRESENCE optional } ,
  ...
}

```

```

PositionPeriodicReport-Extensions PCAP-PROTOCOL-EXTENSION ::= {
  { ID id-GANSS-MeasuredResultsList           CRITICALITY ignore  EXTENSION GANSS-MeasuredResultsList           PRESENCE optional } |
  { ID id-AdditionalGPSAssistDataRequired      CRITICALITY ignore  EXTENSION AdditionalGPSAssistDataRequired      PRESENCE optional } |
  { ID id-AdditionalGansssAssistDataRequired    CRITICALITY ignore  EXTENSION AdditionalGansssAssistDataRequired    PRESENCE optional },
  ...
}

-- ****
-- POSITION PERIODIC RESULT
-- ****

PositionPeriodicResult ::= SEQUENCE {
  protocolIEs      ProtocolIE-Container    {{PositionPeriodicResult-IEs}},
  protocolExtensions ProtocolExtensionContainer {{PositionPeriodicResult-Extensions}}   OPTIONAL,
  ...
}

PositionPeriodicResult-IEs PCAP-PROTOCOL-IES ::= {
  { ID id-UE-PositionEstimate           CRITICALITY ignore  TYPE UE-PositionEstimate           PRESENCE optional } |
  { ID id-VelocityEstimate             CRITICALITY ignore  TYPE VelocityEstimate             PRESENCE optional } |
  { ID id-PositionData                CRITICALITY ignore  TYPE PositionData                PRESENCE optional } |
  { ID id-AccuracyFulfilmentIndicator CRITICALITY ignore  TYPE AccuracyFulfilmentIndicator PRESENCE optional } |
  { ID id-Cause                      CRITICALITY ignore  TYPE Cause                      PRESENCE optional },
  ...
}

PositionPeriodicResult-Extensions PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

-- ****
-- POSITION PERIODIC TERMINATION
-- ****

PositionPeriodicTermination ::= SEQUENCE {
  protocolIEs      ProtocolIE-Container    {{PositionPeriodicTermination-IEs}},
  protocolExtensions ProtocolExtensionContainer {{PositionPeriodicTermination-Extensions}}   OPTIONAL,
  ...
}

PositionPeriodicTermination-IEs PCAP-PROTOCOL-IES ::= {
  { ID id-PeriodicTerminationCause      CRITICALITY ignore  TYPE PeriodicTerminationCause      PRESENCE optional },
  ...
}

PositionPeriodicTermination-Extensions PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

}
END

```

9.3.4 Information Element Definitions

```

-- ****
-- Information Element Definitions
-- ****

PCAP-IEs {
  itu-t (0) identified-organization (4) etsi (0) mobileDomain (0)
  umts-Access (20) modules (3) pcap(4) version1 (1) pcap-IEs (2) }

DEFINITIONS AUTOMATIC TAGS ::=

BEGIN

IMPORTS
  maxNrOfErrors,
  maxSat,
  maxSatAlmanac,
  maxNrOfLevels,
  maxNrOfMeasNCell,
  maxNrOfMeasurements,
  maxNrOfPoints,
  maxNrOfExpInfo,
  maxNrOfSets,
  maxRateMatching,
  maxNrOfTFs,
  maxTTI-count,
  maxTS-1,
  maxCCTrCH,
  maxTF,
  maxTFC,
  maxPRACH,
  maxTrCH,
  maxTGPS,
  maxNoOfMeasurements,
  maxCellMeas,
  maxNrOfEDPCCH-PO-QUANTSTEPS,
  maxNrOfRefETFCI-PO-QUANTSTEPS,
  maxNrOfRefETFCIs,
  maxSet,
  maxGANSS,
  maxGANSSSat,
  maxGANSSSet,
  maxSgnType,
  maxGANSSSatAlmanac,
  maxGANSSClockMod,
  maxGANSS-1,

```

id-UTRAN-GPSReferenceTime,
id-UTRAN-GPSReferenceTimeResult,
id-GPS-UTRAN-TRU,
id-UTRAN-GPS-DriftRate,
id-OTDOA-AddMeasuredResultsInfo,
id-GPS-ReferenceLocation,
id-rxTimingDeviation768Info,
id-rxTimingDeviation384extInfo,
id-MeasurementValidity,
id-ExtendedRoundTripTime,
id-roundTripTimeInfoWithType1,
id-AddMeasurementInfo,
id-Extended-RNC-ID,
id-GANSS-CommonAssistanceData,
id-GANSS-GenericAssistanceDataList,
id-GANSS-PositioningDataSet,
id-GNSS-PositioningMethod,
id-NetworkAssistedGANSSSupport,
id-TUTRANGANSSMeasurementValueInfo,
id-angleOfArrivalLCR,
id-extendedTimingAdvanceLCR,
id-additionalMeasurementInfoForLCR,
id-timingAdvanceLCR-R7,
id-rxTimingDeviationLCR,
id-GPSReferenceTimeUncertainty,
id-GANSS-AddIonoModelReq,
id-GANSS-EarthOrientParaReq,
id-GANSS-Additional-Ionospheric-Model,
id-GANSS-Earth-Orientation-Parameters,
id-GANSS-Additional-Time-Models,
id-GANSS-Additional-Navigation-Models,
id-GANSS-Additional-UTC-Models,
id-GANSS-Auxiliary-Information,
id-GANSS-SBAS-ID,
id-GANSS-SBAS-IDs,
id-GANSS-Signal-IDs,
id-supportGANSSNonNativeADchoices,
id-PositionDataUEbased,
id-ganssCodePhaseAmbiguityExt,
id-ganssIntegerCodePhaseExt,
id-GANSScarrierPhaseRequested,
id-GANSSMultiFreqMeasRequested,
id-ganssReq-AddIonosphericModel,
id-ganssReq-EarthOrientPara,
id-ganssAddNavigationModel-req,
id-ganssAddUTCModel-req,
id-ganssAuxInfo-req,
id-GANSS-AlmanacModelChoice

```

FROM PCAP-Constants

    Criticality,
    ProcedureCode,
    ProtocolIE-ID,
    TransactionID,
    TriggeringMessage
FROM PCAP-CommonDataTypes

    ProtocolExtensionContainer{},
    PCAP-PROTOCOL-EXTENSION
FROM PCAP-Containers;

-- ****
-- 
-- Accuracy Fulfilment Indicator
-- 
-- ****

AccuracyFulfilmentIndicator ::= ENUMERATED{
    requested-Accuracy-Fulfilled,
    requested-Accuracy-Not-Fulfilled,
    ...
}

-- ****
-- 
-- Additional Method Type
-- 
-- ****

AdditionalMethodType ::= ENUMERATED {
    ue-assisted,
    ue-based,
    ue-based-preferred-but-ue-assisted-allowed,
    ue-assisted-preferred-but-ue-based-allowed,
    ...
}

-- ****
-- 
-- Almanac and Satellite Health SIB
-- 
-- ****

AlmanacAndSatelliteHealthSIB ::= SEQUENCE {
    gpsAlmanacAndSatelliteHealth,
    satMask
    lsbTOW
    iE-Extensions
        GPS-AlmanacAndSatelliteHealth,
        BIT STRING (SIZE (1..32)),
        BIT STRING (SIZE (8)),
        ProtocolExtensionContainer { { AlmanacAndSatelliteHealthSIB-ExtIEs } } OPTIONAL,
}

```

```

}
  ...
}

AlmanacAndSatelliteHealthSIB-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

-- ****
-- 
-- Cause IE
-- 
-- ****

Cause ::= CHOICE {
  radioNetwork      CauseRadioNetwork,
  transport        CauseTransport,
  protocol         CauseProtocol,
  misc             CauseMisc,
  ...
}
CauseRadioNetwork ::= ENUMERATED {
  invalid-reference-information,
  information-temporarily-not-available,
  information-provision-not-supported-for-the-object,
  position-calculation-error-invalid-GPS-measured-results,
  ...,
  position-calculation-error-invalid-CellID-measured-results,
  position-calculation-error-invalid-OTDOA-measured-results,
  position-calculation-error-AGPS-positioning-method-not-supported,
  position-calculation-error-CellID-positioning-method-not-supported,
  position-calculation-error-OTDOA-positioning-method-not-supported,
  initial-UE-position-estimate-missing,
  position-calculation-error-invalid-UTDOA-measured-results,
  position-calculation-error-UTDOA-positioning-method-not-supported,
  position-calculation-error-UTDOA-not-supported-UTRAN-cell,
  positioning-method-not-supported,
  loss-of-contact-with-UE,
  sAS-unable-to-perform-UTDOA-positioning-within-response-time,
  location-measurement-failure,
  ue-positioning-error-Not-enough-OTDOA-cells,
  ue-positioning-error-Not-enough-GPS-Satellites,
  ue-positioning-error-Reference-Cell-not-serving-cell,
  ue-positioning-error-Not-Accomplished-GPS-Timing-of-Cell-Frames,
  ue-positioning-error-Undefined-Error,
  position-calculation-error-invalid-Galileo-measured-results,
  position-calculation-error-AGalileo-positioning-method-not-supported,
  ue-positioning-error-Not-enough-Galileo-Satellites,
  ue-positioning-error-Not-Accomplished-Galileo-Timing-of-Cell-Frames,
  ue-positioning-error-Assistance-Data-missing,
  position-calculation-error-invalid-GLONASS-measured-results,
  position-calculation-error-invalid-GANSS-measured-results,
  position-calculation-error-AGANSS-positioning-method-not-supported,
  ue-positioning-error-Not-enough-GANSS-Satellites,
}

```

```

    ue-positioning-error-Not-Accomplished-GANSS-Timing-of-Cell-Frames
}

CauseTransport ::= ENUMERATED {
    transport-resource-unavailable,
    unspecified,
    ...
}

CauseProtocol ::= ENUMERATED {
    transfer-syntax-error,
    abstract-syntax-error-reject,
    abstract-syntax-error-ignore-and-notify,
    message-not-compatible-with-receiver-state,
    semantic-error,
    unspecified,
    abstract-syntax-error-falsely-constructed-message,
    ...
}

CauseMisc ::= ENUMERATED {
    processing-overload,
    hardware-failure,
    o-and-m-intervention,
    unspecified,
    ...
}

-- ****
-- 
-- Cell Id Measured Results Sets
-- 
-- ****

CellId-MeasuredResultsSets ::=      SEQUENCE (SIZE (1..maxNrOfMeasurements)) OF
    CellId-MeasuredResultsInfoList

CellId-MeasuredResultsInfoList ::=    SEQUENCE (SIZE (1..maxNrOfMeasNCell)) OF
    CellId-MeasuredResultsInfo

CellId-MeasuredResultsInfo ::=        SEQUENCE {
        uC-ID,
        uTRANAccessPointPositionAltitude,
        ue-PositionEstimate          OPTIONAL,
        roundTripTimeInfo            OPTIONAL, -- FDD only
        rxTimingDeviationInfo        OPTIONAL, -- 3.84Mcps TDD only
        rxTimingDeviationLCRInfo    OPTIONAL, -- 1.28Mcps TDD only
        pathloss                      OPTIONAL,
        iE-Extensions                 ProtocolExtensionContainer { { CellId-MeasuredResultsInfo-ExtIEs } }    OPTIONAL,
        ...
    }

CellId-MeasuredResultsInfo-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {

```

```

{ ID id-rxTimingDeviation768Info   CRITICALITY reject   EXTENSION RxTimingDeviation768Info
{ ID id-rxTimingDeviation384extInfo CRITICALITY reject   EXTENSION RxTimingDeviation384extInfo
{ ID id-roundTripTimeInfoWithType1 CRITICALITY ignore   EXTENSION RoundTripTimeInfoWithType1
{ ID id-AddMeasurementInfo        CRITICALITY ignore   EXTENSION AddMeasurementInfo
{ ID id-angleOfArrivalLCR        CRITICALITY ignore   EXTENSION AngleOfArrivalLCR
    ...
}

RoundTripTimeInfo ::=

    ue-RxTxTimeDifferenceType2
    ue-PositioningMeasQuality
    roundTripTime
    iE-Extensions
    ...
}

RoundTripTimeInfo-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
    { ID id-ExtendedRoundTripTime   CRITICALITY ignore   EXTENSION ExtendedRoundTripTime
    ...
}

RoundTripTimeInfoWithType1 ::=

    ue-RxTxTimeDifferenceType1
    roundTripTime
    extendedRoundTripTime
    iE-Extensions
    ...
}

RoundTripTimeInfoWithType1-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
    ...
}

UE-RxTxTimeDifferenceType2 ::=           INTEGER (0..8191)

UE-RxTxTimeDifferenceType1 ::=           INTEGER (768..1280)

UE-PositioningMeasQuality ::=

    stdResolution
    numberOfMeasurements
    stdOfMeasurements
    iE-Extensions
    ...
}

UE-PositioningMeasQuality-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
    ...
}

RoundTripTime ::=                         INTEGER (0..32766)
-- Actual value RoundTripTime = IE value * 0.0625 + 876

ExtendedRoundTripTime ::=                 INTEGER (32767..103041)
-- Actual value RoundTripTime = IE value * 0.0625 + 876

PRESENCE optional }| -- 7.68Mcps TDD only
PRESENCE optional }| -- 3.84Mcps TDD only
PRESENCE optional }| -- FDD only
PRESENCE optional }|
PRESENCE optional },

```

```

UTRANAccessPointPositionAltitude ::= SEQUENCE {
  geographicalCoordinates,
  GeographicalCoordinates,
  ga-AltitudeAndDirection
  GA-AltitudeAndDirection
  iE-Extensions
  ProtocolExtensionContainer { { UTRANAccessPointPositionAltitude-ExtIEs } } OPTIONAL,
  ...
}

UTRANAccessPointPositionAltitude-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

RxTimingDeviationInfo ::= SEQUENCE {
  rxTimingDeviation,
  RxTimingDeviation,
  timingAdvance,
  TimingAdvance,
  iE-Extensions
  ProtocolExtensionContainer { { RxTimingDeviationInfo-ExtIEs } } OPTIONAL,
  ...
}

RxTimingDeviationInfo-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

RxTimingDeviationLCRInfo ::= SEQUENCE {
  rxTimingDeviationLCR,
  RxTimingDeviationLCR,
  timingAdvanceLCR,
  TimingAdvanceLCR,
  -- The content of this IE shall be ignored if the id-extendedTimingAdvanceLCR IE is present.
  iE-Extensions
  ProtocolExtensionContainer { { RxTimingDeviationLCRInfo-ExtIEs } } OPTIONAL,
  ...
}

RxTimingDeviationLCRInfo-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  { ID id-extendedTimingAdvanceLCR CRITICALITY ignore EXTENSION ExtendedTimingAdvanceLCR
    PRESENCE optional }, -- 1.28Mcps TDD only
  ...
}

ExtendedTimingAdvanceLCR ::= INTEGER (2048..8191)

RxTimingDeviation768Info ::= SEQUENCE {
  rxTimingDeviation768,
  RxTimingDeviation768,
  timingAdvance768,
  TimingAdvance768,
  iE-Extensions
  ProtocolExtensionContainer { { RxTimingDeviation768Info-ExtIEs } } OPTIONAL,
  ...
}

RxTimingDeviation768Info-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

RxTimingDeviation384extInfo ::= SEQUENCE {
  rxTimingDeviation384ext,
  RxTimingDeviation384ext,
  timingAdvance384ext,
  TimingAdvance384ext,
  iE-Extensions
  ProtocolExtensionContainer { { RxTimingDeviation384extInfo-ExtIEs } } OPTIONAL,
}

```

```

}

RxTimingDeviation384extInfo-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

AddMeasurementInfo ::= SEQUENCE {
  cpich-RSCP          CPICH-RSCP          OPTIONAL,
  cpich-EcNo          CPICH-EcNo          OPTIONAL,
  iE-Extensions       ProtocolExtensionContainer { { AddMeasurementInfo-ExtIEs } } OPTIONAL,
  ...
}

AddMeasurementInfo-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

AngleOfArrivalLCR ::= SEQUENCE {
  aOA-LCR,
  aOA-LCR-Accuracy-Class,
  iE-Extensions       ProtocolExtensionContainer { { AngleOfArrivalLCR-ExtIEs } } OPTIONAL,
  ...
}

AngleOfArrivalLCR-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

RxTimingDeviation ::= INTEGER (0..8191)

RxTimingDeviationLCR ::= INTEGER (0..511)

RxTimingDeviation768 ::= INTEGER (0..65535)

RxTimingDeviation384ext ::= INTEGER (0..32767)

TimingAdvance ::= INTEGER (0..63)

TimingAdvanceLCR ::= INTEGER (0..2047)

TimingAdvance768 ::= INTEGER (0..511)

TimingAdvance384ext ::= INTEGER (0..255)

Pathloss ::= INTEGER (46..158)
-- Unit: dB; as defined in [4] subclause 10.3.7.3

CPICH-EcNo ::= INTEGER (0..49)
-- According to CPICH_Ec/No in [13]

CPICH-RSCP ::= INTEGER (-5..91)
-- According to CPICH_RSCP in [13]

```

```

AOA-LCR ::= INTEGER (0..719)-- According to mapping in [14]

AOA-LCR-Accuracy-Class ::= ENUMERATED {
    a,b,c,d,e,f,g,h, ...
}

-- ****
-- Cell-ID Positioning (Position Activation Request Message)
-- ****

CellIDPositioning ::= SEQUENCE {
    requestedCellIDMeasurements      RequestedCellIDMeasurements,
    iE-Extensions                   ProtocolExtensionContainer { { CellIDPositioning-ExtIEs } } OPTIONAL,
    ...
}

CellIDPositioning-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
    ...
}

RequestedCellIDMeasurements ::= CHOICE {
    fdd                                SEQUENCE {
        roundTripTimeInfoWanted      BOOLEAN,
        pathlossWanted              BOOLEAN,
        roundTripTimeInfoWithType1Wanted BOOLEAN,
        cpichRSCPWanted             BOOLEAN,
        cpicEcNoWanted              BOOLEAN,
        iE-Extensions                ProtocolExtensionContainer { { RequestedCellIDMeasurementsFDD-ExtIEs } } OPTIONAL,
        ...
    },
    tdd                                SEQUENCE {
        rxTimingDeviationInfoWanted BOOLEAN,
        pathlossWanted              BOOLEAN,
        rxTimingDeviationLCRInfoWanted BOOLEAN,
        rxTimingDeviation768InfoWanted BOOLEAN,
        rxTimingDeviation384extInfoWanted BOOLEAN,
        angleOfArrivalLCRWanted      BOOLEAN,
        timingAdvanceLCRWanted       BOOLEAN,
        iE-Extensions                ProtocolExtensionContainer { { RequestedCellIDMeasurementsTDD-ExtIEs } } OPTIONAL,
        ...
    },
    ...
}

RequestedCellIDMeasurementsFDD-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
    ...
}

RequestedCellIDMeasurementsTDD-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
    ...
}

```

```

-- ****
-- Client Type
-- ****

ClientType ::= ENUMERATED {
    emergency-services,
    value-added-services,
    plmn-operator-services,
    lawful-intercept-services,
    plmn-operator-broadcast-services,
    plmn-operator-oam,
    plmn-operator-anonymous-statistics,
    plmn-operator-target-ms-service-support,
    ...
}

-- ****
-- CriticalityDiagnostics
-- ****

CriticalityDiagnostics ::= SEQUENCE {
    procedureCode                  ProcedureCode                               OPTIONAL,
    triggeringMessage              TriggeringMessage              OPTIONAL,
    procedureCriticality          Criticality                    OPTIONAL,
    transactionID                 TransactionID                OPTIONAL,
    iEsCriticalityDiagnostics    CriticalityDiagnostics-IE-List  OPTIONAL,
    iE-Extensions                  ProtocolExtensionContainer { {CriticalityDiagnostics-ExtIEs} }  OPTIONAL,
    ...
}

CriticalityDiagnostics-IE-List ::= SEQUENCE (SIZE (1..maxNrOfErrors)) OF
    SEQUENCE {
        iECriticality          Criticality,
        iE-ID                  ProtocolIE-ID,
        repetitionNumber        CriticalityDiagnosticsRepetition      OPTIONAL,
        messageStructure        MessageStructure              OPTIONAL,
        typeOfError             TypeOfError,
        iE-Extensions          ProtocolExtensionContainer { {CriticalityDiagnostics-IE-List-ExtIEs} }  OPTIONAL,
        ...
    }

CriticalityDiagnostics-IE-List-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
    ...
}

CriticalityDiagnostics-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
    ...
}

```

```
CriticalityDiagnosticsRepetition ::= INTEGER (0..255)
```

```
TypeOfError ::= ENUMERATED {
    not-understood,
    missing,
    ...
}

-- ****
-- 
-- DGPSCorrections
-- 
-- ****

DGPSCorrections ::= SEQUENCE {
    gps-TOW-sec           INTEGER (0..604799),
    statusHealth          DiffCorrectionStatus,
    dgps-CorrectionSatInfoList DGPS-CorrectionSatInfoList           OPTIONAL,
    -- not included if satelliteHealth is equal to noData or invalidData
    iE-Extensions          ProtocolExtensionContainer { { DGPSCorrections-ExtIEs } }   OPTIONAL,
    ...
}

DGPSCorrections-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
    ...
}

DiffCorrectionStatus ::= ENUMERATED {
    udre-1-0, udre-0-75, udre-0-5, udre-0-3,
    udre-0-2, udre-0-1, noData, invalidData
}

DGPS-CorrectionSatInfoList ::= SEQUENCE (SIZE (1..maxSat)) OF
    DGPS-CorrectionSatInfo

DGPS-CorrectionSatInfo ::= SEQUENCE {
    satID                INTEGER (0..63),
    iode                 INTEGER (0..255),
    udre                 UDRE,
    prc                  PRC,
    rrc                  RRC,
    iE-Extensions          ProtocolExtensionContainer { { DGPS-CorrectionSatInfo-ExtIEs } }   OPTIONAL,
    ...
}

DGPS-CorrectionSatInfo-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
    ...
}

UDRE ::= ENUMERATED {
```

```

        lessThan1,
        between1-and-4,
        between4-and-8,
        over8 }

PRC ::= INTEGER (-2047..2047)

RRC ::= INTEGER (-127..127)

-- *****
-- 
-- UE-PositionEstimate (i.e., Geographical Area)
-- 
-- *****

-- UE-PositionEstimate is based on Geographical Area Description in 23.032

UE-PositionEstimate ::= CHOICE {
    point
    pointWithUnCertainty
    polygon
    pointWithUncertaintyEllipse
    pointWithAltitude
    pointWithAltitudeAndUncertaintyEllipsoid
    ellipsoidArc
    ...
}

GeographicalCoordinates ::= SEQUENCE {
    latitudeSign      ENUMERATED {north, south},
    latitude          INTEGER (0..8388607),
    longitude         INTEGER (-8388608..8388607),
    iE-Extensions     ProtocolExtensionContainer { {GeographicalCoordinates-ExtIEs} } OPTIONAL,
    ...
}

GeographicalCoordinates-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
    ...
}

GA-AltitudeAndDirection ::= SEQUENCE {
    directionOfAltitude ENUMERATED {height, depth},
    altitude           INTEGER (0..32767),
    ...
}

GA-EllipsoidArc ::= SEQUENCE {
    geographicalCoordinates  GeographicalCoordinates,
    innerRadius             INTEGER (0..65535),
    ...
}

```

```

uncertaintyRadius          INTEGER (0..127),
offsetAngle                INTEGER (0..179),
includedAngle               INTEGER (0..179),
confidence                 INTEGER (0..100),
iE-Extensions              ProtocolExtensionContainer { { GA-EllipsoidArc-ExtIEs} } OPTIONAL,
...
}

GA-EllipsoidArc-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

GA-Point ::= SEQUENCE {
  geographicalCoordinates   GeographicalCoordinates,
  iE-Extensions              ProtocolExtensionContainer { {GA-Point-ExtIEs} } OPTIONAL,
...
}

GA-Point-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

GA-PointWithAltitude ::= SEQUENCE {
  geographicalCoordinates   GeographicalCoordinates,
  altitudeAndDirection      GA-AltitudeAndDirection,
  iE-Extensions              ProtocolExtensionContainer { { GA-PointWithAltitude-ExtIEs} } OPTIONAL,
...
}

GA-PointWithAltitude-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

GA-PointWithAltitudeAndUncertaintyEllipsoid ::= SEQUENCE {
  geographicalCoordinates   GeographicalCoordinates,
  altitudeAndDirection      GA-AltitudeAndDirection,
  uncertaintyEllipse         GA-UncertaintyEllipse,
  uncertaintyAltitude        INTEGER (0..127),
  confidence                 INTEGER (0..100),
  iE-Extensions              ProtocolExtensionContainer { { GA-PointWithAltitudeAndUncertaintyEllipsoid-ExtIEs} } OPTIONAL,
...
}

GA-PointWithAltitudeAndUncertaintyEllipsoid-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

GA-PointWithUnCertainty ::=SEQUENCE {
  geographicalCoordinates   GeographicalCoordinates,
  uncertaintyCode           INTEGER (0..127),
  iE-Extensions              ProtocolExtensionContainer { {GA-PointWithUnCertainty-ExtIEs} } OPTIONAL,
...
}

GA-PointWithUnCertainty-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {

```

```

}
  ...
}

GA-PointWithUnCertaintyEllipse ::= SEQUENCE {
  geographicalCoordinates    GeographicalCoordinates,
  uncertaintyEllipse        GA-UncertaintyEllipse,
  confidence                INTEGER (0..100),
  iE-Extensions             ProtocolExtensionContainer { { GA-PointWithUnCertaintyEllipse-ExtIEs } } OPTIONAL,
  ...
}

GA-PointWithUnCertaintyEllipse-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

GA-Polygon ::= SEQUENCE (SIZE (1..maxNrOfPoints)) OF
  SEQUENCE {
    geographicalCoordinates    GeographicalCoordinates,
    iE-Extensions             ProtocolExtensionContainer { { GA-Polygon-ExtIEs } } OPTIONAL,
    ...
  }

GA-Polygon-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

GA-UncertaintyEllipse ::= SEQUENCE {
  uncertaintySemi-major      INTEGER (0..127),
  uncertaintySemi-minor      INTEGER (0..127),
  orientationOfMajorAxis     INTEGER (0..89),
  ...
}

-- ****
-- 
-- UE-PositionEstimateInfo
-- 
-- ****

UE-PositionEstimateInfo ::= SEQUENCE {
  referenceTimeChoice         ReferenceTimeChoice,
  ue-positionEstimate        UE-PositionEstimate,
  iE-Extensions               ProtocolExtensionContainer { { UE-PositionEstimateInfo-ExtIEs } } OPTIONAL,
  ...
}

UE-PositionEstimateInfo-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  { ID id-GPSReferenceTimeUncertainty CRITICALITY ignore EXTENSION GPSReferenceTimeUncertainty PRESENCE optional } |
  { ID id-PositionDataUEbased CRITICALITY ignore EXTENSION PositionDataUEbased PRESENCE optional },
  ...
}

ReferenceTimeChoice ::= CHOICE {
  utran-GPSReferenceTimeResult    UTRAN-GPSReferenceTimeResult,

```

```

gps-ReferenceTimeOnly           INTEGER (0..604799999, ...),
cell-Timing                      Cell-Timing,
...
utran-GANSSReferenceTimeResult  UTRAN-GANSSReferenceTimeResult,
ganss-Reference-Time-Only       GANSS-Reference-Time-Only
}

Cell-Timing ::= SEQUENCE {
  sfn                  INTEGER (0..4095),
  uC-ID                UC-ID,
  iE-Extensions        ProtocolExtensionContainer { { Cell-Timing-ExtIEs } }  OPTIONAL,
  ...
}

Cell-Timing-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {

}

GANSS-Reference-Time-Only ::= SEQUENCE {
  ganssTODmsec      INTEGER (0..3599999),
  ganssTimeID       GANSSID
                                OPTIONAL,
  iE-Extensions     ProtocolExtensionContainer { { GANSS-Reference-Time-Only-ExtIEs } } OPTIONAL,
  ...
}

GANSS-Reference-Time-Only-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {

}

PositionDataUEbased ::= SEQUENCE {
  positionData      BIT STRING (SIZE(16))
                                OPTIONAL,
  iE-Extensions    ProtocolExtensionContainer { { PositionDataUEbased-ExtIEs } }  OPTIONAL,
  ...
}

PositionDataUEbased-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {

}

-- ****
-- 
-- Position Data
-- 
-- ****

PositionData ::= SEQUENCE {
  positioningDataDiscriminator      PositioningDataDiscriminator,
  positioningDataSet                PositioningDataSet
                                OPTIONAL,
-- This IE shall be present if the PositioningDataDiscriminator IE is set to the value "0000" --
  iE-Extensions        ProtocolExtensionContainer { { PositionData-ExtIEs } }  OPTIONAL,
  ...
}

```

```

}

PositionData-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  { ID id-GANSS-PositioningDataSet           CRITICALITY ignore  EXTENSION GANSS-PositioningDataSet           PRESENCE optional },
  ...
}

GANSS-PositioningDataSet ::= SEQUENCE(SIZE(1..maxGANSSSet)) OF GANSS-PositioningMethodAndUsage

GANSS-PositioningMethodAndUsage ::= OCTET STRING (SIZE(1))

PositioningDataDiscriminator ::= BIT STRING (SIZE(4))

PositioningDataSet ::= SEQUENCE(SIZE(1..maxSet)) OF PositioningMethodAndUsage

PositioningMethodAndUsage ::= OCTET STRING (SIZE(1))

-- ****
-- 
-- GPS-AcquisitionAssistance:
-- 
-- ****

GPS-AcquisitionAssistance ::= SEQUENCE {
  gps-TOW-1msec           INTEGER (0..604799999),
  satelliteInformationList AcquisitionSatInfoList,
  iE-Extensions           ProtocolExtensionContainer { { GPS-AcquisitionAssistance-ExtIEs } } OPTIONAL,
  ...
}

GPS-AcquisitionAssistance-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  { ID id-UTRAN-GPSReferenceTime   CRITICALITY ignore  EXTENSION UTRAN-GPSReferenceTime   PRESENCE optional} |
  { ID id-GPSReferenceTimeUncertainty CRITICALITY ignore  EXTENSION GPSReferenceTimeUncertainty PRESENCE optional} ,
  ...
}

AcquisitionSatInfoList ::= SEQUENCE (SIZE (1..maxSat)) OF
  AcquisitionSatInfo

AcquisitionSatInfo ::= SEQUENCE {
  satID           INTEGER (0..63),
  doppler0thOrder INTEGER (-2048..2047),
  extraDopplerInfo ExtraDopplerInfo
  codePhase       INTEGER (0..1022),
  integerCodePhase INTEGER (0..19),
  gps-BitNumber   INTEGER (0..3),
  codePhaseSearchWindow CodePhaseSearchWindow,
  azimuthAndElevation AzimuthAndElevation
  iE-Extensions   ProtocolExtensionContainer { { AcquisitionSatInfo-ExtIEs } } OPTIONAL,
  ...
}

```

```

AcquisitionSatInfo-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

ExtraDopplerInfo ::= SEQUENCE {
  doppler1stOrder      INTEGER (-42..21),
  dopplerUncertainty   DopplerUncertainty,
  ie-Extensions        ProtocolExtensionContainer { { ExtraDopplerInfo-ExtIEs } } OPTIONAL,
  ...
}

ExtraDopplerInfo-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

DopplerUncertainty ::= ENUMERATED {
  hz12-5, hz25, hz50, hz100, hz200, ...
}

CodePhaseSearchWindow ::= ENUMERATED {
  w1023, w1, w2, w3, w4, w6, w8,
  w12, w16, w24, w32, w48, w64,
  w96, w128, w192 }

AzimuthAndElevation ::= SEQUENCE {
  azimuth      INTEGER (0..31),
  elevation    INTEGER (0..7),
  ie-Extensions ProtocolExtensionContainer { { AzimuthAndElevation-ExtIEs } } OPTIONAL,
  ...
}

AzimuthAndElevation-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

-- ****
-- 
-- GANSS Elements
-- 
-- ****

AuxInfoGANSS-ID1 ::= SEQUENCE (SIZE(1.. maxGANSSat)) OF AuxInfoGANSS-ID1-element

AuxInfoGANSS-ID1-element ::= SEQUENCE {
  svID          INTEGER(0..63),
  signalsAvailable BIT STRING (SIZE(8)),
  ie-Extensions  ProtocolExtensionContainer { { AuxInfoGANSS-ID1-element-ExtIEs } } OPTIONAL,
  ...
}

AuxInfoGANSS-ID1-element-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

```

```

}

AuxInfoGANSS-ID3 ::= SEQUENCE (SIZE(1.. maxGANSSat)) OF AuxInfoGANSS-ID3-element

AuxInfoGANSS-ID3-element ::= SEQUENCE {
    svID           INTEGER(0..63),
    signalsAvailable  BIT STRING (SIZE(8)),
    channelNumber    INTEGER (-7..13),
    ie-Extensions    ProtocolExtensionContainer { { AuxInfoGANSS-ID3-element-ExtIEs } } OPTIONAL,
    ...
}

AuxInfoGANSS-ID3-element-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
    ...
}

CNAVclockModel ::= SEQUENCE {
    cnavToc          BIT STRING (SIZE (11)),
    cnavTop          BIT STRING (SIZE (11)),
    cnavURA0         BIT STRING (SIZE (5)),
    cnavURA1         BIT STRING (SIZE (3)),
    cnavURA2         BIT STRING (SIZE (3)),
    cnavAf2          BIT STRING (SIZE (10)),
    cnavAf1          BIT STRING (SIZE (20)),
    cnavAf0          BIT STRING (SIZE (26)),
    cnavTgd          BIT STRING (SIZE (13)),
    cnavISCl1cp      BIT STRING (SIZE (13))                                OPTIONAL,
    cnavISCl1cd      BIT STRING (SIZE (13))                                OPTIONAL,
    cnavISCl1ca      BIT STRING (SIZE (13))                                OPTIONAL,
    cnavISCl2c       BIT STRING (SIZE (13))                                OPTIONAL,
    cnavISCl5i5      BIT STRING (SIZE (13))                                OPTIONAL,
    cnavISCl5q5      BIT STRING (SIZE (13))                                OPTIONAL,
    ie-Extensions    ProtocolExtensionContainer { { CNAVclockModel-ExtIEs } } OPTIONAL,
    ...
}

CNAVclockModel-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
    ...
}

DeltaUT1 ::= SEQUENCE {
    b1              BIT STRING (SIZE(11)),
    b2              BIT STRING (SIZE(10)),
    ie-Extensions    ProtocolExtensionContainer { { DeltaUT1-ExtIEs } } OPTIONAL,
    ...
}

DeltaUT1-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
    ...
}

DGANSS-Corrections ::= SEQUENCE {
    dGANSS-ReferenceTime      INTEGER(0..119),
    dGANSS-Information
}
```

```

ie-Extensions          ProtocolExtensionContainer { { DGANSS-Corrections-ExtIEs } }      OPTIONAL,
...
}

DGANSS-Corrections-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

DGANSS-Information ::= SEQUENCE (SIZE (1..maxSgnType)) OF DGANSS-InformationItem

DGANSS-InformationItem ::= SEQUENCE {
  gANSS-SignalId          GANSS-SignalID                                OPTIONAL,
  gANSS-StatusHealth        GANSS-StatusHealth,
  -- The following IE shall be present if the Status/Health IE value is not equal to "no data" or "invalid data"
  dGANSS-SignalInformation  DGANSS-SignalInformation      OPTIONAL,
  ie-Extensions            ProtocolExtensionContainer { { DGANSS-InformationItem-ExtIEs } }  OPTIONAL,
  ...
}

DGANSS-InformationItem-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

DGANSS-SignalInformation ::= SEQUENCE (SIZE (1..maxGANSSSat)) OF DGANSS-SignalInformationItem

DGANSS-SignalInformationItem ::= SEQUENCE {
  satId                  INTEGER(0..63),
  gANSS-iod               BIT STRING (SIZE (10)),
  udre                   UDRE,
  ganss-prc              INTEGER(-2047..2047),
  ganss-rrc              INTEGER(-127..127),
  ie-Extensions          ProtocolExtensionContainer { { DGANSS-SignalInformationItem-ExtIEs } }  OPTIONAL,
  ...
}

DGANSS-SignalInformationItem-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

GANSS-AddClockModels ::= CHOICE {
  navClockModel           NAVclockModel,
  cnavClockModel          CNAVclockModel,
  glonassClockModel        GLONASSclockModel,
  sbasClockModel          SBASclockModel,
  ...
}

GANSS-AddOrbitModels ::= CHOICE {
  navKeplerianSet          NavModel-NAVKeplerianSet,
  cnavKeplerianSet          NavModel-CNAVKeplerianSet,
}

```

```

glonassECEF          NavModel-GLONASSecef,
sbasECEF            NavModel-SBASecef,
...
}

GANSS-Additional-Ionospheric-Model ::= SEQUENCE {
  dataID              BIT STRING (SIZE(2)),
  alpha-beta-parameters  GPS-Ionospheric-Model,
  ie-Extensions        ProtocolExtensionContainer { { GANSS-Additional-Ionospheric-Model-ExtIEs } } OPTIONAL,
  ...
}

GANSS-Additional-Ionospheric-Model-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

GANSS-Additional-Navigation-Models ::= SEQUENCE {
  non-broadcastIndication ENUMERATED { true }                               OPTIONAL,
  ganssSatInfoNavList     Ganss-Sat-Info-AddNavList,
  ie-Extensions           ProtocolExtensionContainer { { GANSS-Additional-Navigation-Models-ExtIEs } } OPTIONAL,
  ...
}

GANSS-Additional-Navigation-Models-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

GANSS-Additional-Time-Models ::= SEQUENCE (SIZE (1..maxGANSS-1)) OF GANSS-Time-Model

GANSS-Additional-UTC-Models ::= CHOICE {
  utcModel1            UTCmodelSet1,
  utcModel2            UTCmodelSet2,
  utcModel3            UTCmodelSet3,
  ...
}

GANSS-ALM-ECEFsbasAlmanacSet ::= SEQUENCE {
  sat-info-SBASecefList  GANSS-SAT-Info-Almanac-SBASecefList,
  ie-Extensions          ProtocolExtensionContainer { { GANSS-ALM-ECEFsbasAlmanacSet-ExtIEs } } OPTIONAL,
  ...
}

GANSS-ALM-ECEFsbasAlmanacSet-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

GANSS-ALM-GlonassAlmanacSet ::= SEQUENCE {
  sat-info-GLOkpList    GANSS-SAT-Info-Almanac-GLOkpList,
  ...
}

```

```

ie-Extensions          ProtocolExtensionContainer { { GANSS-ALM-GlonassAlmanacSet-ExtIEs } }           OPTIONAL,
...
}

GANSS-ALM-GlonassAlmanacSet-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
...
}

GANSS-ALM-MidiAlmanacSet ::= SEQUENCE {
  t-oa                  INTEGER (0..255),
  sat-info-MIDIkpList   GANSS-SAT-Info-Almanac-MIDIkpList,
  ie-Extensions          ProtocolExtensionContainer { { GANSS-ALM-MidiAlmanacSet-ExtIEs } }           OPTIONAL,
...
}

GANSS-ALM-MidiAlmanacSet-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
...
}

GANSS-ALM-NAVKeplerianSet ::= SEQUENCE {
  t-oa                  INTEGER (0..255),
  sat-info-NAVkpList    GANSS-SAT-Info-Almanac-NAVkpList,
  ie-Extensions          ProtocolExtensionContainer { { GANSS-ALM-NAVKeplerianSet-ExtIEs } }           OPTIONAL,
...
}

GANSS-ALM-NAVKeplerianSet-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
...
}

GANSS-ALM-ReducedKeplerianSet ::= SEQUENCE {
  t-oa                  INTEGER (0..255),
  sat-info-REDkpList    GANSS-SAT-Info-Almanac-REDkpList,
  ie-Extensions          ProtocolExtensionContainer { { GANSS-ALM-ReducedKeplerianSet-ExtIEs } }           OPTIONAL,
...
}

GANSS-ALM-ReducedKeplerianSet-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
...
}

GANSS-AlmanacAndSatelliteHealth ::= SEQUENCE {
  weekNumber            INTEGER(0..255),
  gANSS-AlmanacModel    GANSS-AlmanacModel,
}

```

```

ie-Extensions          ProtocolExtensionContainer { { GANSS-AlmanacAndSatelliteHealth-ExtIEs } }           OPTIONAL,
...
}

GANSS-AlmanacAndSatelliteHealth-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
...
}

GANSS-AlmanacModel ::= CHOICE {
  gANSS-keplerianParameters          GANSS-KeplerianParametersAlm,
  ...
  gANSS-alm-keplerianNAvalmanac     GANSS-ALM-NAVKeplerianSet,
  gANSS-alm-keplerianReducedAlmanac  GANSS-ALM-ReducedKeplerianSet,
  gANSS-alm-keplerianMidiAlmanac    GANSS-ALM-MidiAlmanacSet,
  gANSS-alm-keplerianGLONASS       GANSS-ALM-GlonassAlmanacSet,
  gANSS-alm-ecefSBASAlmanac        GANSS-ALM-ECEFsbasAlmanacSet
}

GANSS-Auxiliary-Information ::= CHOICE {
  ganssID1    AuxInfoGANSS-ID1,    -- This choice may only be present if GANSS ID indicates Modernized GPS
  ganssID3    AuxInfoGANSS-ID3,    -- This choice may only be present if GANSS ID indicates GLONASS
  ...
}

GANSS-AzimuthAndElevation ::= SEQUENCE {
  azimuth           INTEGER(0..31),
  elevation         INTEGER(0..75),
  ie-Extensions     ProtocolExtensionContainer { { GANSS-AzimuthAndElevation-ExtIEs } }           OPTIONAL,
  ...
}

GANSS-AzimuthAndElevation-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
...
}

GANSS-Clock-Model ::= SEQUENCE (SIZE (1..maxGANSSClockMod)) OF GANSS-SatelliteClockModelItem

GANSS-CommonAssistanceData ::= SEQUENCE {
  ganss-Reference-Time          GANSS-Reference-Time           OPTIONAL,
  ganss-Ionospheric-Model       GANSS-Ionospheric-Model        OPTIONAL,
  ganss-Reference-Location      GANSS-Reference-Location       OPTIONAL,
  ie-Extensions                 ProtocolExtensionContainer { { GANSS-CommonAssistanceData-ExtIEs } }           OPTIONAL,
  ...
}

GANSS-CommonAssistanceData-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  { ID id-GANSS-Additional-Ionospheric-Model   CRITICALITY ignore  EXTENSION GANSS-Additional-Ionospheric-Model   PRESENCE optional } |
  { ID id-GANSS-Earth-Orientation-Parameters   CRITICALITY ignore  EXTENSION GANSS-Earth-Orientation-Parameters PRESENCE optional },
  ...
}

```

```

}

GANSS-Data-Bit-Assistance ::= SEQUENCE {
  ganssTod                      INTEGER (0..59,...),
  dataBitAssistanceList          GANSS-DataBitAssistanceList,
  ie-Extensions                  ProtocolExtensionContainer { { GANSS-Data-Bit-Assistance-ExtIEs } } OPTIONAL,
  ...
}

GANSS-Data-Bit-Assistance-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

GANSS-DataBitAssistanceList ::= SEQUENCE (SIZE (1..maxGANSSSat)) OF GANSS-DataBitAssistanceItem

GANSS-DataBitAssistanceItem ::= SEQUENCE {
  satId                         INTEGER(0..63),
  dataBitAssistanceSgnList       GANSS-DataBitAssistanceSgnList,
  ie-Extensions                  ProtocolExtensionContainer { { GANSS-DataBitAssistanceItem-ExtIEs } } OPTIONAL,
  ...
}

GANSS-DataBitAssistanceItem-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

GANSS-DataBitAssistanceSgnList ::= SEQUENCE (SIZE (1..maxSgnType)) OF GANSS-DataBitAssistanceSgnItem

GANSS-DataBitAssistanceSgnItem ::= SEQUENCE {
  ganss-SignalId                GANSS-SignalID,
  ganssDataBits                 BIT STRING (SIZE (1..1024)),
  ie-Extensions                  ProtocolExtensionContainer { { GANSS-DataBitAssistanceSgnItem-ExtIEs } } OPTIONAL,
  ...
}

GANSS-DataBitAssistanceSgnItem-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

GANSS-Earth-Orientation-Parameters ::= SEQUENCE {
  teop                          BIT STRING (SIZE (16)),
  pmX                           BIT STRING (SIZE (21)),
  pmXdot                        BIT STRING (SIZE (15)),
  pmY                           BIT STRING (SIZE (21)),
  pmYdot                        BIT STRING (SIZE (15)),
  deltaUT1                      BIT STRING (SIZE (31)),
  deltaUT1dot                    BIT STRING (SIZE (19)),
  ie-Extensions                  ProtocolExtensionContainer { { GANSS-Earth-Orientation-Parameters-ExtIEs } } OPTIONAL,
  ...
}

```

```

GANSS-Earth-Orientation-Parameters-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

GANSS-ExtraDoppler ::= SEQUENCE {
  dopplerFirstOrder           INTEGER(-42..21),
  dopplerUncertainty          ENUMERATED{dH40,dH20,dH10,dH5,dH2-5},
  ie-Extensions                ProtocolExtensionContainer { { GANSS-ExtraDoppler-ExtIEs } }      OPTIONAL,
  ...
}

GANSS-ExtraDoppler-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

GANSS-GenericAssistanceDataList ::= SEQUENCE (SIZE (1..maxGANSS)) OF GANSSGenericAssistanceData

GANSSGenericAssistanceData ::= SEQUENCE{
  ganssId                      GANSSID                                OPTIONAL,
  ganss-Real-Time-Integrity     GANSS-Real-Time-Integrity          OPTIONAL,
  ganss-DataBitAssistance       GANSS-Data-Bit-Assistance          OPTIONAL,
  dganss-Corrections           DGANSS-Corrections           OPTIONAL,
  ganss-AlmanacAndSatelliteHealth GANSS-AlmanacAndSatelliteHealth OPTIONAL,
  ganss-ReferenceMeasurementInfo GANSS-ReferenceMeasurementInfo OPTIONAL,
  ganss-UTC-Model               GANSS-UTC-Model               OPTIONAL,
  ganss-Time-Model              GANSS-Time-Model              OPTIONAL,
  ganss-Navigation-Model       GANSS-Navigation-Model         OPTIONAL,
  ie-Extensions                ProtocolExtensionContainer { { GANSSGenericAssistance-ExtIEs } }      OPTIONAL,
  ...
}

GANSSGenericAssistance-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  { ID id-GANSS-Additional-Time-Models      CRITICALITY ignore  EXTENSION GANSS-Additional-Time-Models      PRESENCE optional } ||
  { ID id-GANSS-Additional-Navigation-Models CRITICALITY ignore  EXTENSION GANSS-Additional-Navigation-Models  PRESENCE optional } ||
  { ID id-GANSS-Additional-UTC-Models        CRITICALITY ignore  EXTENSION GANSS-Additional-UTC-Models        PRESENCE optional } ||
  { ID id-GANSS-Auxiliary-Information       CRITICALITY ignore  EXTENSION GANSS-Auxiliary-Information       PRESENCE optional } ||
  { ID id-GANSS-SBAS-ID                      CRITICALITY ignore  EXTENSION GANSS-SBAS-ID                      PRESENCE optional },
  ...
}

GANSS-GenericMeasurementInfo ::= SEQUENCE(SIZE(1..maxGANSS)) OF SEQUENCE {
  ganssId                      GANSSID                                OPTIONAL,
  ganssMeasurementSignalList    GANSSMeasurementSignalList,
  ie-Extensions                ProtocolExtensionContainer { { GANSS-GenericMeasurementInfo-ExtIEs } }      OPTIONAL,
  ...
}

GANSS-GenericMeasurementInfo-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {

```

```

}

GANSSID ::= SEQUENCE {
  ganss-ID          INTEGER(0..7),
  ie-Extensions     ProtocolExtensionContainer { { GANSSID-ExtIEs } } OPTIONAL,
  ...
}

GANSSID-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {

}

GANSSMeasurementSignalList ::= SEQUENCE (SIZE (1..maxSgnType)) OF SEQUENCE {
  ganssSignalId      GANSS-SignalID           OPTIONAL,
  ganssCodePhaseAmbiguity  INTEGER (0..31)        OPTIONAL,
  ganssMeasurementParameters  GANSS-MeasurementParameters,
  ie-Extensions       ProtocolExtensionContainer { { GANSSMeasurementSignalList-ExtIEs } } OPTIONAL,
  ...
}

GANSSMeasurementSignalList-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  {ID id-ganssCodePhaseAmbiguityExt  CRITICALITY ignore  EXTENSION  GanssCodePhaseAmbiguityExt PRESENCE      optional},
  ...
}

GanssCodePhaseAmbiguityExt ::= SEQUENCE {
  ganssCodePhaseAmbiguity-ext    INTEGER (32..127)           OPTIONAL,
  ie-Extensions                 ProtocolExtensionContainer { { GanssCodePhaseAmbiguityExt-ExtIEs } }           OPTIONAL,
  ...
}

GanssCodePhaseAmbiguityExt-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {

}

GANSS-Ionospheric-Model ::= SEQUENCE {
  alpha-zero-ionos      BIT STRING (SIZE (12)),
  alpha-one-ionos       BIT STRING (SIZE (12)),
  alpha-two-ionos       BIT STRING (SIZE (12)),
  gANSS-IonosphereRegionalStormFlags  GANSS-IonosphereRegionalStormFlags           OPTIONAL,
  ie-Extensions         ProtocolExtensionContainer { { GANSS-Ionospheric-Model-ExtIEs } }           OPTIONAL,
  ...
}

```

```

GANSS-Ionospheric-Model-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

GANSS-IonosphereRegionalStormFlags ::= SEQUENCE {
  storm-flag-one          BOOLEAN,
  storm-flag-two          BOOLEAN,
  storm-flag-three         BOOLEAN,
  storm-flag-four          BOOLEAN,
  storm-flag-five          BOOLEAN,
  ie-Extensions            ProtocolExtensionContainer { { GANSS-IonosphereRegionalStormFlags-ExtIEs } } OPTIONAL,
  ...
}

GANSS-IonosphereRegionalStormFlags-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

GANSS-KeplerianParametersAlm ::= SEQUENCE {
  t-oa                     INTEGER(0..255),
  iod-a                   INTEGER(0..3),
  gANSS-SatelliteInformationKP  GANSS-SatelliteInformationKP,
  ie-Extensions            ProtocolExtensionContainer { { GANSS-KeplerianParametersAlm-ExtIEs } } OPTIONAL,
  ...
}

GANSS-KeplerianParametersAlm-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

GANSS-KeplerianParametersOrb ::= SEQUENCE {
  toe-nav                  BIT STRING (SIZE (14)),
  ganss-omega-nav          BIT STRING (SIZE (32)),
  delta-n-nav               BIT STRING (SIZE (16)),
  m-zero-nav                BIT STRING (SIZE (32)),
  omegadot-nav              BIT STRING (SIZE (24)),
  ganss-e-nav               BIT STRING (SIZE (32)),
  idot-nav                 BIT STRING (SIZE (14)),
  a-sqrt-nav                BIT STRING (SIZE (32)),
  i-zero-nav                BIT STRING (SIZE (32)),
  omega-zero-nav            BIT STRING (SIZE (32)),
  c-rs-nav                 BIT STRING (SIZE (16)),
  c-is-nav                  BIT STRING (SIZE (16)),
  c-us-nav                  BIT STRING (SIZE (16)),
  c-rc-nav                  BIT STRING (SIZE (16)),
  c-ic-nav                  BIT STRING (SIZE (16)),
  c-uc-nav                  BIT STRING (SIZE (16)),
  ie-Extensions            ProtocolExtensionContainer { { GANSS-KeplerianParametersOrb-ExtIEs } } OPTIONAL,
  ...
}

```

```

}

GANSS-KeplerianParametersOrb-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

GANSS-MeasurementParameters ::= SEQUENCE (SIZE(1..maxGANSSSat)) OF GANSS-MeasurementParametersItem

GANSS-MeasurementParametersItem ::= SEQUENCE {
  satId                      INTEGER (0..63),
  cToNzero                    INTEGER (0..63),
  multipathIndicator          ENUMERATED{nm,low,medium,high},
  carrierQualityIndication   BIT STRING(SIZE(2))      OPTIONAL,
  ganssCodePhase               INTEGER (0..2097151),
  ganssIntegerCodePhase        INTEGER (0..63)        OPTIONAL,
  codePhaseRmsError           INTEGER (0..63),
  doppler                      INTEGER (-32768..32767),
  adr                          INTEGER (0..33554431)  OPTIONAL,
  ie-Extensions                ProtocolExtensionContainer { { GANSS-MeasurementParametersItem-ExtIEs } } OPTIONAL,
  ...
}

GANSS-MeasurementParametersItem-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  {ID id-ganssIntegerCodePhaseExt CRITICALITY ignore EXTENSION GanssIntegerCodePhaseExt PRESENCE optional},
  ...
}

GanssIntegerCodePhaseExt ::= SEQUENCE {
  ganssIntegerCodePhase-ext    INTEGER (64..127)           OPTIONAL,
  ie-Extensions                ProtocolExtensionContainer { { GanssIntegerCodePhaseExt-ExtIEs } }           OPTIONAL,
  ...
}

GanssIntegerCodePhaseExt-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

GANSS-MeasuredResultsList ::= SEQUENCE (SIZE (1..maxNrOfSets)) OF GANSS-MeasuredResults

GANSS-MeasuredResults ::= SEQUENCE {
  referenceTime    CHOICE {
    utranReferenceTime   UTRAN-GANSSReferenceTimeUL,
    ganssReferenceTimeOnly GANSS-ReferenceTimeOnly,
    ...
  },
  ganssGenericMeasurementInfo GANSS-GenericMeasurementInfo,
  ie-Extensions      ProtocolExtensionContainer { { GANSS-MeasuredResults-ExtIEs } } OPTIONAL,
  ...
}

```

```

GANSS-MeasuredResults-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

GANSS-Navigation-Model ::= SEQUENCE {
  non-broadcastIndication      ENUMERATED{true}           OPTIONAL,
  ganssSatInfoNav              GANSS-Sat-Info-Nav,
  ie-Extensions                 ProtocolExtensionContainer { { GANSS-Navigation-Model-ExtIEs } } OPTIONAL,
  ...
}

GANSS-Navigation-Model-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

GANSS-Orbit-Model ::= CHOICE {
  gANSS-keplerianParameters    GANSS-KeplerianParametersOrb,
  ...
}

GANSS-Real-Time-Integrity ::= SEQUENCE (SIZE (1..maxGANSSSat)) OF GANSS-RealTimeInformationItem

GANSS-RealTimeInformationItem ::= SEQUENCE {
  bad-ganss-satId              INTEGER(0..63),
  bad-ganss-signalId           BIT STRING(SIZE(8))           OPTIONAL,
  ie-Extensions                 ProtocolExtensionContainer { { GANSS-RealTimeInformationItem-ExtIEs } }   OPTIONAL,
  ...
}

GANSS-RealTimeInformationItem-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

GANSS-Reference-Location ::=      SEQUENCE {
  ue-PositionEstimate          UE-PositionEstimate,
  ie-Extensions                 ProtocolExtensionContainer { { GANSS-Reference-Location-ExtIEs } } OPTIONAL,
  ...
}

GANSS-Reference-Location-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

GANSS-ReferenceMeasurementInfo ::= SEQUENCE {
  ganssSignalId                GANSS-SignalID
  ...
  ...
}

```

```

satelliteInformation      GANSS-SatelliteInformation,
ie-Extensions            ProtocolExtensionContainer { { GANSS-ReferenceMeasurementInfo-ExtIEs } }           OPTIONAL,
...
}

GANSS-ReferenceMeasurementInfo-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
...
}

GANSS-Reference-Time ::= SEQUENCE {
  ganssDay                INTEGER(0..8191)           OPTIONAL,
  ganssTod                INTEGER(0..86399),
  ganssTodUncertainty     INTEGER(0..127)           OPTIONAL,
  ganssTimeId              GANSSID                 OPTIONAL,
  utran-ganssreferenceTime UTRAN-GANSSReferenceTimeDL OPTIONAL,
  tutran-ganss-driftRate   TUTRAN-GANSS-DriftRate    OPTIONAL,
  ie-Extensions            ProtocolExtensionContainer { { GANSS-Reference-Time-ExtIEs } }   OPTIONAL,
...
}

GANSS-Reference-Time-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
...
}

GANSS-ReferenceTimeOnly ::= SEQUENCE {
  gANSS-tod                INTEGER(0..3599999),
  gANSS-timeId              GANSSID                 OPTIONAL,
  gANSS-TimeUncertainty     INTEGER(0..127)           OPTIONAL,
  ie-Extensions            ProtocolExtensionContainer { { GANSS-ReferenceTimeOnly-ExtIEs } }   OPTIONAL,
...
}

GANSS-ReferenceTimeOnly-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
...
}

GANSS-SatelliteClockModelItem ::= SEQUENCE {
  t-oc                     BIT STRING (SIZE(14)),
  a-i2                     BIT STRING (SIZE(12)),
  a-i1                     BIT STRING (SIZE(18)),
  a-i0                     BIT STRING (SIZE(28)),
  t-gd                     BIT STRING (SIZE(10))           OPTIONAL,
  model-id                INTEGER(0..3)           OPTIONAL,
  ie-Extensions            ProtocolExtensionContainer { { GANSS-SatelliteClockModelItem-ExtIEs } }   OPTIONAL,
...
}

GANSS-SatelliteClockModelItem-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
...
}

```

```

...
}

GANSS-SatelliteInformation ::= SEQUENCE (SIZE(1..maxGANSSSat)) OF GANSS-SatelliteInformationItem

GANSS-SatelliteInformationItem ::= SEQUENCE {
  ganssSatId           INTEGER(0..63),
  dopplerZeroOrder     INTEGER(-2048..2047),
  extraDoppler         GANSS-ExtraDoppler           OPTIONAL,
  codePhase             INTEGER(0..1023),
  integerCodePhase     INTEGER(0..127),
  codePhaseSearchWindow INTEGER(0..31),
  azimuthAndElevation  GANSS-AzimuthAndElevation    OPTIONAL,
  ie-Extensions         ProtocolExtensionContainer { { GANSS-SatelliteInformationItem-ExtIEs } }           OPTIONAL,
  ...
}

GANSS-SatelliteInformationItem-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

GANSS-SatelliteInformationKP ::= SEQUENCE (SIZE (1..maxGANSSSatAlmanac)) OF GANSS-SatelliteInformationKPIItem

GANSS-SatelliteInformationKPIItem ::= SEQUENCE {
  satId                INTEGER(0..63),
  ganss-e-alm          BIT STRING (SIZE (11)),
  ganss-delta-I-alm    BIT STRING (SIZE (11)),
  ganss-omegadot-alm   BIT STRING (SIZE (11)),
  ganss-svhealth-alm   BIT STRING (SIZE (4)),
  ganss-delta-a-sqrt-alm BIT STRING (SIZE (17)),
  ganss-omegazero-alm  BIT STRING (SIZE (16)),
  ganss-m-zero-alm     BIT STRING (SIZE (16)),
  ganss-omega-alm      BIT STRING (SIZE (16)),
  ganss-af-zero-alm    BIT STRING (SIZE (14)),
  ganss-af-one-alm     BIT STRING (SIZE (11)),
  ie-Extensions         ProtocolExtensionContainer { { GANSS-SatelliteInformationKPIItem-ExtIEs } }           OPTIONAL,
  ...
}

GANSS-SatelliteInformationKPIItem-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

GANSS-SAT-Info-Almanac-GLOkpList ::= SEQUENCE (SIZE (1.. maxGANSSSatAlmanac)) OF GANSS-SAT-Info-Almanac-GLOkp

GANSS-SAT-Info-Almanac-GLOkp ::= SEQUENCE {
  gloAlmNA              BIT STRING (SIZE(11)),
  gloAlmna              BIT STRING (SIZE(5)),
  gloAlmHA              BIT STRING (SIZE(5)),

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```

gloAlmLambdaA          BIT STRING (SIZE(21)),
gloAlmTlambdaA         BIT STRING (SIZE(21)),
gloAlmDeltaIA          BIT STRING (SIZE(18)),
gloAkmDeltaTA          BIT STRING (SIZE(22)),
gloAlmDeltaTdotA       BIT STRING (SIZE(7)),
gloAlmEpsilonA          BIT STRING (SIZE(15)),
gloAlmOmegaA           BIT STRING (SIZE(16)),
gloAlmTauA             BIT STRING (SIZE(10)),
gloAlmCA               BIT STRING (SIZE(1)),
gloAlmMA               BIT STRING (SIZE(2))                                         OPTIONAL,
ie-Extensions          ProtocolExtensionContainer { { GANSS-SAT-Info-Almanac-GLOkp-ExtIEs } }          OPTIONAL,
...
}

GANSS-SAT-Info-Almanac-GLOkp-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

GANSS-SAT-Info-Almanac-MIDIkpList ::= SEQUENCE (SIZE (1.. maxGANSSsatAlmanac)) OF GANSS-SAT-Info-Almanac-MIDIkp

GANSS-SAT-Info-Almanac-MIDIkp ::= SEQUENCE {
  svID                  INTEGER(0..63),
  midiAlmE              BIT STRING (SIZE (11)),
  midiAlmDeltaI          BIT STRING (SIZE (11)),
  midiAlmOmegaDot        BIT STRING (SIZE (11)),
  midiAlmSqrtA           BIT STRING (SIZE (17)),
  midiAlmOmega0           BIT STRING (SIZE (16)),
  midiAlmOmega            BIT STRING (SIZE (16)),
  midiAlmMo              BIT STRING (SIZE (16)),
  midiAlmaf0             BIT STRING (SIZE (11)),
  midiAlmaf1             BIT STRING (SIZE (10)),
  midiAlmL1Health         BIT STRING (SIZE (1)),
  midiAlmL2Health         BIT STRING (SIZE (1)),
  midiAlmL5Health         BIT STRING (SIZE (1)),
  ie-Extensions          ProtocolExtensionContainer { { GANSS-SAT-Info-Almanac-MIDIkp-ExtIEs } }          OPTIONAL,
  ...
}

GANSS-SAT-Info-Almanac-MIDIkp-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

GANSS-SAT-Info-Almanac-NAVkpList ::= SEQUENCE (SIZE (1.. maxGANSSsatAlmanac)) OF GANSS-SAT-Info-Almanac-NAVkp

GANSS-SAT-Info-Almanac-NAVkp ::= SEQUENCE {
  svID                  INTEGER(0..63),
  navAlmE               BIT STRING (SIZE (16)),
  navAlmDeltaI           BIT STRING (SIZE (16)),
  navAlmOMEGADOT         BIT STRING (SIZE (16)),
  navAlmSVHealth         BIT STRING (SIZE (8)),

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```

navAlmSqrtA          BIT STRING (SIZE (24)),
navAlmOMEGAo         BIT STRING (SIZE (24)),
navAlmOmega          BIT STRING (SIZE (24)),
navAlmMo             BIT STRING (SIZE (24)),
navAlmaf0            BIT STRING (SIZE (11)),
navAlmaf1            BIT STRING (SIZE (11)),
ie-Extensions        ProtocolExtensionContainer { { GANSS-SAT-Info-Almanac-NAVkp-ExtIEs } }           OPTIONAL,
...
}

GANSS-SAT-Info-Almanac-NAVkp-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
...
}

GANSS-SAT-Info-Almanac-REDkpList ::= SEQUENCE (SIZE (1.. maxGANSSSatAlmanac)) OF GANSS-SAT-Info-Almanac-REDkp

GANSS-SAT-Info-Almanac-REDkp ::= SEQUENCE {
  svID                INTEGER(0..63),
  redAlmDeltaA         BIT STRING (SIZE (8)),
  redAlmOmega0         BIT STRING (SIZE (7)),
  redAlmPhi0           BIT STRING (SIZE (7)),
  redAlmL1Health       BIT STRING (SIZE (1)),
  redAlmL2Health       BIT STRING (SIZE (1)),
  redAlmL5Health       BIT STRING (SIZE (1)),
  ie-Extensions        ProtocolExtensionContainer { { GANSS-SAT-Info-Almanac-REDkp-ExtIEs } }           OPTIONAL,
...
}

GANSS-SAT-Info-Almanac-REDkp-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
...
}

GANSS-SAT-Info-Almanac-SBAScefList ::= SEQUENCE (SIZE (1.. maxGANSSSatAlmanac)) OF GANSS-SAT-Info-Almanac-SBAScef

GANSS-SAT-Info-Almanac-SBAScef ::= SEQUENCE {
  sbasAlmDataID        BIT STRING (SIZE(2)),
  svID                 INTEGER(0..63),
  sbasAlmHealth         BIT STRING (SIZE(8)),
  sbasAlmXg             BIT STRING (SIZE(15)),
  sbasAlmYg             BIT STRING (SIZE(15)),
  sbasAlmZg             BIT STRING (SIZE(9)),
  sbasAlmXgdot          BIT STRING (SIZE(3)),
  sbasAlmYgDot          BIT STRING (SIZE(3)),
  sbasAlmZgDot          BIT STRING (SIZE(4)),
  sbasAlmTo             BIT STRING (SIZE(11)),
  ie-Extensions        ProtocolExtensionContainer { { GANSS-SAT-Info-Almanac-SBAScef-ExtIEs } }           OPTIONAL,
...
}

GANSS-SAT-Info-Almanac-SBAScef-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
}

```

```

...
}

Ganss-Sat-Info-AddNavList ::= SEQUENCE (SIZE (1..maxGANSSSat)) OF SEQUENCE {
    satId                  INTEGER (0..63),
    svHealth                BIT STRING (SIZE (6)),
    iod                     BIT STRING (SIZE (11)),
    ganssAddClockModels    GANSS-AddClockModels,
    ganssAddOrbitModels    GANSS-AddOrbitModels,
    ie-Extensions           ProtocolExtensionContainer { { Ganss-Sat-Info-AddNavList-ExtIEs } } OPTIONAL,
    ...
}

Ganss-Sat-Info-AddNavList-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {

}

GANSS-Sat-Info-Nav ::= SEQUENCE (SIZE(1..maxGANSSSat)) OF SEQUENCE {
    satId                  INTEGER(0..63),
    svHealth                BIT STRING (SIZE(5)),
    iod                     BIT STRING (SIZE(10)),
    ganssClockModel        GANSS-Clock-Model,
    ganssOrbitModel        GANSS-Orbit-Model,
    ie-Extensions           ProtocolExtensionContainer { { GANSS-Sat-Info-Nav-ExtIEs } } OPTIONAL,
    ...
}

GANSS-Sat-Info-Nav-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {

}

GANSS-SignalID ::= SEQUENCE {
    ganssSignalID          INTEGER(0..3,...,4..7),
    ie-Extensions           ProtocolExtensionContainer { { GANSS-SignalID-ExtIEs } } OPTIONAL,
    ...
}

GANSS-SignalID-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {

}

GANSS-StatusHealth ::= ENUMERATED {
    udre-scale-1dot0,
    udre-scale-0dot75,
    udre-scale-0dot5,
    udre-scale-0dot3,
    udre-scale-0dot2,
    udre-scale-0dot1,
    no-data,
}

```

```

    invalid-data
}

GANSS-Time-Model ::= SEQUENCE {
    ganss-time-model-refTime           INTEGER(0..37799),
    ganss-t-a0                         INTEGER(-2147483648..2147483647),
    ganss-t-a1                         INTEGER(-8388608..8388607)                               OPTIONAL,
    ganss-t-a2                         INTEGER(-64..63)                               OPTIONAL,
    gnss-to-id                          ENUMERATED{gps,...,galileo,qzss,glonass},
    ganss-wk-number                     INTEGER(0..8191)                               OPTIONAL,
    ie-Extensions                      ProtocolExtensionContainer { { GANSS-Time-Model-ExtIEs } }  OPTIONAL,
    ...
}

GANSS-Time-Model-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
    ...
}

GANSS-UTRAN-TimeRelationshipUncertainty ::= ENUMERATED {
    gANSS-UTRAN-TRU-50nano,
    gANSS-UTRAN-TRU-500nano,
    gANSS-UTRAN-TRU-1micro,
    gANSS-UTRAN-TRU-10micro,
    gANSS-UTRAN-TRU-1milli,
    gANSS-UTRAN-TRU-10milli,
    gANSS-UTRAN-TRU-100milli,
    gANSS-UTRAN-TRU-unreliable,
    ...
}

GANSS-UTRAN-TRU ::= SEQUENCE {
    gANSS-UTRAN-TimeRelationshipUncertainty,
    ganssId                           GANSSID                                         OPTIONAL,
    ie-Extensions                      ProtocolExtensionContainer { { GANSS-UTRAN-TRU-ExtIEs } }  OPTIONAL,
    ...
}

GANSS-UTRAN-TRU-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
    ...
}

GANSS-UTC-Model ::= SEQUENCE {
    a-one-utc                          BIT STRING (SIZE (24)),
    a-zero-utc                         BIT STRING (SIZE (32)),
    t-ot-utc                           BIT STRING (SIZE (8)),
    w-n-t-utc                          BIT STRING (SIZE (8)),

```

```

delta-t-ls-utc          BIT STRING (SIZE (8)),
w-n-lsf-utc            BIT STRING (SIZE (8)),
dn-utc                 BIT STRING (SIZE (8)),
delta-t-lsf-utc        BIT STRING (SIZE (8)),
ie-Extensions          ProtocolExtensionContainer { { GANSS-UTC-Model-ExtIEs } }
                        OPTIONAL,
...
}

GANSS-UTC-Model-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

TUTRAN-GANSS-DriftRate ::= ENUMERATED {
  uTRAN-GANSSDrift0,      uTRAN-GANSSDrift1,      uTRAN-GANSSDrift2,
  uTRAN-GANSSDrift5,      uTRAN-GANSSDrift10,     uTRAN-GANSSDrift15,
  uTRAN-GANSSDrift25,     uTRAN-GANSSDrift50,     uTRAN-GANSSDrift-1,
  uTRAN-GANSSDrift-2,     uTRAN-GANSSDrift-5,     uTRAN-GANSSDrift-10,
  uTRAN-GANSSDrift-15,    uTRAN-GANSSDrift-25,    uTRAN-GANSSDrift-50,
...
}

GLONASSclockModel ::= SEQUENCE {
  gloTau                 BIT STRING (SIZE (22)),
  gloGamma               BIT STRING (SIZE (11)),
  gloDeltaTau             BIT STRING (SIZE (5))           OPTIONAL,
  ie-Extensions          ProtocolExtensionContainer { { GLONASSclockModel-ExtIEs } } OPTIONAL,
  ...
}

GLONASSclockModel-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

NAVclockModel ::= SEQUENCE {
  navToc                 BIT STRING (SIZE (16)),
  navaf2                 BIT STRING (SIZE (8)),
  navaf1                 BIT STRING (SIZE (16)),
  navaf0                 BIT STRING (SIZE (22)),
  navTgd                 BIT STRING (SIZE (8)),
  ie-Extensions          ProtocolExtensionContainer { { NAVclockModel-ExtIEs } } OPTIONAL,
  ...
}

NAVclockModel-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

NavModel-CNAVKeplerianSet ::= SEQUENCE {
  cnavTop                BIT STRING (SIZE (11)),
  cnavURAindex           BIT STRING (SIZE (5)),

```

```

cnavDeltaA          BIT STRING (SIZE (26)),
cnavAdot          BIT STRING (SIZE (25)),
cnavDeltaNo        BIT STRING (SIZE (17)),
cnavDeltaNoDot    BIT STRING (SIZE (23)),
cnavMo            BIT STRING (SIZE (33)),
cnavE             BIT STRING (SIZE (33)),
cnavOmega         BIT STRING (SIZE (33)),
cnavOMEGA0        BIT STRING (SIZE (33)),
cnavDeltaOmegaDot BIT STRING (SIZE (17)),
cnavIo            BIT STRING (SIZE (33)),
cnavIoDot        BIT STRING (SIZE (15)),
cnavCis           BIT STRING (SIZE (16)),
cnavCic           BIT STRING (SIZE (16)),
cnavCrs           BIT STRING (SIZE (24)),
cnavCrc           BIT STRING (SIZE (24)),
cnavCus           BIT STRING (SIZE (21)),
cnavCuc           BIT STRING (SIZE (21)),
ie-Extensions     ProtocolExtensionContainer { { NavModel-CNAVKeplerianSet-ExtIEs } } OPTIONAL,
...
}

NavModel-CNAVKeplerianSet-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

NavModel-GLONASSceef ::= SEQUENCE {
  gloEn            BIT STRING (SIZE (5)),
  gloP1            BIT STRING (SIZE(2)),
  gloP2            BIT STRING (SIZE (1)),
  gloM             BIT STRING (SIZE (2))                                     OPTIONAL,
  gloX             BIT STRING (SIZE (27)),
  gloXdot          BIT STRING (SIZE (24)),
  gloXdotdot      BIT STRING (SIZE (5)),
  gloY             BIT STRING (SIZE (27)),
  gloYdot          BIT STRING (SIZE (24)),
  gloYdotdot      BIT STRING (SIZE (5)),
  gloZ             BIT STRING (SIZE (27)),
  gloZdot          BIT STRING (SIZE (24)),
  gloZdotdot      BIT STRING (SIZE (5)),
  ie-Extensions     ProtocolExtensionContainer { { NavModel-GLONASSceef-ExtIEs } } OPTIONAL,
  ...
}

NavModel-GLONASSceef-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

NavModel-NAVKeplerianSet ::= SEQUENCE {
  navURA          BIT STRING (SIZE (4)),
  navFitFlag      BIT STRING (SIZE (1)),
  navToe          BIT STRING (SIZE (16)),
  navOmega        BIT STRING (SIZE (32)),
  navDeltaN        BIT STRING (SIZE (16)),

```

```

navM0           BIT STRING (SIZE (32)),
navOmegaADot   BIT STRING (SIZE (24)),
navE            BIT STRING (SIZE (32)),
navIDot         BIT STRING (SIZE (14)),
navAPowerHalf  BIT STRING (SIZE (32)),
navI0           BIT STRING (SIZE (32)),
navOmegaA0     BIT STRING (SIZE (32)),
navCrs          BIT STRING (SIZE (16)),
navCis          BIT STRING (SIZE (16)),
navCus          BIT STRING (SIZE (16)),
navCrc          BIT STRING (SIZE (16)),
navCic          BIT STRING (SIZE (16)),
navCuc          BIT STRING (SIZE (16)),
ie-Extensions   ProtocolExtensionContainer { { NavModel-NAVKeplerianSet-ExtIEs } } OPTIONAL,
...
}

NavModel-NAVKeplerianSet-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

NavModel-SBASceef ::= SEQUENCE {
  sbasTo          BIT STRING (SIZE (13))                               OPTIONAL,
  sbasAccuracy   BIT STRING (SIZE (4)),
  sbasXg          BIT STRING (SIZE (30)),
  sbasYg          BIT STRING (SIZE (30)),
  sbasZg          BIT STRING (SIZE (25)),
  sbasXgDot       BIT STRING (SIZE (17)),
  sbasYgDot       BIT STRING (SIZE (17)),
  sbasZgDot       BIT STRING (SIZE (18)),
  sbasXgDotDot   BIT STRING (SIZE (10)),
  sbagYgDotDot   BIT STRING (SIZE (10)),
  sbasZgDotDot   BIT STRING (SIZE (10)),
  ie-Extensions   ProtocolExtensionContainer { { NavModel-SBASceef-ExtIEs } } OPTIONAL,
  ...
}

NavModel-SBASceef-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

SBASclockModel ::= SEQUENCE {
  sbasTo          BIT STRING (SIZE (13)),
  sbasAgfo        BIT STRING (SIZE (12)),
  sbasAgf1        BIT STRING (SIZE (8)),
  ie-Extensions   ProtocolExtensionContainer { { SBASclockModel-ExtIEs } } OPTIONAL,
  ...
}

SBASclockModel-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

```

```

UTCmodelSet1 ::= SEQUENCE {
  utcA0          BIT STRING (SIZE(16)),
  utcA1          BIT STRING (SIZE(13)),
  utcA2          BIT STRING (SIZE(7)),
  utcDeltaTls    BIT STRING (SIZE(8)),
  utcTot         BIT STRING (SIZE(16)),
  utcWNot        BIT STRING (SIZE(13)),
  utcWNlsf       BIT STRING (SIZE(8)),
  utcDN          BIT STRING (SIZE(4)),
  utcDeltaTlsf   BIT STRING (SIZE(8)),
  ie-Extensions  ProtocolExtensionContainer { { UTCmodelSet1-ExtIEs } } OPTIONAL,
  ...
}

UTCmodelSet1-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

UTCmodelSet2 ::= SEQUENCE {
  nA             BIT STRING (SIZE(11)),
  tauC           BIT STRING (SIZE(32)),
  deltaUT1       DeltaUT1                               OPTIONAL,
  kp              BIT STRING (SIZE(2))                 OPTIONAL,
  ie-Extensions  ProtocolExtensionContainer { { UTCmodelSet2-ExtIEs } } OPTIONAL,
  ...
}

UTCmodelSet2-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

UTCmodelSet3 ::= SEQUENCE {
  utcA1wnt       BIT STRING (SIZE(24)),
  utcA0wnt       BIT STRING (SIZE(32)),
  utcTot         BIT STRING (SIZE(8)),
  utcWNt         BIT STRING (SIZE(8)),
  utcDeltaTls    BIT STRING (SIZE(8)),
  utcWNlsf       BIT STRING (SIZE(8)),
  utcDN          BIT STRING (SIZE(8)),
  utcDeltaTlsf   BIT STRING (SIZE(8)),
  utcStandardID  BIT STRING (SIZE(3)),
  ie-Extensions  ProtocolExtensionContainer { { UTCmodelSet3-ExtIEs } } OPTIONAL,
  ...
}

UTCmodelSet3-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

UTRAN-GANSSReferenceTimeDL ::= SEQUENCE {
  utran-GANSSTimingOfCellFrames  INTEGER(0..3999999),
  ...
}

```

```

uC-ID           UC-ID           OPTIONAL,
referenceSfn   INTEGER(0..4095),
ie-Extensions  ProtocolExtensionContainer { { UTRAN-GANSSReferenceTimeDL-ExtIEs } }   OPTIONAL,
...
}

UTRAN-GANSSReferenceTimeDL-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
...
}

UTRAN-GANSSReferenceTimeUL ::= SEQUENCE {
  ue-GANSSTimingOfCellFrames  INTEGER(0..345599999999),
  gANSS-TimeId                GANSSID           OPTIONAL,
  gANSS-TimeUncertainty       INTEGER(0..127)      OPTIONAL,
  uC-ID                       UC-ID           OPTIONAL,
  referenceSfn                INTEGER(0..4095),
  ie-Extensions               ProtocolExtensionContainer { { UTRAN-GANSSReferenceTimeUL-ExtIEs } }   OPTIONAL,
...
}

UTRAN-GANSSReferenceTimeUL-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
...
}

-- ****
-- 
-- GPS Almanac and Satellite Health
-- 
-- ****

GPS-AlmanacAndSatelliteHealth ::= SEQUENCE {
  wn-a           BIT STRING (SIZE (8)),
  almanacSatInfoList  AlmanacSatInfoList,
  svGlobalHealth  BIT STRING (SIZE (364)) OPTIONAL,
  iE-Extensions   ProtocolExtensionContainer { { GPS-AlmanacAndSatelliteHealth-ExtIEs } }   OPTIONAL,
...
}

GPS-AlmanacAndSatelliteHealth-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
...
}

AlmanacSatInfoList ::= SEQUENCE (SIZE (1..maxSatAlmanac)) OF
  AlmanacSatInfo

AlmanacSatInfo ::= SEQUENCE {
  dataID        BIT STRING (SIZE (2)),
  satID         INTEGER (0..63),
  e             BIT STRING (SIZE (16)),
...
}

```

```

t-oa                                BIT STRING (SIZE (8)),
deltaI                               BIT STRING (SIZE (16)),
omegaDot                            BIT STRING (SIZE (16)),
satHealth                            BIT STRING (SIZE (8)),
a-Sqrt                               BIT STRING (SIZE (24)),
omega0                               BIT STRING (SIZE (24)),
m0                                    BIT STRING (SIZE (24)),
omega                                BIT STRING (SIZE (24)),
af0                                    BIT STRING (SIZE (11)),
af1                                    BIT STRING (SIZE (11)),
iE-Extensions                         ProtocolExtensionContainer { { AlmanacSatInfo-ExtIEs } } OPTIONAL,
...
}

AlmanacSatInfo-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
...
}

-- ****
-- 
-- GPS Clock And Ephemeris Parameters
-- 
-- ****

GPS-ClockAndEphemerisParameters ::= SEQUENCE {
  codeOnL2                           BIT STRING (SIZE (2)),
  uraIndex                            BIT STRING (SIZE (4)),
  satHealth                            BIT STRING (SIZE (6)),
  iodc                                 BIT STRING (SIZE (10)),
  l2Pflag                             BIT STRING (SIZE (1)),
  sf1Revd                            SubFrame1Reserved,
  t-GD                                 BIT STRING (SIZE (8)),
  t-oc                                 BIT STRING (SIZE (16)),
  af2                                 BIT STRING (SIZE (8)),
  af1                                 BIT STRING (SIZE (16)),
  af0                                 BIT STRING (SIZE (22)),
  c-rs                                BIT STRING (SIZE (16)),
  delta-n                            BIT STRING (SIZE (16)),
  m0                                    BIT STRING (SIZE (32)),
  c-uc                                BIT STRING (SIZE (16)),
  e                                     BIT STRING (SIZE (32)),
  c-us                                BIT STRING (SIZE (16)),
  a-Sqrt                               BIT STRING (SIZE (32)),
  t-oe                                 BIT STRING (SIZE (16)),
  fitInterval                          BIT STRING (SIZE (1)),
  aodo                                BIT STRING (SIZE (5)),
  c-ic                                BIT STRING (SIZE (16)),
  omega0                               BIT STRING (SIZE (32)),
  c-is                                BIT STRING (SIZE (16)),
  i0                                    BIT STRING (SIZE (32)),
  c-rc                                BIT STRING (SIZE (16)),
  omega                               BIT STRING (SIZE (32)),
  omegaDot                            BIT STRING (SIZE (24)),
}

```

```

iDot                                BIT STRING (SIZE (14)),
iE-Extensions                         ProtocolExtensionContainer { { GPS-ClockAndEphemerisParameters-ExtIEs } }      OPTIONAL,
...
}

GPS-ClockAndEphemerisParameters-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
...
}

SubFrame1Reserved ::=          SEQUENCE {
  reserved1                         BIT STRING (SIZE (23)),
  reserved2                         BIT STRING (SIZE (24)),
  reserved3                         BIT STRING (SIZE (24)),
  reserved4                         BIT STRING (SIZE (16))
}

-- ****
-- 
-- GPS Ionospheric Model
-- 
-- ****

GPS-Ionospheric-Model ::=          SEQUENCE {
  alfa0                            BIT STRING (SIZE (8)),
  alfa1                            BIT STRING (SIZE (8)),
  alfa2                            BIT STRING (SIZE (8)),
  alfa3                            BIT STRING (SIZE (8)),
  beta0                            BIT STRING (SIZE (8)),
  beta1                            BIT STRING (SIZE (8)),
  beta2                            BIT STRING (SIZE (8)),
  beta3                            BIT STRING (SIZE (8)),
  iE-Extensions                    ProtocolExtensionContainer { { GPS-Ionospheric-Model-ExtIEs } }      OPTIONAL,
...
}

GPS-Ionospheric-Model-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
...
}

-- ****
-- 
-- GPS Measured Results
-- 
-- ****

MeasuredResultsList ::=          SEQUENCE (SIZE (1..maxNrOfSets)) OF
  GPS-MeasuredResults

GPS-MeasuredResults ::=          SEQUENCE {
  gps-TOW-1msec                    INTEGER (0..604799999),
...
}

```

```

gps-MeasurementParamList          GPS-MeasurementParamList,
iE-Extensions                     ProtocolExtensionContainer { { GPS-MeasuredResults-ExtIEs } } OPTIONAL,
...
}

GPS-MeasuredResults-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  { ID id-UTRAN-GPSReferenceTimeResult CRITICALITY ignore EXTENSION UTRAN-GPSReferenceTimeResult PRESENCE optional} |
  { ID id-GPSReferenceTimeUncertainty CRITICALITY ignore EXTENSION GPSReferenceTimeUncertainty PRESENCE optional},
...
}

GPS-MeasurementParamList ::=      SEQUENCE (SIZE (1..maxSat)) OF
                                  GPS-MeasurementParam

GPS-MeasurementParam ::=          SEQUENCE {
  satelliteID                   INTEGER (0..63),
  c-N0                          INTEGER (0..63),
  doppler                        INTEGER (-32768..32768),
  wholeGPS-Chips                INTEGER (0..1022),
  fractionalGPS-Chips           INTEGER (0..1023),
  multipathIndicator            MultipathIndicator,
  pseudorangeRMS-Error          INTEGER (0..63),
  iE-Extensions                  ProtocolExtensionContainer { { GPS-MeasurementParam-ExtIEs } } OPTIONAL,
...
}

MultipathIndicator ::=           ENUMERATED {
  nm,
  low,
  medium,
  high
}

GPS-MeasurementParam-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
...
}

-- ****
-- 
-- GPS Navigation Model
-- 
-- ****

GPS-NavigationModel ::=          SEQUENCE (SIZE (1..maxSat)) OF
                                  NavigationModelSatInfo

NavigationModelSatInfo ::=        SEQUENCE {
  satID                         INTEGER (0..63),
  satelliteStatus                SatelliteStatus,
  gps-clockAndEphemerisParms    GPS-ClockAndEphemerisParameters
  -- This IE is not present if satelliteStatus is es-SN
  ...
  OPTIONAL,
}

```

```

iE-Extensions                               ProtocolExtensionContainer { { NavigationModelSatInfo-ExtIEs } } OPTIONAL,
...
}

NavigationModelSatInfo-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
...
}

SatelliteStatus ::= ENUMERATED {
    ns-NN,
    es-SN,
    es-NN,
    rev2,
    rev
}

-- ****
-- GPS Real Time Integrity
-- ****

GPS-RealTimeIntegrity ::= CHOICE {
    badSatellites      BadSatList,
    noBadSatellites   NoBadSatellites,
...
}

BadSatList ::= SEQUENCE (SIZE (1..maxSat)) OF
    INTEGER (0..63)

NoBadSatellites ::= NULL

-- ****
-- GPS Reference Location
-- ****

GPS-ReferenceLocation ::= SEQUENCE {
    ue-PositionEstimate,
    iE-Extensions
    ProtocolExtensionContainer { { GPS-ReferenceLocation-ExtIEs } } OPTIONAL,
...
}

GPS-ReferenceLocation-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
...
}

-- ****
-- GPS Reference Time

```

```

-- ****
-- ****
GPS-ReferenceTime ::= SEQUENCE {
  gps-Week           INTEGER (0..1023),
  gps-TOW-1msec     INTEGER (0..604799999),
  gps-TOW-AssistList GPS-TOW-AssistList                                OPTIONAL,
  iE-Extensions      ProtocolExtensionContainer { { GPS-ReferenceTime-ExtIEs } } OPTIONAL,
  ...
}

GPS-ReferenceTime-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  { ID id-UTRAN-GPSReferenceTime   CRITICALITY ignore  EXTENSION  UTRAN-GPSReferenceTime      PRESENCE optional } |
  { ID id-GPS-UTRAN-TRU           CRITICALITY ignore  EXTENSION  GPS-UTRAN-TRU                  PRESENCE optional } |
  { ID id-UTRAN-GPS-DriftRate    CRITICALITY ignore  EXTENSION  UTRAN-GPS-DriftRate        PRESENCE optional } |
  { ID id-GPSReferenceTimeUncertainty CRITICALITY ignore  EXTENSION  GPSReferenceTimeUncertainty PRESENCE optional },
  ...
}

GPS-TOW-AssistList ::= SEQUENCE (SIZE (1..maxSat)) OF
  GPS-TOW-Assist

GPS-TOW-Assist ::= SEQUENCE {
  satID           INTEGER (0..63),
  tlm-Message     BIT STRING (SIZE (14)),
  antiSpoof       BOOLEAN,
  alert           BOOLEAN,
  tlm-Reserved    BIT STRING (SIZE (2)),
  iE-Extensions   ProtocolExtensionContainer { { GPS-TOW-Assist-ExtIEs } } OPTIONAL,
  ...
}

GPS-TOW-Assist-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

UTRAN-GPS-DriftRate ::= ENUMERATED {
  utran-GPSDrift0, utran-GPSDrift1, utran-GPSDrift2,
  utran-GPSDrift5, utran-GPSDrift10, utran-GPSDrift15,
  utran-GPSDrift25, utran-GPSDrift50, utran-GPSDrift-1,
  utran-GPSDrift-2, utran-GPSDrift-5, utran-GPSDrift-10,
  utran-GPSDrift-15, utran-GPSDrift-25, utran-GPSDrift-50,
  ...
}

-- ****
-- GPS Reference Time Uncertainty
-- ****
GPSReferenceTimeUncertainty ::= SEQUENCE {

```

```

gps-RefTimeUNC      INTEGER(0..127),
iE-Extensions      ProtocolExtensionContainer { { GPSReferenceTimeUncertainty-ExtIEs } }  OPTIONAL,
...
}

GPSReferenceTimeUncertainty-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

-- ****
-- 
-- GPS Transmission TOW
-- 
-- ****

GPS-Transmission-TOW ::= INTEGER (0..604799)

-- ****
-- 
-- GPS UTC Model
-- 
-- ****

GPS-UTC-Model ::=          SEQUENCE {
  a1                  BIT STRING (SIZE (24)),
  a0                  BIT STRING (SIZE (32)),
  t-ot                BIT STRING (SIZE (8)),
  delta-t-LS          BIT STRING (SIZE (8)),
  wn-t                BIT STRING (SIZE (8)),
  wn-lsf              BIT STRING (SIZE (8)),
  dn                  BIT STRING (SIZE (8)),
  delta-t-LSF         BIT STRING (SIZE (8)),
  iE-Extensions      ProtocolExtensionContainer { { GPS-UTCmodel-ExtIEs } }  OPTIONAL,
  ...
}

GPS-UTCmodel-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

-- ****
-- 
-- GPS UTRAN Time Relationship Uncertainty
-- nsec=nanosecond, usec=microsecond, msec=millisecond, sec=second
-- 
-- ****

GPS-UTRAN-TRU ::=  ENUMERATED {
  nsec-50,
  ...
}

```

```

    nsec-500,
    usec-1,
    usec-10,
    msec-1,
    msec-10,
    msec-100,
    unreliable,
    ...
}

-- ****
-- Additional GPS Assistance Data Required
-- ****

AdditionalGPSAssistDataRequired ::= SEQUENCE {
    almanacRequest           BOOLEAN,
    utcModelRequest          BOOLEAN,
    ionosphericModelRequest  BOOLEAN,
    navigationModelRequest   BOOLEAN,
    dgpsCorrectionsRequest  BOOLEAN,
    referenceLocationRequest BOOLEAN,
    referenceTimeRequest     BOOLEAN,
    aquisitionAssistanceRequest  BOOLEAN,
    realTimeIntegrityRequest BOOLEAN,
    navModelAddDataRequest   NavModelAdditionalData      OPTIONAL,
    iE-Extensions             ProtocolExtensionContainer { { AdditionalGPSAssistDataRequired-ExtIEs } } OPTIONAL,
    ...
}

AdditionalGPSAssistDataRequired-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
    ...
}

-- ****
-- Additional GANSS Assistance Data Required
-- ****

AdditionalGanssAssistDataRequired ::= SEQUENCE {
    ganssReferenceTime        BOOLEAN,
    ganssreferenceLocation    BOOLEAN,
    ganssIonosphericModel    BOOLEAN,
    ganssRequestedGenericAssistanceDataList GanssRequestedGenericAssistanceDataList,
    iE-Extensions             ProtocolExtensionContainer { { AdditionalGanssAssistDataRequired-ExtIEs } } OPTIONAL,
    ...
}

AdditionalGanssAssistDataRequired-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
    {ID id-ganssReq-AddIonosphericModel      CRITICALITY ignore      EXTENSION      GANSSReq-AddIonosphericModel      PRESENCE optional} |

```

```

{ID id-ganssReq-EarthOrientPara      CRITICALITY ignore  EXTENSION  GANSSReq-EarthOrientPara      PRESENCE optional},
...
}

GANSSReq-AddIonosphericModel ::= SEQUENCE {
  ganss-add-iono-mode-req      BIT STRING (SIZE(2))          OPTIONAL,
  iE-Extensions                ProtocolExtensionContainer { { GANSSReq-AddIonosphericModel-ExtIEs } } OPTIONAL,
  ...
}

GANSSReq-AddIonosphericModel-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

GANSSReq-EarthOrientPara ::= SEQUENCE {
  ganss-earth-orient-para-req    ENUMERATED { true }          OPTIONAL,
  iE-Extensions                  ProtocolExtensionContainer { { GANSSReq-EarthOrientPara-ExtIEs } } OPTIONAL,
  ...
}

GANSSReq-EarthOrientPara-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

GanssRequestedGenericAssistanceDataList ::= SEQUENCE (SIZE (1..maxGANSS)) OF
  GanssReqGenericData

GanssReqGenericData ::=      SEQUENCE {
  ganssId                      GANSSID                      OPTIONAL,
  ganssRealTimeIntegrity        BOOLEAN                     OPTIONAL,
  ganssDifferentialCorrection  DGANSS-Sig-Id-Req        OPTIONAL,
  ganssAlmanac                  BOOLEAN                     OPTIONAL,
  ganssNavigationModel          BOOLEAN                     OPTIONAL,
  ganssTimeModelGnssGnss        BIT STRING (SIZE (9))    OPTIONAL,
  ganssReferenceMeasurementInfo BOOLEAN                     OPTIONAL,
  ganssDataBits                 GanssDataBits            OPTIONAL,
  ganssUTCModel                BOOLEAN                     OPTIONAL,
  ganssNavigationModelAdditionalData NavigationModelGANSS  OPTIONAL,
  iE-Extensions                 ProtocolExtensionContainer { { GanssReqGenericData-ExtIEs } } OPTIONAL,
  ...
}

GanssReqGenericData-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  {ID id-ganssAddNavigationModel-req      CRITICALITY ignore  EXTENSION  GANSS-AddNavigationModel-Req      PRESENCE optional}| 
  {ID id-ganssAddUTCModel-req            CRITICALITY ignore  EXTENSION  GANSS-AddUTCModel-Req            PRESENCE optional}| 
  {ID id-ganssAuxInfo-req              CRITICALITY ignore  EXTENSION  GANSS-AuxInfo-req              PRESENCE optional},
  ...
}

GANSS-AddNavigationModel-Req ::= SEQUENCE {
  ganss-AddNavigationModel-Req      ENUMERATED { true }          OPTIONAL,
  iE-Extensions                  ProtocolExtensionContainer { { GANSS-AddNavigationModel-Req-ExtIEs } } OPTIONAL,
  ...
}

GANSS-AddNavigationModel-Req-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

```

```

GANSS-AddUTCModel-Req ::= SEQUENCE {
  ganss-AddUTCModel-Req      ENUMERATED { true }                               OPTIONAL,
  iE-Extensions               ProtocolExtensionContainer { { GANSS-AddUTCModel-Req-ExtIEs } } OPTIONAL,
  ...
}

GANSS-AddUTCModel-Req-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

GANSS-AuxInfo-req ::= SEQUENCE {
  ganss-AuxInfo-Req      ENUMERATED { true }                               OPTIONAL,
  iE-Extensions               ProtocolExtensionContainer { { GANSS-AuxInfo-req-ExtIEs } } OPTIONAL,
  ...
}

GANSS-AuxInfo-req-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

DGANSS-Sig-Id-Req ::=           BIT STRING (SIZE (8))

GanssDataBits ::=           SEQUENCE {
  ganssTod                  INTEGER (0..86399),
  dataBitAssistanceList,
  iE-Extensions               ProtocolExtensionContainer { { GanssDataBits-ExtIEs } } OPTIONAL,
  ...
}

GanssDataBits-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

ReqDataBitAssistanceList ::=           SEQUENCE {
  ganssSignalID               BIT STRING (SIZE (8)),
  ganssDataBitInterval        INTEGER(0..15),
  ganssSatelliteInfo          SEQUENCE (SIZE (1..maxGANSSSat)) OF INTEGER(0..63)           OPTIONAL,
  iE-Extensions               ProtocolExtensionContainer { { ReqDataBitAssistanceList-ExtIEs } } OPTIONAL,
  ...
}

ReqDataBitAssistanceList-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

-- ****
-- 
-- Information Exchange ID
-- 
-- ****

InformationExchangeID ::= INTEGER (0..1048575)

```

```

-- ****
-- Information Report Characteristics
-- ****

InformationReportCharacteristics ::= SEQUENCE {
    type                InformationReportCharacteristicsType,
    periodicity         InformationReportPeriodicity      OPTIONAL,
    -- present if type indicates periodic
    ...
}

InformationReportCharacteristicsType ::= ENUMERATED {
    onDemand,
    periodic,
    onModification,
    ...
}

InformationReportPeriodicity ::= CHOICE {
    min                INTEGER (1..60, ...),
    -- Unit min, Step 1min
    hour               INTEGER (1..24, ...),
    -- Unit hour, Step 1hour
    ...
}

-- ****
-- Information Type
-- ****

InformationType ::= CHOICE {
    implicitInformation    MethodType,
    explicitInformation    ExplicitInformationList,
    ...
}

ExplicitInformationList ::= SEQUENCE (SIZE (1..maxNrOfExpInfo)) OF ExplicitInformation

ExplicitInformation ::= CHOICE {
    almanacAndSatelliteHealth      AlmanacAndSatelliteHealth,
    utcModel                      UtcModel,
    ionosphericModel              IonosphericModel,
    navigationModel               NavigationModel,
    dgpsCorrections               DgpsCorrections,
    referenceTime                 ReferenceTime,
}

```

```

acquisitionAssistance          AcquisitionAssistance,
realTimeIntegrity              RealTimeIntegrity,
almanacAndSatelliteHealthSIB  AlmanacAndSatelliteHealthSIB-InfoType,
...
referenceLocation              ReferenceLocation,
ganss-Common-DataReq          GANSSCommonDataReq,
ganss-Generic-DataList         GANSSGenericDataList
}

DganssCorrectionsReq ::= SEQUENCE {
  transmissionGanssTimeIndicator  TransmissionGanssTimeIndicator
                                         OPTIONAL,
  dganss-sig-id-req              DGANSS-Sig-Id-Req,
  iE-Extensions                  ProtocolExtensionContainer { { DganssCorrectionsReq-ExtIEs} } OPTIONAL,
  ...
}

DganssCorrectionsReq-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

Ganss-almanacAndSatelliteHealthReq ::= SEQUENCE {
  transmissionGanssTimeIndicator  TransmissionGanssTimeIndicator OPTIONAL,
  iE-Extensions                  ProtocolExtensionContainer { { Ganss-almanacAndSatelliteHealthReq-ExtIEs} } OPTIONAL,
  ...
}

Ganss-almanacAndSatelliteHealthReq-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

GANSSCommonDataReq ::= SEQUENCE{
  ganss-ReferenceTime            ENUMERATED {requested, not-requested} OPTIONAL,
  ganss-IonosphericModel          ENUMERATED {requested, not-requested} OPTIONAL,
  ganss-ReferenceLocation         ENUMERATED {requested, not-requested} OPTIONAL,
  ie-Extensions                  ProtocolExtensionContainer { { GANSSCommonDataReq-ExtIEs} } OPTIONAL,
  ...
}

GANSSCommonDataReq-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  { ID id-GANSS-AddIonoModelReq    CRITICALITY ignore EXTENSION GANSS-AddIonoModelReq    PRESENCE optional} |
  { ID id-GANSS-EarthOrientParaReq CRITICALITY ignore EXTENSION GANSS-EarthOrientParaReq PRESENCE optional} ,
  ...
}

GANSS-AddIonoModelReq ::= SEQUENCE {
  dataID          BIT STRING (SIZE(2))          OPTIONAL,
  ie-Extensions   ProtocolExtensionContainer { { GANSS-AddIonoModelReq-ExtIEs} } OPTIONAL,
  ...
}

GANSS-AddIonoModelReq-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

```

```

}

GANSS-EarthOrientParaReq ::= SEQUENCE {
  eopReq          ENUMERATED {requested, not-requested}                                OPTIONAL,
  iE-Extensions   ProtocolExtensionContainer { { GANSS-EarthOrientParaReq-ExtIEs} }    OPTIONAL,
  ...
}

GANSS-EarthOrientParaReq-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

GANSSGenericDataList ::= SEQUENCE (SIZE(1..maxGANSS)) OF GANSSGenericDataReq

GANSSGenericDataReq ::= SEQUENCE {
  ganssID          GANSSID                                                 OPTIONAL,
  ganss-realTimeIntegrity  Ganss-realTimeIntegrityReq                         OPTIONAL,
  ganss-dataBitAssistance GanssDataBits                                         OPTIONAL,
  dganssCorrections   DganssCorrectionsReq                                     OPTIONAL,
  ganss-almanacAndSatelliteHealth Ganss-almanacAndSatelliteHealthReq          OPTIONAL,
  ganss-referenceMeasurementInfo Ganss-referenceMeasurementInfoReq           OPTIONAL,
  ganss-utcModel      Ganss-utcModelReq                                       OPTIONAL,
  ganss-TimeModel-Gnss-Gnss      Ganss-TimeModel-Gnss-Gnss                    OPTIONAL,
  navigationModel    NavigationModelGANSS                                     OPTIONAL,
  ...,
  ganss-AddNavModelsReq  AddNavigationModelsGANSS                           OPTIONAL,
  ganss-AddUtcModelsReq  GANSS-AddUtcModelsReq                           OPTIONAL,
  ganss-AuxInfoReq     GANSS-AuxInfoReq                                     OPTIONAL,
  ganss-SBAS-ID        GANSS-SBAS-ID                                     OPTIONAL
}

AddNavigationModelsGANSS ::= SEQUENCE {
  ganssWeek          INTEGER(0..4095),
  ganssTOE           INTEGER(0..167),
  t-toe-limit        INTEGER(0..10),
  addSatRelatedDataListGANSS AddSatelliteRelatedDataListGANSS,
  iE-Extensions      ProtocolExtensionContainer { { AddNavigationModelsGANSS-ExtIEs} }  OPTIONAL,
  ...
}

AddNavigationModelsGANSS-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

AddSatelliteRelatedDataListGANSS ::= SEQUENCE (SIZE (0..maxGANSSSat)) OF AddSatelliteRelatedDataGANSS

AddSatelliteRelatedDataGANSS ::= SEQUENCE {
  satID             INTEGER (0..63),
  iod               BIT STRING (SIZE(10)),
  iE-Extensions     ProtocolExtensionContainer { { AddSatelliteRelatedDataGANSS-ExtIEs} } OPTIONAL,
  ...
}

```

```

AddSatelliteRelatedDataGANSS-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

GANSS-AddUtcModelsReq ::= SEQUENCE {
  transmissionGanssTimeIndicator TransmissionGanssTimeIndicator OPTIONAL,
  iE-Extensions ProtocolExtensionContainer { { GANSS-AddUtcModelsReq-ExtIEs} } OPTIONAL,
  ...
}

GANSS-AddUtcModelsReq-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

GANSS-AuxInfoReq ::= SEQUENCE {
  transmissionGanssTimeIndicator TransmissionGanssTimeIndicator OPTIONAL,
  iE-Extensions ProtocolExtensionContainer { { GANSS-AuxInfoReq-ExtIEs} } OPTIONAL,
  ...
}

GANSS-AuxInfoReq-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

GANSS-SBAS-ID ::= ENUMERATED {
  waas,
  egnos,
  msas,
  gagan,
  ...
}

Ganss-utcModelReq ::= SEQUENCE {
  transmissionGanssTimeIndicator TransmissionGanssTimeIndicator OPTIONAL,
  iE-Extensions ProtocolExtensionContainer { { Ganss-utcModelReq-ExtIEs} } OPTIONAL,
  ...
}

Ganss-utcModelReq-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

Ganss-realTimeIntegrityReq ::= SEQUENCE {
  transmissionGanssTimeIndicator TransmissionGanssTimeIndicator OPTIONAL,
  iE-Extensions ProtocolExtensionContainer { { Ganss-realTimeIntegrityReq-ExtIEs} } OPTIONAL,
  ...
}

Ganss-realTimeIntegrityReq-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

```

```

Ganss-referenceMeasurementInfoReq ::= SEQUENCE {
  transmissionGanssTimeIndicator  TransmissionGanssTimeIndicator OPTIONAL,
  iE-Extensions                  ProtocolExtensionContainer { { Ganss-referenceMeasurementInfoReq-ExtIEs } } OPTIONAL,
  ...
}

Ganss-referenceMeasurementInfoReq-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

Ganss-TimeModel-Gnss ::= SEQUENCE{
  ganssTimeModelGnssGnssExt      BIT STRING (SIZE(9)),
  transmissionGanssTimeIndicator TransmissionGanssTimeIndicator OPTIONAL,
  iE-Extensions                  ProtocolExtensionContainer { { Ganss-TimeModel-Gnss-ExtIEs } } OPTIONAL,
  ...
}

Ganss-TimeModel-Gnss-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

TransmissionGanssTimeIndicator ::= ENUMERATED {
  requested,
  not-Requested
}

AlmanacAndSatelliteHealth ::= NULL

UtcModel ::= SEQUENCE {
  transmissionTOWIndicator      TransmissionTOWIndicator,
  iE-Extensions                  ProtocolExtensionContainer { { UtcModel-ExtIEs } } OPTIONAL,
  ...
}

UtcModel-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

IonosphericModel ::= SEQUENCE {
  transmissionTOWIndicator      TransmissionTOWIndicator,
  iE-Extensions                  ProtocolExtensionContainer { { IonosphericModel-ExtIEs } } OPTIONAL,
  ...
}

IonosphericModel-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

NavigationModel ::= SEQUENCE {
  transmissionTOWIndicator      TransmissionTOWIndicator,
  ...
}

```

```

navModelAdditionalData          NavModelAdditionalData          OPTIONAL,
iE-Extensions                  ProtocolExtensionContainer { { NavigationModel-ExtIEs } }  OPTIONAL,
...
}

NavigationModel-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

NavModelAdditionalData ::= SEQUENCE {
  gps-Week                      INTEGER (0..1023),
  gps-TOE                        INTEGER (0..167),
  t-TOE-limit                     INTEGER (0..10),
  satRelatedDataList              SatelliteRelatedDataList,
  iE-Extensions                  ProtocolExtensionContainer { { NavModelAdditionalData-ExtIEs } } OPTIONAL,
  ...
}

NavModelAdditionalData-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

SatelliteRelatedDataList ::= SEQUENCE (SIZE (0..maxSat)) OF SatelliteRelatedData

SatelliteRelatedData ::= SEQUENCE {
  satID                         INTEGER (0..63),
  iode                          INTEGER (0..255),
  iE-Extensions                  ProtocolExtensionContainer { { SatelliteRelatedData-ExtIEs } } OPTIONAL,
  ...
}

SatelliteRelatedData-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

NavigationModelGANSS ::= SEQUENCE {
  ganssWeek                     INTEGER (0..4095),
  ganssTOE                       INTEGER (0..167),
  t-toe-limit                     INTEGER (0..10),
  satRelatedDataListGANSS        SatelliteRelatedDataListGANSS,
  iE-Extensions                  ProtocolExtensionContainer { { NavigationModelGANSS-ExtIEs } } OPTIONAL,
  ...
}

NavigationModelGANSS-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

SatelliteRelatedDataListGANSS ::= SEQUENCE (SIZE (0..maxGANSSSat)) OF SatelliteRelatedDataGANSS

SatelliteRelatedDataGANSS ::= SEQUENCE {
  satID                         INTEGER (0..63),
  iod                           BIT STRING (SIZE(10)),
  ...
}

```

```

iE-Extensions          ProtocolExtensionContainer { { SatelliteRelatedDataGANSS-ExtIEs } } OPTIONAL,
...
}

SatelliteRelatedDataGANSS-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
...
}

DgpsCorrections ::= NULL

ReferenceTime ::= NULL

AcquisitionAssistance ::= NULL

RealTimeIntegrity ::= NULL

AlmanacAndSatelliteHealthSIB-InfoType ::= SEQUENCE {
  transmissionTOWIndicator      TransmissionTOWIndicator,
  iE-Extensions          ProtocolExtensionContainer { { AlmanacAndSatelliteHealthSIB-InfoType-ExtIEs } } OPTIONAL,
...
}

AlmanacAndSatelliteHealthSIB-InfoType-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
...
}

ReferenceLocation ::= NULL

TransmissionTOWIndicator ::= ENUMERATED {
  requested,
  not-Requested
}

-- ****
-- 
-- Message Structure
-- 
-- ****

MessageStructure ::= SEQUENCE (SIZE (1..maxNrOfLevels)) OF
  SEQUENCE {
    iE-ID          ProtocolIE-ID,
    repetitionNumber  MessageStructureRepetition
    iE-Extensions  ProtocolExtensionContainer { {MessageStructure-ExtIEs} } OPTIONAL,
    ...
  }

MessageStructureRepetition ::= INTEGER (1..256)

MessageStructure-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
...
}

-- ****

```

```

-- Measurement Instructions Used
--
-- ****
MeasInstructionsUsed ::= SEQUENCE {
    measurementValidity      MeasurementValidity,
    iE-Extensions           ProtocolExtensionContainer { { MeasInstructionsUsed-ExtIEs } }  OPTIONAL,
    ...
}

MeasInstructionsUsed-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
    ...
}

-- ****
-- Measurement Validity
--
-- ****
MeasurementValidity ::= SEQUENCE {
    ue-State          ENUMERATED { cell-DCH, all-States-Except-Cell-DCH, all-States, ... },
    iE-Extensions     ProtocolExtensionContainer { { MeasurementValidity-ExtIEs } }  OPTIONAL,
    ...
}
MeasurementValidity-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
    ...
}

-- ****
-- Method Type
--
-- ****
MethodType ::= ENUMERATED {
    ue-assisted,
    ue-based
}

-- ****
-- OTDOA Measurement Group
--
-- ****
OTDOA-MeasurementGroup ::=      SEQUENCE {
    otdoa-ReferenceCellInfo,
    otdoa-NeighbourCellInfoList,
    otdoa-MeasuredResultsSets,
    iE-Extensions           ProtocolExtensionContainer { { OTDOA-MeasurementGroup-ExtIEs } }  OPTIONAL,
    ...
}

```

```

}

OTDOA-MeasurementGroup-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

OTDOA-ReferenceCellInfo ::= SEQUENCE {
  uC-ID,
  uTRANAccessPointPositionAltitude,
  tUTRANGPSMeasurementValueInfo
  iE-Extensions
  ...
}

OTDOA-ReferenceCellInfo-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  { ID id-TUTRANGANSSMeasurementValueInfo      CRITICALITY ignore  EXTENSION TUTRANGANSSMeasurementValueInfo
  { ID id-additionalMeasurementInforLCR        CRITICALITY ignore  EXTENSION AdditionalMeasurementInforLCR
    -- 1.28Mcps TDD only
  ...
}

OTDOA-NeighbourCellInfoList ::= SEQUENCE (SIZE (1..maxNrOfMeasNCell)) OF
  OTDOA-NeighbourCellInfo

OTDOA-NeighbourCellInfo ::= SEQUENCE {
  uC-ID,
  uTRANAccessPointPositionAltitude,
  relativeTimingDifferenceInfo,
  iE-Extensions
  ...
}

OTDOA-NeighbourCellInfo-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

OTDOA-MeasuredResultsSets ::= SEQUENCE (SIZE (1..maxNrOfMeasurements)) OF
  OTDOA-MeasuredResultsInfoList

OTDOA-MeasuredResultsInfoList ::= SEQUENCE (SIZE (1..maxNrOfMeasNCell)) OF
  OTDOA-MeasuredResultsInfo

OTDOA-MeasuredResultsInfo ::= SEQUENCE {
  uC-ID,
  ue-SFNSFNTimeTypeDifferenceType2Info,
  iE-Extensions
  ...
}

OTDOA-MeasuredResultsInfo-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  { ID id-OTDOA-AddMeasuredResultsInfo CRITICALITY ignore  EXTENSION  OTDOA-AddMeasuredResultsInfo PRESENCE optional},
  ...
}

```

```

OTDOA-AddMeasuredResultsInfo ::= SEQUENCE {
    primaryCPICH-Info      PrimaryScramblingCode,
    iE-Extensions          ProtocolExtensionContainer { { OTDOA-AddMeasuredResultsInfo-ExtIEs } }      OPTIONAL,
    ...
}

OTDOA-AddMeasuredResultsInfo-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
    ...
}

UE-SFNSFNTimeDifferenceType2Info ::= SEQUENCE {
    ue-SFNSFNTimeDifferenceType2      INTEGER (0..40961),
    ue-PositioningMeasQuality        UE-PositioningMeasQuality,
    measurementDelay                INTEGER (0..65535),
    iE-Extensions                   ProtocolExtensionContainer { { UE-SFNSFNTimeDifferenceInfo-ExtIEs } }      OPTIONAL,
    ...
}

UE-SFNSFNTimeDifferenceInfo-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
    ...
}

UC-ID ::= SEQUENCE {
    rNC-ID           INTEGER (0..4095),
    c-ID             INTEGER (0..65535),
    iE-Extensions    ProtocolExtensionContainer { { UC-ID-ExtIEs } }      OPTIONAL,
    ...
}

UC-ID-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
    { ID id-Extended-RNC-ID      CRITICALITY reject      EXTENSION      Extended-RNC-ID PRESENCE      optional},
    ...
}

Extended-RNC-ID ::= INTEGER (4096..65535)

RelativeTimingDifferenceInfo ::= CHOICE {
    SFNSFNMeasurementValueInfo      SFNSFNMeasurementValueInfo,
    tUTRANGPSMeasurementValueInfo   TUTRANGPSMeasurementValueInfo,
    ...,
    tUTRANGANSSMeasurementValueInfo TUTRANGANSSMeasurementValueInfo
}

SFNSFNMeasurementValueInfo ::= SEQUENCE {
    sFNSFNValue           SFNSFNValue,
    sFNSFNQuality         SFNSFNQuality,
    sFNSFNDriftRate       SFNSFNDriftRate,
    sFNSFNDriftRateQuality SFNSFNDriftRateQuality,
    iE-Extensions         ProtocolExtensionContainer { { SFNSFNMeasurementValueInfo-ExtIEs } }      OPTIONAL,
    ...
}

```

```

SFNSFMeasurementValueInfo-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

SFNSFValue ::= INTEGER (0..614399)

SFNSFQuality ::= INTEGER (0..255)
-- Unit chip, Step 1/16 chip, Range 0.. 255/16 chip

SFNSFDriftRate ::= INTEGER (-100..100)
-- Unit chip/s, Step 1/256 chip/s, Range -100/256..+100/256 chip/s

SFNSFDriftRateQuality ::= INTEGER (0..100)
-- Unit chip/s, Step 1/256 chip/s, Range 0..100/256 chip/s

TUTRANGPSMeasurementValueInfo ::= SEQUENCE {
  sFN
  SFN,
  tUTRANGPS
  TUTRANGPS,
  tUTRANGPSQuality
  TUTRANGPSQuality
  tUTRANGPSDriftRate
  TUTRANGPSDriftRate,
  tUTRANGPSDriftRateQuality
  TUTRANGPSDriftRateQuality
  iE-Extensions
  ProtocolExtensionContainer { { TUTRANGPSMeasurementValueInfo-ExtIEs } } OPTIONAL,
  ...
}

TUTRANGPSMeasurementValueInfo-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

SFN ::= INTEGER (0..4095)

TUTRANGPS ::= SEQUENCE {
  ms-part
  INTEGER (0..16383),
  ls-part
  INTEGER (0..4294967295)
}

TUTRANGPSQuality ::= INTEGER (0..255)
-- Unit chip, Step 1/16 chip, Range 0.. 255/16 chip

TUTRANGPSDriftRate ::= INTEGER (-50..50)
-- Unit chip/s, Step 1/256 chip/s, Range -50/256..+50/256 chip/s

TUTRANGPSDriftRateQuality ::= INTEGER (0..50)
-- Unit chip/s, Step 1/256 chip/s, Range 0..50/256 chip/s

TUTRANGANSSMeasurementValueInfo ::= SEQUENCE {
  ganssID
  GANSSID
  SFN,
  tUTRANGANSS
  TUTRANGANSS,
  tUTRANGANSSQuality
  INTEGER(0..255)
  OPTIONAL,
  tUTRANGANSSDriftRate
  INTEGER(-50..50),
  tUTRANGANSSDriftRateQuality
  INTEGER(0..50)
  OPTIONAL,
  iE-Extensions
  ProtocolExtensionContainer { { TUTRANGANSSMeasurementValueInfo-ExtIEs } } OPTIONAL,
  ...
}

```

```

}

TUTRANGANSSMeasurementValueInfo-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

TUTRANGANSS ::= SEQUENCE {
  ms-part          INTEGER (0..16383),
  ls-part          INTEGER (0..4294967295)
}

AdditionalMeasurementInforLCR ::= SEQUENCE {
  timingAdvanceLCR-R7      TimingAdvanceLCR-R7,
  rxTimingDeviationLCR    RxTimingDeviationLCR,
  angleOfArrivalLCR        AngleOfArrivalLCR OPTIONAL,
  iE-Extensions            ProtocolExtensionContainer { { AdditionalMeasurementInforLCR-ExtIEs } } OPTIONAL,
  ...
}

AdditionalMeasurementInforLCR-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

TimingAdvanceLCR-R7 ::= INTEGER (0..8191)

-- ****
-- 
-- Periodic Position Calculation Info
-- 
-- ****

PeriodicPosCalcInfo ::= SEQUENCE {
  referenceNumber      INTEGER (0..32767, ...),
  amountOutstandingRequests  INTEGER (1..8639999, ...),
  reportingInterval    INTEGER (1..8639999, ...),
  iE-Extensions        ProtocolExtensionContainer { { PeriodicPosCalcInfo-ExtIEs } } OPTIONAL,
  ...
}

PeriodicPosCalcInfo-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

-- ****
-- 
-- Periodic Location Info
-- 
-- ****

PeriodicLocationInfo ::= SEQUENCE {
  reportingAmount      INTEGER (1..8639999, ...),
  reportingInterval    INTEGER (1..8639999, ...),
  iE-Extensions        ProtocolExtensionContainer { { PeriodicLocationInfo-ExtIEs } } OPTIONAL,
}

```

```

}
  ...
}

PeriodicLocationInfo-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

-- ****
-- 
-- Periodic Termination Cause
-- 
-- ****

PeriodicTerminationCause ::= ENUMERATED {
  rrc-state-transition,
  cancelled-by-srnc,
  cancelled-by-sas,
  undefined,
  ...
}

-- ****
-- 
-- Positioning Method
-- 
-- ****

PositioningMethod ::= SEQUENCE {
  additionalMethodType,
  selectedPositionMethod,
  iE-Extensions
    ProtocolExtensionContainer { { PositioningMethod-ExtIEs } } OPTIONAL,
  ...
}

PositioningMethod-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
-- The following IE shall be present if the Selected Position Method IE value is set to "GNSS" or "OTDOA or GNSS"
  { ID id-GNSS-PositioningMethod CRITICALITY ignore EXTENSION GNSS-PositioningMethod PRESENCE conditional },
  ...
}

GNSS-PositioningMethod ::= BIT STRING (SIZE(9))

SelectedPositionMethod ::= ENUMERATED {
  oTDOA,
  gPS,
  oTDOA-or-GPS,
  cell-id,
  uTDOA,
  ...,
  gNSS,
  oTDOA-or-GNSS
}

```

```

-- ****
-- Positioning Priority
-- ****
PositioningPriority ::= ENUMERATED {
    high-priority,
    normal-priority,
    ...
}

-- ****
-- RRC State Change
-- ****
RRCstateChange ::= SEQUENCE {
    new-ue-State      ENUMERATED { cell-DCH, cell-FACH, cell-PCH, ura-PCH, ... },
    iE-Extensions    ProtocolExtensionContainer { { RRCstateChange-ExtIEs } }    OPTIONAL,
    ...
}

RRCstateChange-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
    ...
}

-- ****
-- Requested Data Value
-- ****
RequestedDataValue ::= SEQUENCE {
    gpsAlmanacAndSatelliteHealth      GPS-AlmanacAndSatelliteHealth          OPTIONAL,
    gps-UTC-Model                    GPS-UTC-Model                         OPTIONAL,
    gps-Ionospheric-Model           GPS-Ionospheric-Model          OPTIONAL,
    gps-NavigationModel            GPS-NavigationModel          OPTIONAL,
    dgpsCorrections                 DGPGSCorrections          OPTIONAL,
    referenceTime                   GPS-ReferenceTime          OPTIONAL,
    gps-AcquisitionAssistance      GPS-AcquisitionAssistance      OPTIONAL,
    gps-RealTime-Integrity         GPS-RealtimeIntegrity          OPTIONAL,
    almanacAndSatelliteHealthSIB   AlmanacAndSatelliteHealthSIB      OPTIONAL,
    gps-Transmission-TOW          GPS-Transmission-TOW          OPTIONAL,
    iE-Extensions                  ProtocolExtensionContainer { { RequestedDataValue-ExtIEs } } OPTIONAL,
    ...
}

--at least one of the above IEs shall be present in the requested data value

RequestedDataValue-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
    { ID id-GPS-ReferenceLocation      CRITICALITY ignore EXTENSION GPS-ReferenceLocation      PRESENCE optional } |
    { ID id-GANSS-CommonAssistanceData CRITICALITY ignore EXTENSION GANSS-CommonAssistanceData PRESENCE optional } |
}

```

```

{ ID id-GANSS-GenericAssistanceDataList CRITICALITY ignore EXTENSION GANSS-GenericAssistanceDataList PRESENCE optional },
...
}

-- ****
-- 
-- Requested Data Value Information
-- 

RequestedDataValueInformation ::= CHOICE {
  informationAvailable      InformationAvailable,
  informationNotAvailable   InformationNotAvailable
}

InformationAvailable ::= SEQUENCE {
  requestedDataValue      RequestedDataValue,
  iE-Extensions           ProtocolExtensionContainer { { InformationAvailable-ExtIEs} } OPTIONAL,
...
}

InformationAvailable-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
...
}

InformationNotAvailable ::= NULL

-- ****
-- 
-- Request Type
-- 

RequestType ::= SEQUENCE {
  event                  RequestTypeEvent,
  reportArea             RequestTypeReportArea,
  horizontalaccuracyCode RequestTypeAccuracyCode   OPTIONAL,
  iE-Extensions          ProtocolExtensionContainer { { RequestType-ExtIEs} }   OPTIONAL,
...
}

RequestType-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
...
}

RequestTypeEvent ::= ENUMERATED {
  stop-change-of-service-area,
  direct,
  change-of-service-area,
  stop-direct,
  ...,
  periodic,
  stop-periodic
}

```

```

RequestTypeReportArea ::= ENUMERATED {
    service-area,
    geographical-area,
    ...
}

RequestTypeAccuracyCode ::= INTEGER (0..127)

-- ****
-- 
-- Response Time
-- 
-- ****
ResponseTime ::= ENUMERATED {
    low-delay,
    delay-tolerant,
    ...
}

-- ****
-- 
-- Horizontal Accuracy Code
-- 
-- ****

HorizontalAccuracyCode ::= INTEGER (0..127)

-- ****
-- 
-- UE Positioning Capability
-- 
-- ****
UE-PositioningCapability ::= SEQUENCE {
    standAloneLocationMethodsSupported BOOLEAN,
    ueBasedOTDOASupported BOOLEAN,
    networkAssistedGPSSupport NetworkAssistedGPSSuport,
    supportGPSTimingOfCellFrame BOOLEAN,
    supportForIPDL BOOLEAN,
    supportForRxTxTimeDiff BOOLEAN,
    supportForUEAGPSinCellPCH BOOLEAN,
    supportForSFNSFNTimeDiff BOOLEAN,
    iE-Extensions ProtocolExtensionContainer { {UE-PositioningCapability-ExtIEs} } OPTIONAL,
    ...
}

UE-PositioningCapability-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
    { ID id-NetworkAssistedGANSSSupport CRITICALITY ignore EXTENSION NetworkAssistedGANSSSupport PRESENCE optional },
    ...
}

NetworkAssistedGANSSSupport ::= SEQUENCE (SIZE (1..maxGANSS)) OF SEQUENCE {
    ganssID GANSSID OPTIONAL,
    ganssMode ENUMERATED {
        networkBased,
        ...
    }
}

```

```

    ue-Based,
    both,
    none
  },
  ganssSignalID          GANSS-SignalID
  supportGANSSTimingOfCellFrame  BOOLEAN,
  supportGANSSCarrierPhaseMeasurement BOOLEAN,
  iE-Extensions  ProtocolExtensionContainer { { NetworkAssistedGANSSSuport-ExtIEs } } OPTIONAL,
  ...
}

NetworkAssistedGANSSSuport-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  { ID id-GANSS-SBAS-IDs          CRITICALITY ignore EXTENSION GANSS-SBAS-IDs          PRESENCE optional } |
  { ID id-GANSS-Signal-IDs        CRITICALITY ignore EXTENSION GANSS-Signal-IDs        PRESENCE optional } |
  { ID id-supportGANSSNonNativeADchoices  CRITICALITY ignore EXTENSION SupportGANSSNonNativeADchoices  PRESENCE optional },
  ...
}

NetworkAssistedGPSSuport ::= ENUMERATED {
  network-based,
  ue-based,
  both,
  none,
  ...
}

GANSS-SBAS-IDs ::= SEQUENCE {
  ganss-sbas-ids      BIT STRING (SIZE(8))          OPTIONAL,
  iE-Extensions       ProtocolExtensionContainer { { GANSS-SBAS-IDs-ExtIEs } } OPTIONAL,
  ...
}

GANSS-SBAS-IDs-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

GANSS-Signal-IDs ::= SEQUENCE {
  ganss-signal-ids    BIT STRING (SIZE(8))          OPTIONAL,
  iE-Extensions       ProtocolExtensionContainer { { GANSS-Signal-IDs-ExtIEs } } OPTIONAL,
  ...
}

GANSS-Signal-IDs-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

SupportGANSSNonNativeADchoices ::= SEQUENCE {
  support-ganss-NonNative-AD-choices ENUMERATED { true }          OPTIONAL,
  iE-Extensions       ProtocolExtensionContainer { { SupportGANSSNonNativeADchoices-ExtIEs } } OPTIONAL,
  ...
}

```

```

SupportGANSSNonNativeADchoices-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

-- ****
-- 
-- UTDOA Positioning (Position Activation Request Message)
-- 
-- ****

UTDOAPositioning ::= SEQUENCE {
  utdoa-BitCount          UTDOA-BitCount,
  utdoa-timeInterval       UTDOA-TimeInterval,
  iE-Extensions            ProtocolExtensionContainer { { UTDOAPositioning-ExtIEs } } OPTIONAL,
  ...
}

UTDOAPositioning-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

UTDOA-BitCount ::= INTEGER (0..5000)

UTDOA-TimeInterval ::= INTEGER (0..3000)

EnvironmentCharacterisation ::= ENUMERATED { heavyMultipathAndNLOSconditions,
  noOrLightMultipathAndUsuallyLOSconditions,
  notDefinedOrMixedEnvironment,
  ...
}

-- ****
-- 
-- GPS and GANSS Positioning (Position Activation Request Message)
-- 
-- ****

GPSPositioning ::= SEQUENCE {
  gpsPositioningInstructions   GPSPositioningInstructions,
  requestedDataValue          RequestedDataValue      OPTIONAL,
  iE-Extensions                ProtocolExtensionContainer { { GPSPositioning-ExtIEs } } OPTIONAL,
  ...
}

GPSPositioning-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

GPSPositioningInstructions ::= SEQUENCE {
  horizontalAccuracyCode      HorizontalAccuracyCode      OPTIONAL,
  verticalAccuracyCode        VerticalAccuracyCode      OPTIONAL,
  gpsTimingOfCellWanted       BOOLEAN,
}

```

```

additionalAssistanceDataRequest      BOOLEAN,
iE-Extensions                      ProtocolExtensionContainer { { GPSPositioningInstructions-ExtIEs } } OPTIONAL,
...
}

GPSPositioningInstructions-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  {ID id-MeasurementValidity CRITICALITY ignore EXTENSION MeasurementValidity PRESENCE optional},
  ...
}

GANSSPositioning ::= SEQUENCE {
  ganssPositioningInstructions      GANSS-PositioningInstructions,
  requestedDataValue               RequestedDataValue           OPTIONAL,
  iE-Extensions                     ProtocolExtensionContainer { { GANSSPositioning-ExtIEs } } OPTIONAL,
  ...
}

GANSSPositioning-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

GANSS-PositioningInstructions ::= SEQUENCE {
  horizontalAccuracyCode           HorizontalAccuracyCode      OPTIONAL,
  verticalAccuracyCode             VerticalAccuracyCode      OPTIONAL,
  ganssTimingOfCellWanted         BIT STRING (SIZE (8)),
  additionalAssistanceDataRequest  BIT STRING (SIZE (8)),
  measurementValidity             MeasurementValidity        OPTIONAL,
  iE-Extensions                     ProtocolExtensionContainer { { GANSS-PositioningInstructions-ExtIEs } } OPTIONAL,
  ...
}

GANSS-PositioningInstructions-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  {ID id-GANSScarrierPhaseRequested CRITICALITY ignore EXTENSION GANSScarrierPhaseRequested PRESENCE optional}| 
  {ID id-GANSSMultiFreqMeasRequested CRITICALITY ignore EXTENSION GANSSMultiFreqMeasRequested PRESENCE optional},
  ...
}

GANSScarrierPhaseRequested ::= SEQUENCE {
  ganss-carrierPhaseRequested      BIT STRING (SIZE (8))           OPTIONAL,
  iE-Extensions                     ProtocolExtensionContainer { { GANSScarrierPhaseRequested-ExtIEs } } OPTIONAL,
  ...
}

GANSScarrierPhaseRequested-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

GANSSMultiFreqMeasRequested ::= SEQUENCE {
  ganss-multiFreqMeasRequested    BIT STRING (SIZE (8))           OPTIONAL,
  iE-Extensions                     ProtocolExtensionContainer { { GANSSMultiFreqMeasRequested-ExtIEs } } OPTIONAL,
  ...
}

GANSSMultiFreqMeasRequested-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {

```

```

}
  ...
-- ****
-- OTDOA Assistance Data
-- ****
OTDOAAssistanceData ::= SEQUENCE {
  uE-Positioning-OTDOA-AssistanceData      UE-Positioning-OTDOA-AssistanceData,
  iE-Extensions                           ProtocolExtensionContainer { { OTDOAAssistanceData-ExtIEs } } OPTIONAL,
  ...
}

OTDOAAssistanceData-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

-- ****
-- UE Positioning OTDOA Assistance Data
-- ****
UE-Positioning-OTDOA-AssistanceData ::= SEQUENCE {
  ue-positioning-OTDOA-ReferenceCellInfo    UE-Positioning-OTDOA-ReferenceCellInfo      OPTIONAL,
  ue-positioning-OTDOA-NeighbourCellList     UE-Positioning-OTDOA-NeighbourCellList      OPTIONAL,
  iE-Extensions                           ProtocolExtensionContainer { { UE-Positioning-OTDOAAssistanceData-ExtIEs } } OPTIONAL,
  ...
}

UE-Positioning-OTDOAAssistanceData-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

UE-Positioning-OTDOA-ReferenceCellInfo ::= SEQUENCE {
  sfn                           SFN                                OPTIONAL,
  modeSpecificInfo CHOICE {
    fdd                         SEQUENCE {
      primaryCPICH-Info          PrimaryScramblingCode,
      ...
    },
    tdd                         SEQUENCE{
      cellParameterID           CellParameterID,
      --- coding is FFS
      ...
    },
    ...
  },
  frequencyInfo                 FrequencyInfo           OPTIONAL,
  positioningMode CHOICE {
    ueBased                     SEQUENCE {
      cellPosition               ReferenceCellPosition  OPTIONAL,
      -- actual value roundTripTime = (IE value * 0.0625) + 876
      ...
    }
  }
}

```

```

    roundTripTime           INTEGER (0..32766)           OPTIONAL,
    ...
  },
  ueAssisted              SEQUENCE {
    ...
  },
  ...
},
ue-positioning-IPDL-Parameters  UE-Positioning-IPDL-Parameters OPTIONAL,
iE-Extensions             ProtocolExtensionContainer { { UE-Positioning-OTDOAReferenceCellInfo-ExtIEs } } OPTIONAL,
...
}

UE-Positioning-OTDOAReferenceCellInfo-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  { ID id-ExtendedRoundTripTime   CRITICALITY ignore  EXTENSION ExtendedRoundTripTime           PRESENCE optional }| -- FDD only
  { ID id-timingAdvanceLCR-R7    CRITICALITY ignore  EXTENSION TimingAdvanceLCR-R7           PRESENCE optional }| -- 1.28Mcps TDD only
  { ID id-rxTimingDeviationLCR  CRITICALITY ignore  EXTENSION RxTimingDeviationLCR          PRESENCE optional }| -- 1.28Mcps TDD only
  { ID id-angleOfArrivalLCR     CRITICALITY ignore  EXTENSION AngleOfArrivalLCR           PRESENCE optional }, -- 1.28Mcps TDD only
  ...
}

ReferenceCellPosition ::= CHOICE {
  ellipsoidPoint           GeographicalCoordinates,
  ellipsoidPointWithAltitude  GA-PointWithAltitude,
  ...
}

UE-Positioning-IPDL-Parameters ::= SEQUENCE {
  modeSpecificInfo          CHOICE {
    fdd                      SEQUENCE {
      ip-Spacing               IP-Spacing,
      ip-Length                IP-Length,
      ip-Offset                INTEGER (0..9),
      seed                     INTEGER (0..63),
      ...
    },
    tdd                      SEQUENCE {
      ...
    },
    ...
  },
  burstModeParameters        BurstModeParameters           OPTIONAL,
  iE-Extensions             ProtocolExtensionContainer { { UE-Positioning-IPDL-Parameters-ExtIEs } } OPTIONAL,
  ...
}

UE-Positioning-IPDL-Parameters-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

IP-Spacing ::= ENUMERATED {

```

```

e5, e7, e10, e15, e20,
e30, e40, e50, ... }

IP-Length ::= ENUMERATED {
    ip15, ip110, ... }

BurstModeParameters ::= SEQUENCE {
    burstStart
    burstLength
    burstFreq
    iE-Extensions
    ProtocolExtensionContainer { { BurstModeParameters-ExtIEs } } OPTIONAL,
    ...
}

BurstModeParameters-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
    ...
}

```

```
UE-Positioning-OTDOA-NeighbourCellList ::= SEQUENCE (SIZE (1..maxCellMeas)) OF
    UE-Positioning-OTDOA-NeighbourCellInfo
```

```

UE-Positioning-OTDOA-NeighbourCellInfo ::= SEQUENCE {
    modeSpecificInfo CHOICE {
        fdd
            primaryCPICH-Info
            ...
        },
        tdd
            cellParameterID
            -- coding is FFS
            ...
    },
    ...
},
frequencyInfo FrequencyInfo OPTIONAL,
ue-positioning-IPDL-Parameters UE-Positioning-IPDL-Parameters OPTIONAL,
sfn-SFN-RelTimeDifference SFN-SFN-RelTimeDifference1, OPTIONAL,
sfn-Offset-Validity SFN-Offset-Validity OPTIONAL,
sfn-SFN-Drift SFN-SFN-Drift OPTIONAL,
searchWindowSize OTDOA-SearchWindowSize,
positioningMode CHOICE {
    ueBased
        relativeNorth
        relativeEast
        relativeAltitude
        fineSFN-SFN
        -- actual value roundTripTime = (IE value * 0.0625) + 876
        roundTripTime
        ...
},

```

```

ueAssisted
SEQUENCE {
  ...
  ...
  },
iE-Extensions
ProtocolExtensionContainer { { UE-Positioning-OTDOANeighbourCellInfo-ExtIEs } } OPTIONAL,
  ...
}

UE-Positioning-OTDOANeighbourCellInfo-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  { ID id-ExtendedRoundTripTime CRITICALITY ignore EXTENSION ExtendedRoundTripTime
    PRESENCE optional }, -- FDD only
  ...
}

SFN-SFN-RelTimeDifference1 ::= SEQUENCE {
  sfn-Offset
    INTEGER (0 .. 4095),
  sfn-sfn-Reltimedifference
    INTEGER (0.. 38399),
  iE-Extensions
    ProtocolExtensionContainer { { SFN-SFN-RelTimeDifference1-ExtIEs } } OPTIONAL,
  ...
}

SFN-SFN-RelTimeDifference1-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

SFN-Offset-Validity ::= ENUMERATED { false }

OTDOA-SearchWindowSize ::= ENUMERATED {
  c20, c40, c80, c160, c320,
  c640, c1280, moreThan1280, ...
}

SFN-SFN-Drift ::= ENUMERATED {
  sfnsfndrift0, sfnsfndrift1, sfnsfndrift2,
  sfnsfndrift3, sfnsfndrift4, sfnsfndrift5,
  sfnsfndrift8, sfnsfndrift10, sfnsfndrift15,
  sfnsfndrift25, sfnsfndrift35, sfnsfndrift50,
  sfnsfndrift65, sfnsfndrift80, sfnsfndrift100,
  sfnsfndrift-1, sfnsfndrift-2, sfnsfndrift-3,
  sfnsfndrift-4, sfnsfndrift-5, sfnsfndrift-8,
  sfnsfndrift-10, sfnsfndrift-15, sfnsfndrift-25,
  sfnsfndrift-35, sfnsfndrift-50, sfnsfndrift-65,
  sfnsfndrift-80, sfnsfndrift-100, ...
}

FineSFNSFN ::= INTEGER (0..15)
-- Range 0..0.9375 step size 0.0625

-- ****
-- Vertical Accuracy Code
-- ****

```

```

VerticalAccuracyCode ::= INTEGER (0..127)

-- ****
-- UTDOA Group
-- ****

UTDOA-Group ::= SEQUENCE {
    uC-ID,
    frequencyInfo,
    uTDOA-ChannelSettings,
    iE-Extensions
        ProtocolExtensionContainer { { UTDOA-Group-ExtIEs } } OPTIONAL,
    ...
}

UTDOA-Group-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
    ...
}

FrequencyInfo ::= SEQUENCE {
    modeSpecificInfo CHOICE {
        fdd FrequencyInfoFDD,
        tdd FrequencyInfoTDD,
        ...
    },
    iE-Extensions
        ProtocolExtensionContainer { { FrequencyInfo-ExtIEs } } OPTIONAL,
    ...
}

FrequencyInfo-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
    ...
}

FrequencyInfoFDD ::= SEQUENCE {
    uarfcn-UL UARFCN OPTIONAL,
    uarfcn-DL UARFCN,
    iE-Extensions
        ProtocolExtensionContainer { { FrequencyInfoFDD-ExtIEs } } OPTIONAL,
    ...
}

FrequencyInfoFDD-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
    ...
}

FrequencyInfoTDD ::= SEQUENCE {
    uarfcn UARFCN,
    iE-Extensions
        ProtocolExtensionContainer { { FrequencyInfoTDD-ExtIEs } } OPTIONAL,
    ...
}

```

```

FrequencyInfoTDD-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

UTDOA-RRCState ::= CHOICE {
  uTDOA-CELLDCH  UTDOA-CELLDCH,
  uTDOA-CELLFACH UTDOA-CELLFACH,
  ...
}

-- ****
-- UTDOA Cell DCH Information
-- ****

UTDOA-CELLDCH ::= SEQUENCE {
  uL-DPCHInfo,
  compressedModeAssistanceData,
  dCH-Information,
  e-DPCH-Information,
  iE-Extensions
    UL-DPCHInfo,
    Compressed-Mode-Assistance-Data OPTIONAL,
    DCH-Information OPTIONAL,
    E-DPCH-Information OPTIONAL,
    ProtocolExtensionContainer { { UTDOA-CELLDCH-ExtIEs} } OPTIONAL,
  ...
}

UTDOA-CELLDCH-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

UL-DPCHInfo ::= CHOICE {
  fdd {
    scramblingCodeType,
    scramblingCode,
    tfci-Existence,
    numberOffBI-Bits,
    iE-Extensions
      ScramblingCodeType,
      UL-ScramblingCode,
      BOOLEAN,
      NumberOffBI-Bits,
      ProtocolExtensionContainer { { UL-DPCHInfoFDD-ExtIEs} } OPTIONAL,
    ...
  },
  tdd {
    cellParameterID,
    tFCI-Coding,
    punctureLimit,
    repetitionPeriod,
    repetitionLength,
    tdd-DPCHOffset,
    uL-Timeslot-Information,
    frameOffset,
    specialBurstScheduling,
    iE-Extensions
      CellParameterID,
      TFCI-Coding,
      PuncturingLimit,
      RepetitionPeriod,
      RepetitionLength,
      TDD-DPCHOffset,
      UL-Timeslot-Information,
      FrameOffset,
      SpecialBurstScheduling,
      ProtocolExtensionContainer { { UL-DPCHInfoTDD-ExtIEs} } OPTIONAL,
    ...
  },
  ...
}

```

```

}

UL-DPCHInfoFDD-ExtIEs      PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

UL-DPCHInfoTDD-ExtIEs      PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

Compressed-Mode-Assistance-Data ::=      SEQUENCE {
  dl-information          DL-InformationFDD,
  ul-information          UL-InformationFDD,
  iE-Extensions           ProtocolExtensionContainer { { Compressed-Mode-Assistance-DataFDD-ExtIEs} } OPTIONAL,
  ...
}

Compressed-Mode-Assistance-DataFDD-ExtIEs      PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

DL-InformationFDD ::=      SEQUENCE {
  primaryScramblingCode   PrimaryScramblingCode,
  chipOffset               ChipOffset,
  frameOffset              FrameOffset,
  iE-Extensions            ProtocolExtensionContainer { { DL-InformationFDD-ExtIEs} } OPTIONAL,
  ...
}

DL-InformationFDD-ExtIEs      PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

UL-InformationFDD ::=      SEQUENCE {
  transmissionGapPatternSequenceInfo  Transmission-Gap-Pattern-Sequence-Information,
  activePatternSequenceInfo          Active-Pattern-Sequence-Information,
  cFN                                CFN,
  iE-Extensions           ProtocolExtensionContainer { { UL-InformationFDD-ExtIEs} } OPTIONAL,
  ...
}

UL-InformationFDD-ExtIEs      PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

Transmission-Gap-Pattern-Sequence-Information ::= SEQUENCE (SIZE (1..maxTGPS)) OF
  SEQUENCE {
    tGPSID                  TGPSID,
    tGSN                    TGSN,
    tGL1                    GapLength,
    tGL2                    GapLength OPTIONAL,
    tGD                     TGD,
  }

```

```

tGPL1                      GapDuration,
uplink-Compressed-Mode-Method      Uplink-Compressed-Mode-Method,
iE-Extensions      ProtocolExtensionContainer { {Transmission-Gap-Pattern-Sequence-Information-ExtIEs} } OPTIONAL,
...
}

Transmission-Gap-Pattern-Sequence-Information-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
...
}

TGD          ::= INTEGER (0|15..269)
-- 0 = Undefined, only one transmission gap in the transmission gap pattern sequence

TGPNC          ::= INTEGER (0..511)
-- 0 = infinity

TGPSID          ::= INTEGER (1.. maxTGPS)

TGSN          ::= INTEGER (0..14)

Uplink-Compressed-Mode-Method  ::= ENUMERATED {
  sFdiv2,
  higher-layer-scheduling,
...
}

GapDuration      ::= INTEGER (1..144,...)
-- Unit frame

GapLength      ::= INTEGER (1..14)
-- Unit slot

Active-Pattern-Sequence-Information ::= SEQUENCE {
  cMConfigurationChangeCFN      CFN,
  transmission-Gap-Pattern-Sequence-Status  Transmission-Gap-Pattern-Sequence-Status-List  OPTIONAL,
  iE-Extensions      ProtocolExtensionContainer { {Active-Pattern-Sequence-Information-ExtIEs} } OPTIONAL,
...
}

Active-Pattern-Sequence-Information-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
...
}

Transmission-Gap-Pattern-Sequence-Status-List ::= SEQUENCE (SIZE (1..maxTGPS)) OF
SEQUENCE {
  tGPSID          TGPSID,
  tGPRC          TGPNC,
  tGCFN          CFN,
  iE-Extensions      ProtocolExtensionContainer { { Transmission-Gap-Pattern-Sequence-Status-List-ExtIEs } } OPTIONAL,
...
}

```

```

Transmission-Gap-Pattern-Sequence-Status-List-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

DCH-Information ::= SEQUENCE {
  tFCS,
  trChInfo,
  iE-Extensions
  ProtocolExtensionContainer { { DCH-Information-ExtIEs } } OPTIONAL,
  ...
}

DCH-Information-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

TrChInfoList ::= SEQUENCE (SIZE(1..maxTrCH)) OF
  UL-TrCHInfo

UL-TrCHInfo ::= SEQUENCE {
  uL-TrCHtype,
  tfs
  iE-Extensions
  ProtocolExtensionContainer { { UL-TrCHInfo-ExtIEs } } OPTIONAL,
  ...
}

UL-TrCHInfo-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

UL-TrCHType ::= ENUMERATED {dch, usch, ...}

E-DPCH-Information ::= SEQUENCE {
  maxSet-E-DPDCHs,
  ul-PunctureLimit,
  e-TFCS-Information,
  e-TTI,
  e-DPCCH-PO
  iE-Extensions
  ProtocolExtensionContainer { { E-DPCH-Information-ExtIEs } } OPTIONAL,
  ...
}

E-DPCH-Information-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

Max-Set-E-DPDCHs ::= ENUMERATED {
  vN64, vN32, vN16, vN8, v2xN4, v2xN2, v2xN2plus2xN4,
  ...
}
-- Values related to [16]

```

```

E-TFCS-Information ::= SEQUENCE {
  e-DCH-TFCS-Index
  reference-E-TFCI-Information
  iE-Extensions
  ...
}

E-TFCS-Information-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

E-DCH-TFCS-Index ::= INTEGER (1..4,...)

Reference-E-TFCI-Information ::= SEQUENCE (SIZE (1..maxNrOfRefETFCIs)) OF Reference-E-TFCI-Information-Item

Reference-E-TFCI-Information-Item ::= SEQUENCE {
  reference-E-TFCI
  E-TFCI,
  reference-E-TFCI-PO
  Reference-E-TFCI-PO,
  iE-Extensions
  ProtocolExtensionContainer { { Reference-E-TFCI-Information-Item-ExtIEs} } OPTIONAL,
  ...
}

Reference-E-TFCI-Information-Item-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

Reference-E-TFCI-PO ::= INTEGER (0.. maxNrOfRefETFCI-PO-QUANTSTEPS)
  -- FFS according to mapping in [17]

E-TFCI ::= INTEGER (0..127)

E-TTI ::= ENUMERATED {
  e-TTI-2ms,
  e-TTI-10ms,
  ...
}

E-DPCCH-PO ::= INTEGER (0..maxNrOfEDPCCH-PO-QUANTSTEPS)

CellParameterID ::= INTEGER (0..127,...)

TFCI-Coding ::= ENUMERATED {
  v4,
  v8,
  v16,
  v32,
  ...
}

RepetitionLength ::= INTEGER (1..63)

RepetitionPeriod ::= ENUMERATED {
  v1,
  ...
}

```

```

v2,
v4,
v8,
v16,
v32,
v64,
...
}

TDD-DPCHOffset ::= CHOICE {
  initialOffset      INTEGER (0..255),
  noinitialOffset   INTEGER (0..63)
}

UL-Timeslot-Information ::= SEQUENCE (SIZE (1..maxNrOfULTSS)) OF UL-Timeslot-InformationItem

maxNrOfULTSS          INTEGER ::= 15
UL-Timeslot-InformationItem ::= SEQUENCE {
  timeSlot           TimeSlot,
  midambleShiftAndBurstType  MidambleShiftAndBurstType,
  tFCI-Presence      BOOLEAN,
  uL-Code-InformationList TDD-UL-Code-Information,
  iE-Extensions       ProtocolExtensionContainer { { UL-Timeslot-InformationItem-ExtIEs} } OPTIONAL,
  ...
}

UL-Timeslot-InformationItem-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

TimeSlot ::= INTEGER (0..14)

MidambleShiftAndBurstType ::= CHOICE {
  type1              SEQUENCE {
    midambleConfigurationBurstType1And3 MidambleConfigurationBurstType1And3,
    midambleAllocationMode      CHOICE {
      defaultMidamble        NULL,
      commonMidamble         NULL,
      ueSpecificMidamble    MidambleShiftLong,
      ...
    },
    ...
  },
  type2              SEQUENCE {
    midambleConfigurationBurstType2 MidambleConfigurationBurstType2,
    midambleAllocationMode      CHOICE {
      defaultMidamble        NULL,
      commonMidamble         NULL,
      ueSpecificMidamble    MidambleShiftShort,
      ...
    },
    ...
  },
  ...
}

```

```

type3                               SEQUENCE {
    midambleConfigurationBurstType1And3  MidambleConfigurationBurstType1And3,
    midambleAllocationMode             CHOICE {
        defaultMidamble              NULL,
        ueSpecificMidamble          MidambleShiftLong,
    ...
},
    ...
},
    ...
}

MidambleShiftLong ::=          INTEGER (0..15)
MidambleShiftShort ::=          INTEGER (0..5)
MidambleConfigurationBurstType1And3 ::=      ENUMERATED {v4, v8, v16}
MidambleConfigurationBurstType2 ::=      ENUMERATED {v3, v6}
TDD-UL-Code-Information ::= SEQUENCE (SIZE (1..maxNrOfDPCHs)) OF TDD-UL-Code-InformationItem
maxNrOfDPCHs ::=          INTEGER ::= 240
TDD-UL-Code-InformationItem ::= SEQUENCE {
    tdd-ChannelisationCode          TDD-ChannelisationCode,
    iE-Extensions                  ProtocolExtensionContainer { { TDD-UL-Code-InformationItem-ExtIEs} } OPTIONAL,
    ...
}
TDD-UL-Code-InformationItem-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
    ...
}

TDD-ChannelisationCode ::= ENUMERATED {
    chCode1div1,
    chCode2div1,
    chCode2div2,
    chCode4div1,
    chCode4div2,
    chCode4div3,
    chCode4div4,
    chCode8div1,
    chCode8div2,
    chCode8div3,
    chCode8div4,
    chCode8div5,
    chCode8div6,
    chCode8div7,
    chCode8div8,
    chCode16div1,
    chCode16div2,
    chCode16div3,
    chCode16div4,
}

```

```

chCode16div5,
chCode16div6,
chCode16div7,
chCode16div8,
chCode16div9,
chCode16div10,
chCode16div11,
chCode16div12,
chCode16div13,
chCode16div14,
chCode16div15,
chCode16div16,
...
}

SpecialBurstScheduling ::= INTEGER (1..256) -- Number of frames between special burst transmission during DTX

-- ****
-- 
-- UTDOA Cell Fach Information
-- 
-- ****

UTDOA-CELLFACH ::= SEQUENCE {
  pRACHparameters          PRACHparameters,
  cRNTI                    C-RNTI,
  uschParameters           UschParameters      OPTIONAL,
  iE-Extensions            ProtocolExtensionContainer { { UTDOA-CELLFACH-ExtIEs } } OPTIONAL,
  ...
}

UTDOA-CELLFACH-ExtIEs      PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

PRACHparameters ::= SEQUENCE (SIZE (1..maxPRACH)) OF
  PRACH-ChannelInfo

PRACH-ChannelInfo ::= SEQUENCE {
  pRACH-Info               PRACH-Info,
  tFS                      TransportFormatSet,
  tFCS                     TFCS,
  iE-Extensions            ProtocolExtensionContainer { { PRACH-ChannelInfo-ExtIEs } } OPTIONAL,
  ...
}

PRACH-ChannelInfo-ExtIEs    PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

PRACH-Info ::= CHOICE {

```

```

fdd          SEQUENCE {
  availableSignatures      AvailableSignatures,
  availableSF              SF-PRACH,
  preambleScramblingCodeWordNumber  PreambleScramblingCodeWordNumber,
  puncturingLimit          PuncturingLimit,
  availableSubChannelNumbers AvailableSubChannelNumbers,
  iE-Extensions           ProtocolExtensionContainer { { PRACH-Info-FDD-ExtIEs} } OPTIONAL,
  ...
  },
  tdd          SEQUENCE {
    timeSlot                TimeSlot,
    tdd-ChannelisationCode  TDD-ChannelisationCode,
    maxPRACH-MidambleShifts MaxPRACH-MidambleShifts,
    pRACH-Midamble          PRACH-Midamble,
    iE-Extensions           ProtocolExtensionContainer { { PRACH-Info-TDD-ExtIEs} } OPTIONAL,
    ...
  },
  ...
}

PRACH-Info-FDD-ExtIEs      PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

PRACH-Info-TDD-ExtIEs      PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

SF-PRACH ::=          ENUMERATED {
  sfpr32, sfpr64, sfpr128, sfpr256, ...
}

AvailableSignatures ::=      BIT STRING {
  signature15(0),
  signature14(1),
  signature13(2),
  signature12(3),
  signature11(4),
  signature10(5),
  signature9(6),
  signature8(7),
  signature7(8),
  signature6(9),
  signature5(10),
  signature4(11),
  signature3(12),
  signature2(13),
  signature1(14),
  signature0(15)
}      (SIZE(16))

PreambleScramblingCodeWordNumber ::=      INTEGER (0..15)
PuncturingLimit ::=      INTEGER (0..15)
-- 0: 40%; 1: 44%; ... 14: 96%; 15: 100%

```

```

AvailableSubChannelNumbers ::=      BIT STRING {
                                         subCh11(0),
                                         subCh10(1),
                                         subCh9(2),
                                         subCh8(3),
                                         subCh7(4),
                                         subCh6(5),
                                         subCh5(6),
                                         subCh4(7),
                                         subCh3(8),
                                         subCh2(9),
                                         subCh1(10),
                                         subCh0(11)
                                         }      (SIZE(12))

ScramblingCodeType ::=          ENUMERATED {
                                         shortSC,
                                         longSC
                                         }

UL-ScramblingCode ::=          INTEGER (0..16777215)

NumberOfFBI-Bits ::=          INTEGER (0..2)

TransportFormatSet ::=          SEQUENCE {
                                         dynamicPart          TransportFormatSet-DynamicPartList,
                                         semi-staticPart       TransportFormatSet-Semi-staticPart,
                                         iE-Extensions         ProtocolExtensionContainer { { TransportFormatSet-ExtIEs} }      OPTIONAL,
                                         ...
                                         }

TransportFormatSet-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
                                         ...
                                         }

TransportFormatSet-DynamicPartList ::= SEQUENCE (SIZE (1..maxNrOfTFs)) OF
                                         SEQUENCE {
                                         rlc-Size           RLC-Size,
                                         numberOfTbsTTIList SEQUENCE (SIZE (1..maxNrOfTFs)) OF TbsTTIInfo,
                                         iE-Extensions       ProtocolExtensionContainer { { TransportFormatSet-DynamicPartList-ExtIEs} }      OPTIONAL,
                                         ...
                                         }

TransportFormatSet-DynamicPartList-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
                                         ...
                                         }

TbsTTIInfo ::= SEQUENCE {
                                         tTIInfo             TransportFormatSet-TransmissionTimeIntervalDynamic      OPTIONAL,
                                         numberOfTbs         TransportFormatSet-NrOfTransportBlocks,
                                         iE-Extensions       ProtocolExtensionContainer { { TbsTTIInfo-ExtIEs} } OPTIONAL,
                                         ...
                                         }

```

```

}

TbsTTIInfo-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

RLC-Size ::= INTEGER (129..5055)

TransportFormatSet-NrOfTransportBlocks ::= INTEGER (0..512)

TransportFormatSet-Semi-staticPart ::= SEQUENCE {
  transmissionTimeInterval      TransportFormatSet-TransmissionTimeIntervalSemiStatic,
  channelCoding                 TransportFormatSet-ChannelCodingType,
  codingRate                    TransportFormatSet-CodingRate           OPTIONAL,
  -- This IE shall be present if the Type of channel coding IE is set to 'convolutional' or 'turbo'
  rateMatchingAttribute        TransportFormatSet-RateMatchingAttribute,
  cRC-Size                      TransportFormatSet-CRC-Size,
  iE-Extensions                 ProtocolExtensionContainer { { TransportFormatSet-Semi-staticPart-ExtIEs } }   OPTIONAL,
  ...
}

TransportFormatSet-Semi-staticPart-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

TransportFormatSet-TransmissionTimeIntervalSemiStatic ::= ENUMERATED {
  msec-5,
  msec-10,
  msec-20,
  msec-40,
  msec-80,
  dynamic,
  ...
}

TransportFormatSet-ChannelCodingType ::= ENUMERATED {
  no-codingTDD,
  convolutional-coding,
  turbo-coding,
  ...
}

TransportFormatSet-CodingRate ::= ENUMERATED {
  half,
  third,
  ...
}

TransportFormatSet-RateMatchingAttribute ::= INTEGER (1..maxRateMatching)

TransportFormatSet-CRC-Size ::= ENUMERATED {
  v0,
  ...
}

```

```

v8,
v12,
v16,
v24,
...
}

TransportFormatSet-TransmissionTimeIntervalDynamic ::= ENUMERATED {
  msec-10,
  msec-20,
  msec-40,
  msec-80,
  dynamic,
  ...
}

TFCS ::= SEQUENCE (SIZE (1..maxTFC)) OF CTFC

CTFC ::= CHOICE{
  ctfc2Bit          SEQUENCE (SIZE (1..maxTFC)) OF INTEGER (0..3),
  ctfc4Bit          SEQUENCE (SIZE (1..maxTFC)) OF INTEGER (0..15),
  ctfc6Bit          SEQUENCE (SIZE (1..maxTFC)) OF INTEGER (0..63),
  ctfc8Bit          SEQUENCE (SIZE (1..maxTFC)) OF INTEGER (0..255),
  ctfc12Bit         SEQUENCE (SIZE (1..maxTFC)) OF INTEGER (0..4095),
  ctfc16Bit         SEQUENCE (SIZE (1..maxTFC)) OF INTEGER (0..65535),
  ctfc24Bit         SEQUENCE (SIZE (1..maxTFC)) OF INTEGER (0..16777215),
  ...
}

C-RNTI ::= BIT STRING (SIZE (16))

UARFCN ::= INTEGER (0..16383)

CFN ::= INTEGER (0..255)

ChipOffset ::= INTEGER (0..38399)
-- Unit Chip

FrameOffset ::= INTEGER (0..255)

PrimaryScramblingCode ::= INTEGER (0..511)

UschParameters ::= SEQUENCE {
  cellParameterID          CellParameterID,
  tFCI-Coding               TFCI-Coding,
  punctureLimit             PuncturingLimit,
  repetitionPeriod          RepetitionPeriod,
  uSCH-SchedulingOffset    USCH-SchedulingOffset,
  uL-Timeslot-Information  UL-Timeslot-Information,
  tFCS
}

```

```

trChInfo                                TrChInfoList,
iE-Extensions   ProtocolExtensionContainer { { UschParameters-ExtIEs } } OPTIONAL,
...
}

UschParameters-ExtIEs      PCAP-PROTOCOL-EXTENSION ::= {
...
}

USCH-SchedulingOffset ::= INTEGER (0..255)

MaxPRACH-MidambleShifts ::= ENUMERATED {
  shift4,
  shift8,
...
}

PRACH-Midamble ::= ENUMERATED {
  inverted,
  direct,
...
}

--*****
-- Positioning Response Time
--*****
Positioning-ResponseTime ::=           ENUMERATED { ms250, ms500, s1, s2, s3, s4, s6,
  s8, s12, s16, s20, s24, s28, s32, s64,
...
}

--*****
-- Amount of Reporting
--*****
AmountOfReporting ::=    ENUMERATED { ra2, ra4, ra8, ra16, ra32,
  ra64, ra-Infinity, ... }

-- *****
-- Include Velocity
-- *****
IncludeVelocity      ::= ENUMERATED {
  requested
}

```

```

}

-- ****
-- VelocityEstimate
-- ****
-- VelocityEstimate is based on Description of Velocity in 23.032

VelocityEstimate ::= CHOICE {
    horizontalVelocity                      HorizontalVelocity,
    horizontalWithVerticalVelocity           HorizontalWithVerticalVelocity,
    horizontalVelocityWithUncertainty       HorizontalVelocityWithUncertainty,
    horizontalWithVerticalVelocityAndUncertainty HorizontalWithVerticalVelocityAndUncertainty,
    ...
}

HorizontalVelocity ::= SEQUENCE {
    horizontalSpeedAndBearing      HorizontalSpeedAndBearing,
    iE-Extensions                 ProtocolExtensionContainer { { HorizontalVelocity-ExtIEs} } OPTIONAL,
    ...
}

HorizontalVelocity-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
    ...
}

HorizontalWithVerticalVelocity ::= SEQUENCE {
    horizontalSpeedAndBearing      HorizontalSpeedAndBearing,
    verticalVelocity                VerticalVelocity,
    iE-Extensions                 ProtocolExtensionContainer { { HorizontalWithVerticalVelocity-ExtIEs} } OPTIONAL,
    ...
}

HorizontalWithVerticalVelocity-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
    ...
}

HorizontalVelocityWithUncertainty ::= SEQUENCE {
    horizontalSpeedAndBearing      HorizontalSpeedAndBearing,
    uncertaintySpeed               INTEGER (0..255),
    iE-Extensions                 ProtocolExtensionContainer { { HorizontalVelocityWithUncertainty-ExtIEs} } OPTIONAL,
    ...
}

HorizontalVelocityWithUncertainty-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
    ...
}

HorizontalWithVerticalVelocityAndUncertainty ::= SEQUENCE {

```

```

horizontalSpeedAndBearing
verticalVelocity
horizontalUncertaintySpeed
verticalUncertaintySpeed
iE-Extensions      ProtocolExtensionContainer { { HorizontalWithVerticalVelocityAndUncertainty-ExtIEs } } OPTIONAL,
...
}

HorizontalWithVerticalVelocityAndUncertainty-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

HorizontalSpeedAndBearing ::= SEQUENCE {
  bearing
  horizontalSpeed
}
  INTEGER (0..359),
  INTEGER (0..2047)

VerticalVelocity ::= SEQUENCE {
  verticalSpeed
  verticalSpeedDirection
}
  INTEGER (0..255),
  VerticalSpeedDirection

VerticalSpeedDirection ::= ENUMERATED {
  upward,
  downward
}

--*****
-- 
-- UTRAN-GPS Reference Time
-- 
--*****

UTRAN-GPSReferenceTime ::= SEQUENCE {
  utran-GPSTimingOfCell
  INTEGER (0..2322431999999, ...),
  uC-ID
  OPTIONAL,
  sfn
  INTEGER (0..4095),
  iE-Extensions
  ProtocolExtensionContainer { { UTRAN-GPSReferenceTime-ExtIEs } } OPTIONAL,
  ...
}

UTRAN-GPSReferenceTime-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

--*****
-- 
-- UTRAN-GPS Reference Time Result
-- 
--*****

UTRAN-GPSReferenceTimeResult ::= SEQUENCE {

```

```

ue-GPSTimingOfCell      INTEGER (0..37158911999999, ...),
uC-ID                   UC-ID,
sfn                     INTEGER (0..4095),
iE-Extensions          ProtocolExtensionContainer { { UTRAN-GPSReferenceTimeResult-ExtIEs } } OPTIONAL,
...
}

UTRAN-GPSReferenceTimeResult-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
...
}

-- ****
-- 
-- UTRAN-GANSS Reference Time Result
-- 
-- ****

UTRAN-GANSSReferenceTimeResult ::= SEQUENCE {
  ue-GANSSTimingOfCell      INTEGER (0..345599999999, ...),
  ganss-Time-ID              GANSSID                               OPTIONAL,
  ganssTodUncertainty       INTEGER(0..127)                         OPTIONAL,
  uC-ID                     UC-ID,
  sfn                       INTEGER (0..4095),
  iE-Extensions             ProtocolExtensionContainer { { UTRAN-GANSSReferenceTimeResult-ExtIEs } } OPTIONAL,
...
}

UTRAN-GANSSReferenceTimeResult-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
...
}

END

```

9.3.5 Common Definitions

```

-- ****
-- 
-- Common definitions
-- 
-- ****

PCAP-CommonDataTypes {
  itu-t (0) identified-organization (4) etsi (0) mobileDomain (0)
  umts-Access (20) modules (3) pcap(4) version1 (1) pcap-CommonDataTypes (3)  }
}

DEFINITIONS AUTOMATIC TAGS ::=

BEGIN

```

```

-- ****
-- Extension constants
--
-- ****

maxPrivateIEs           INTEGER ::= 65535
maxProtocolExtensions   INTEGER ::= 65535
maxProtocolIEs          INTEGER ::= 65535

-- ****
-- Common Data Types
--
-- ****

Criticality   ::= ENUMERATED { reject, ignore, notify }

Presence      ::= ENUMERATED { optional, conditional, mandatory }

PrivateIE-ID   ::= CHOICE {
    local          INTEGER (0..65535),
    global         OBJECT IDENTIFIER
}

ProcedureCode   ::= INTEGER (0..255)

ProtocolIE-ID  ::= INTEGER (0..maxProtocolIEs)

TransactionID   ::= CHOICE {
    shortTID      INTEGER (0..127),
    longTID       INTEGER (0..32767)
}

TriggeringMessage ::= ENUMERATED { initiating-message, successful-outcome, unsuccessful-outcome, outcome }

END

```

9.3.6 Constant Definitions

```

-- ****
-- Constant definitions
--
-- ****

PCAP-Constants {
    itu-t (0) identified-organization (4) etsi (0) mobileDomain (0)
    umts-Access (20) modules (3) pcap(4) version1 (1) pcap-Constants (4)
}

```

```

DEFINITIONS AUTOMATIC TAGS ::=

BEGIN

IMPORTS
  ProcedureCode,
  ProtocolIE-ID
FROM PCAP-CommonDataTypes;

-- ****
-- 
-- Elementary Procedures
-- 
-- ****

id-PositionCalculation          ProcedureCode ::= 1
id-InformationExchangeInitiation ProcedureCode ::= 2
id-InformationReporting          ProcedureCode ::= 3
id-InformationExchangeTermination ProcedureCode ::= 4
id-InformationExchangeFailure    ProcedureCode ::= 5
id-ErrorIndication               ProcedureCode ::= 6
id-privateMessage                ProcedureCode ::= 7
id-PositionParameterModification ProcedureCode ::= 8
id-PositionInitiation            ProcedureCode ::= 9
id-PositionActivation            ProcedureCode ::= 10
id-Abort                         ProcedureCode ::= 11
id-PositionPeriodicReport        ProcedureCode ::= 12
id-PositionPeriodicResult        ProcedureCode ::= 13
id-PositionPeriodicTermination   ProcedureCode ::= 14

-- ****
-- 
-- Lists
-- 
-- ****

maxNrOfErrors          INTEGER ::= 256
maxSat                 INTEGER ::= 16
maxSatAlmanac           INTEGER ::= 32
maxNrOfLevels           INTEGER ::= 256
maxNrOfPoints            INTEGER ::= 15
maxNrOfExpInfo           INTEGER ::= 32
maxNrOfMeasNCell          INTEGER ::= 32
maxNrOfMeasurements       INTEGER ::= 16
maxNrOfSets              INTEGER ::= 3
maxRateMatching           INTEGER ::= 256
maxNrOfTFS                INTEGER ::= 32
maxTTI-count              INTEGER ::= 4
maxTS-1                  INTEGER ::= 13

```

```

maxCCTrCH          INTEGER ::= 8
maxTF              INTEGER ::= 32
maxTFC             INTEGER ::= 1024
maxPRACH           INTEGER ::= 16
maxTrCH            INTEGER ::= 32
maxTGPS             INTEGER ::= 6
maxNoOfMeasurements INTEGER ::= 16
maxCellMeas         INTEGER ::= 32
maxNrOfEDPCCH-PO-QUANTSTEPS  INTEGER ::= 8    -- FFS
maxNrOfRefETFCI-PO-QUANTSTEPS  INTEGER ::= 8    -- FFS
maxNrOfRefETFCIs        INTEGER ::= 8
maxSet              INTEGER ::= 9
maxGANSSSat         INTEGER ::= 64
maxSgnType          INTEGER ::= 8
maxGANSSSet          INTEGER ::= 8
maxGANSSSatAlmanac   INTEGER ::= 9
maxGANSSClockMod     INTEGER ::= 4
maxGANSS-1           INTEGER ::= 7

-- *****
-- IEs
-- *****
id-Cause             ProtocolIE-ID ::= 1
id-CriticalityDiagnostics ProtocolIE-ID ::= 2
id-GPS-UTRAN-TRU      ProtocolIE-ID ::= 3
id-InformationExchangeID ProtocolIE-ID ::= 4
id-InformationExchangeObjectType-InfEx-Rprt ProtocolIE-ID ::= 5
id-InformationExchangeObjectType-InfEx-Rgst  ProtocolIE-ID ::= 6
id-InformationExchangeObjectType-InfEx-Rsp   ProtocolIE-ID ::= 7
id-InformationReportCharacteristics ProtocolIE-ID ::= 8
id-InformationType       ProtocolIE-ID ::= 9
id-GPS-MeasuredResultsList ProtocolIE-ID ::= 10
id-MethodType          ProtocolIE-ID ::= 11
id-RefPosition-InfEx-Rqst  ProtocolIE-ID ::= 12
id-RefPosition-InfEx-Rsp   ProtocolIE-ID ::= 13
id-RefPosition-Inf-Rprt   ProtocolIE-ID ::= 14
id-RequestedDataValue     ProtocolIE-ID ::= 15
id-RequestedDataValueInformation ProtocolIE-ID ::= 16
id-TransactionID         ProtocolIE-ID ::= 17
id-UE-PositionEstimate   ProtocolIE-ID ::= 18
id-CellId-MeasuredResultsSets ProtocolIE-ID ::= 20
id-OTDOA-MeasurementGroup ProtocolIE-ID ::= 22
id-AccuracyFulfilmentIndicator ProtocolIE-ID ::= 23
id-HorizontalAccuracyCode ProtocolIE-ID ::= 24
id-VerticalAccuracyCode   ProtocolIE-ID ::= 25
id-UTDOA-Group           ProtocolIE-ID ::= 26
id-RequestType            ProtocolIE-ID ::= 28
id-UE-PositioningCapability ProtocolIE-ID ::= 29
id-UC-id                 ProtocolIE-ID ::= 30

```

id-ResponseTime	ProtocolIE-ID ::= 31
id-PositioningPriority	ProtocolIE-ID ::= 32
id-ClientType	ProtocolIE-ID ::= 33
id-PositioningMethod	ProtocolIE-ID ::= 34
id-UTDOAPositioning	ProtocolIE-ID ::= 35
id-GPSPositioning	ProtocolIE-ID ::= 36
id-OTDOAAssistanceData	ProtocolIE-ID ::= 37
id-Positioning-ResponseTime	ProtocolIE-ID ::= 38
id-EnvironmentCharacterisation	ProtocolIE-ID ::= 39
id-PositionData	ProtocolIE-ID ::= 40
id-IncludeVelocity	ProtocolIE-ID ::= 41
id-VelocityEstimate	ProtocolIE-ID ::= 42
id-rxTimingDeviation768Info	ProtocolIE-ID ::= 43
id-UC-ID-InfEx-Rqst	ProtocolIE-ID ::= 44
id-UE-PositionEstimateInfo	ProtocolIE-ID ::= 45
id-UTRAN-GPSReferenceTime	ProtocolIE-ID ::= 46
id-UTRAN-GPSReferenceTimeResult	ProtocolIE-ID ::= 47
id-UTRAN-GPS-DriftRate	ProtocolIE-ID ::= 48
id-OTDOA-AddMeasuredResultsInfo	ProtocolIE-ID ::= 49
id-GPS-ReferenceLocation	ProtocolIE-ID ::= 50
id-OTDOA-MeasuredResultsSets	ProtocolIE-ID ::= 51
id-rxTimingDeviation384extInfo	ProtocolIE-ID ::= 55
id-ExtendedRoundTripTime	ProtocolIE-ID ::= 56
id-PeriodicPosCalcInfo	ProtocolIE-ID ::= 57
id-PeriodicLocationInfo	ProtocolIE-ID ::= 58
id-AmountOfReporting	ProtocolIE-ID ::= 59
id-MeasInstructionsUsed	ProtocolIE-ID ::= 60
id-RRCstateChange	ProtocolIE-ID ::= 61
id-PeriodicTerminationCause	ProtocolIE-ID ::= 62
id-MeasurementValidity	ProtocolIE-ID ::= 63
id-roundTripTimeInfoWithType1	ProtocolIE-ID ::= 64
id-CellIDPositioning	ProtocolIE-ID ::= 66
id-AddMeasurementInfo	ProtocolIE-ID ::= 67
id-Extended-RNC-ID	ProtocolIE-ID ::= 68
id-GANSS-CommonAssistanceData	ProtocolIE-ID ::= 69
id-GANSS-GenericAssistanceDataList	ProtocolIE-ID ::= 70
id-GANSS-MeasuredResultsList	ProtocolIE-ID ::= 71
id-GANSS-UTRAN-TRU	ProtocolIE-ID ::= 72
id-GANSSPositioning	ProtocolIE-ID ::= 73
id-GANSS-PositioningDataSet	ProtocolIE-ID ::= 74
id-GNSS-PositioningMethod	ProtocolIE-ID ::= 75
id-NetworkAssistedGANSSSuport	ProtocolIE-ID ::= 76
id-TUTRANGANSSMeasurementValueInfo	ProtocolIE-ID ::= 77
id-AdditionalGPSAssistDataRequired	ProtocolIE-ID ::= 78
id-AdditionalGanssAssistDataRequired	ProtocolIE-ID ::= 79
id-angleOfArrivalLCR	ProtocolIE-ID ::= 80
id-extendedTimingAdvanceLCR	ProtocolIE-ID ::= 81
id-additionalMeasurementInforLCR	ProtocolIE-ID ::= 82
id-timingAdvanceLCR-R7	ProtocolIE-ID ::= 83
id-rxTimingDeviationLCR	ProtocolIE-ID ::= 84
id-GPSReferenceTimeUncertainty	ProtocolIE-ID ::= 85
id-GANSS-AddIonoModelReq	ProtocolIE-ID ::= 86
id-GANSS-EarthOrientParaReq	ProtocolIE-ID ::= 87
id-GANSS-Additional-Ionospheric-Model	ProtocolIE-ID ::= 88

id-GANSS-Earth-Orientation-Parameters	ProtocolIE-ID ::= 89
id-GANSS-Additional-Time-Models	ProtocolIE-ID ::= 90
id-GANSS-Additional-Navigation-Models	ProtocolIE-ID ::= 91
id-GANSS-Additional-UTC-Models	ProtocolIE-ID ::= 92
id-GANSS-Auxiliary-Information	ProtocolIE-ID ::= 93
id-GANSS-SBAS-ID	ProtocolIE-ID ::= 94
id-GANSS-SBAS-IDs	ProtocolIE-ID ::= 95
id-GANSS-Signal-IDs	ProtocolIE-ID ::= 96
id-supportGANSSNonNativeADchoices	ProtocolIE-ID ::= 97
id-PositionDataUEbased	ProtocolIE-ID ::= 98
id-ganssCodePhaseAmbiguityExt	ProtocolIE-ID ::= 99
id-ganssIntegerCodePhaseExt	ProtocolIE-ID ::= 100
id-GANSScarrierPhaseRequested	ProtocolIE-ID ::= 101
id-GANSSMultiFreqMeasRequested	ProtocolIE-ID ::= 102
id-ganssReq-AddIonosphericModel	ProtocolIE-ID ::= 103
id-ganssReq-EarthOrientPara	ProtocolIE-ID ::= 104
id-ganssAddNavigationModel-req	ProtocolIE-ID ::= 105
id-ganssAddUTCModel-req	ProtocolIE-ID ::= 106
id-ganssAuxInfo-req	ProtocolIE-ID ::= 107
id-GANSS-AlmanacModelChoice	ProtocolIE-ID ::= 108

END

9.3.7 Container Definitions

```
-- ****
-- 
-- Container definitions
-- 
-- ****

PCAP-Containers {
  itu-t (0) identified-organization (4) etsi (0) mobileDomain (0)
  umts-Access (20) modules (3) pcap(4) version1 (1) pcap-Containers (5) }

DEFINITIONS AUTOMATIC TAGS ::=

BEGIN

-- ****
-- 
-- IE parameter types from other modules.
-- 
-- ****

IMPORTS
  Criticality,
  Presence,
  PrivateIE-ID,
```

```

ProtocolIE-ID,
maxPrivateIEs,
maxProtocolExtensions,
maxProtocolIEs
FROM PCAP-CommonDataTypes;

-- ****
-- 
-- Class Definition for Protocol IEs
-- 
-- ****

PCAP-PROTOCOL-IES ::= CLASS {
  &id                  ProtocolIE-ID      UNIQUE,
  &criticality        Criticality,
  &Value,
  &presence           Presence
}
WITH SYNTAX {
  ID                  &id
  CRITICALITY        &criticality
  TYPE                &Value
  PRESENCE            &presence
}

-- ****
-- 
-- Class Definition for Protocol Extensions
-- 
-- ****

PCAP-PROTOCOL-EXTENSION ::= CLASS {
  &id                  ProtocolIE-ID UNIQUE,
  &criticality        Criticality,
  &Extension,
  &presence           Presence
}
WITH SYNTAX {
  ID                  &id
  CRITICALITY        &criticality
  EXTENSION           &Extension
  PRESENCE            &presence
}

-- ****
-- 
-- Class Definition for Private IEs
-- 
-- ****

PCAP-PRIVATE-IES ::= CLASS {
  &id                  PrivateIE-ID,
  &criticality        Criticality,
  &Value,
}

```

```

    &presence          Presence
}
WITH SYNTAX {
    ID                &id
    CRITICALITY      &criticality
    TYPE              &Value
    PRESENCE          &presence
}

-- ****
-- Container for Protocol IEs
--
-- ****

ProtocolIE-Container {PCAP-PROTOCOL-IES : IEsSetParam} ::=

SEQUENCE (SIZE (0..maxProtocolIEs)) OF
    ProtocolIE-Field {{IEsSetParam}}


ProtocolIE-Single-Container {PCAP-PROTOCOL-IES : IEsSetParam} ::=

ProtocolIE-Field {{IEsSetParam}}


ProtocolIE-Field {PCAP-PROTOCOL-IES : IEsSetParam} ::= SEQUENCE {
    id                PCAP-PROTOCOL-IES.&id          {{IEsSetParam}},
    criticality       PCAP-PROTOCOL-IES.&criticality {{IEsSetParam}{@id}},
    value              PCAP-PROTOCOL-IES.&Value       {{IEsSetParam}{@id}}
}

-- ****
-- Container Lists for Protocol IE Containers
--
-- ****

ProtocolIE-ContainerList {INTEGER : lowerBound, INTEGER : upperBound, PCAP-PROTOCOL-IES : IEsSetParam} ::=

SEQUENCE (SIZE (lowerBound..upperBound)) OF
    ProtocolIE-Container {{IEsSetParam}}


-- ****
-- Container for Protocol Extensions
--
-- ****

ProtocolExtensionContainer {PCAP-PROTOCOL-EXTENSION : ExtensionSetParam} ::=

SEQUENCE (SIZE (1..maxProtocolExtensions)) OF
    ProtocolExtensionField {{ExtensionSetParam}}


ProtocolExtensionField {PCAP-PROTOCOL-EXTENSION : ExtensionSetParam} ::= SEQUENCE {
    id                PCAP-PROTOCOL-EXTENSION.&id          {{ExtensionSetParam}},
    criticality       PCAP-PROTOCOL-EXTENSION.&criticality {{ExtensionSetParam}{@id}},
    extensionValue    PCAP-PROTOCOL-EXTENSION.&Extension   {{ExtensionSetParam}{@id}}
}

```

```

-- ****
-- Container for Private IEs
--
-- ****

PrivateIE-Container {PCAP-PRIVATE-IES : IEsSetParam} ::=

SEQUENCE (SIZE (1.. maxPrivateIES)) OF
  PrivateIE-Field {{IEsSetParam}}


PrivateIE-Field {PCAP-PRIVATE-IES : IEsSetParam} ::= SEQUENCE {
  id          PCAP-PRIVATE-IES.&id          {{IEsSetParam}},
  criticality PCAP-PRIVATE-IES.&criticality {{IEsSetParam}}{@id}),
  value        PCAP-PRIVATE-IES.&Value        {{IEsSetParam}}{@id})
}

END

```

9.4 Message Transfer Syntax

PCAP shall use the ASN.1 Basic Packed Encoding Rules (BASIC-PER) Aligned Variant as transfer syntax, as specified in [9].

10 Handling of Unknown, Unforeseen and Erroneous Protocol Data

10.1 General

Protocol Error cases can be divided into three classes:

- Transfer Syntax Error.
- Abstract Syntax Error.
- Logical Error.

Protocol errors can occur in the following functions within a receiving node.

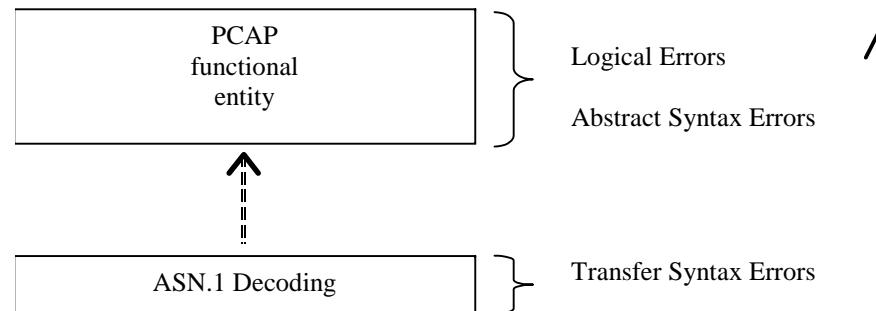


Figure 10: Protocol Errors in PCAP

The information stated in subclauses 10.2, 10.3 and 10.4, to be included in the message used when reporting an error, is what at minimum shall be included. Other optional information elements within the message may also be included, if available. This is also valid for the case when the reporting is done with a response message. The latter is an exception to what is stated in subclause 4.1.

10.2 Transfer Syntax Error

A Transfer Syntax Error occurs when the receiver is not able to decode the received physical message. Transfer syntax errors are always detected in the process of ASN.1 decoding. If a Transfer Syntax Error occurs, the receiver should initiate Error Indication procedure with appropriate cause value for the Transfer Syntax protocol error.

Examples for Transfer Syntax Errors are:

- Violation of value ranges in ASN.1 definition of messages. e.g.: If an IE has a defined value range of 0 to 10 (ASN.1: INTEGER (0..10)), and 12 will be received, then this will be treated as a transfer syntax error.
- Violation in list element constraints. e.g.: If a list is defined as containing 1 to 10 elements, and 12 elements will be received, then this case will be handled as a transfer syntax error.
- Missing mandatory elements in ASN.1 SEQUENCE definitions (as sent by the originator of the message).
- Wrong order of elements in ASN.1 SEQUENCE definitions (as sent by the originator of the message).

10.3 Abstract Syntax Error

10.3.1 General

An Abstract Syntax Error occurs when the receiving functional PCAP entity:

- 1) receives IEs or IE groups that cannot be understood (unknown IE id);

- 2) receives IEs for which the logical range is violated (e.g.: ASN.1 definition: 0 to 15, the logical range is 0 to 10 (values 11 to 15 are undefined), and 12 will be received; this case will be handled as an abstract syntax error using criticality information sent by the originator of the message);
- 3) does not receive IEs or IE groups but according to the specified presence of the concerning object, the IEs or IE groups should have been present in the received message;
- 4) receives IEs or IE groups that are defined to be part of that message in wrong order or with too many occurrences of the same IE or IE group;
- 5) receives IEs or IE groups but according to the conditional presence of the concerning object and the specified condition, the IEs or IE groups should not have been present in the received message.

Cases 1 and 2 (not comprehended IE/IE group) are handled based on received Criticality information. Case 3 (missing IE/IE group) is handled based on Criticality information and Presence information for the missing IE/IE group specified in the version of the specification used by the receiver. Case 4 (IEs or IE groups in wrong order or with too many occurrences) and Case 5 (erroneously present conditional IEs or IE groups) result in rejecting the procedure.

If an Abstract Syntax Error occurs, the receiver shall read the remaining message and shall then for each detected Abstract Syntax Error that belong to cases 1-3 act according to the Criticality Information and Presence Information for the IE/IE group due to which Abstract Syntax Error occurred in accordance with subclauses 10.3.4 and 10.3.5. The handling of cases 4 and 5 is specified in subclause 10.3.6.

10.3.2 Criticality Information

In the PCAP messages there is criticality information set for individual IEs and/or IE groups. This criticality information instructs the receiver how to act when receiving an IE or an IE group that is not comprehended, i.e. the entire item (IE or IE group) which is not (fully or partially) comprehended shall be treated in accordance with its own criticality information as specified in subclause 10.3.4.

In addition, the criticality information is used in case of the missing IE/IE group abstract syntax error (see subclause 10.3.5).

The receiving node shall take different actions depending on the value of the Criticality Information. The three possible values of the Criticality Information for an IE/IE group are:

- Reject IE.
- Ignore IE and Notify Sender.
- Ignore IE.

The following rules restrict when a receiving entity may consider an IE, an IE group, or an EP not comprehended (not implemented), and when action based on criticality information is applicable:

1. IE or IE group: When one new or modified IE or IE group is implemented for one EP from a standard version, then other new or modified IEs or IE groups specified for that EP in that standard version shall be considered comprehended by a receiving entity (some may still remain unsupported).
2. EP: The comprehension of different EPs within a standard version or between different standard versions is not mandated. Any EP that is not supported may be considered not comprehended, even if another EP from that standard version is comprehended, and action based on criticality shall be applied.

10.3.3 Presence Information

For many IEs/IE groups which are optional according to the ASN.1 transfer syntax, PCAP specifies separately if the presence of these IEs/IE groups is optional or mandatory with respect to RNS application by means of the presence field of the concerning object of class PCAP-PROTOCOL-IES, PCAP -PROTOCOL-IES-PAIR, PCAP -PROTOCOL-EXTENSION or PCAP -PRIVATE-IES.

The presence field of the indicated classes supports three values:

1. Optional;
2. Conditional;
3. Mandatory.

If an IE/IE group is not included in a received message and the presence of the IE/IE group is mandatory or the presence is conditional and the condition is true according to the version of the specification used by the receiver, an abstract syntax error occurs due to a missing IE/IE group.

If an IE/IE group is included in a received message and the presence of the IE/IE group is conditional and the condition is false according to the version of the specification used by the receiver, an abstract syntax error occurs due to this erroneously present conditional IE/IE group.

10.3.4 Not comprehended IE/IE group

10.3.4.1 Procedure Code

The receiving node shall treat the different types of received criticality information of the *Procedure Code* IE according to the following:

Reject IE:

- If a message is received with a *Procedure Code* IE marked with "*Reject IE*" which the receiving node does not comprehend, the receiving node shall reject the procedure using the Error Indication procedure.

Ignore IE and Notify Sender:

- If a message is received with a *Procedure Code* IE marked with "*Ignore IE and Notify Sender*" which the receiving node does not comprehend, the receiving node shall ignore the procedure and initiate the Error Indication procedure.

Ignore IE:

- If a message is received with a *Procedure Code* IE marked with "*Ignore IE*" which the receiving node does not comprehend, the receiving node shall ignore the procedure.

When using the Error Indication procedure to reject a procedure or to report an ignored procedure it shall include the *Procedure Code* IE, the *Triggering Message* IE, and the *Procedure Criticality* IE in the *Criticality Diagnostics* IE.

10.3.4.1A Type of Message

When the receiving node cannot decode the *Type of Message* IE, the Error Indication procedure shall be initiated with an appropriate cause value.

10.3.4.2 IEs other than the Procedure Code and Type of Message

The receiving node shall treat the different types of received criticality information of an IE/IE group other than the *Procedure Code* IE and *Type of Message* IE according to the following:

Reject IE:

- If a message *initiating* a procedure is received containing one or more IEs/IE groups marked with "*Reject IE*" which the receiving node does not comprehend; none of the functional requests of the message shall be executed. The receiving node shall reject the procedure and report the rejection of one or more IEs/IE groups using the message normally used to report unsuccessful outcome of the procedure. In case the information received in the initiating message was insufficient to determine a value for all IEs that are required to be present in the message used to report the unsuccessful outcome of the procedure, the receiving node shall instead terminate the procedure and initiate the Error Indication procedure.
- If a message *initiating* a procedure that does not have a message to report unsuccessful outcome is received containing one or more IEs/IE groups marked with "*Reject IE*" which the receiving node does not comprehend, the receiving node shall terminate the procedure and initiate the Error Indication procedure.
- If a *response* message is received containing one or more IEs/IE groups marked with "*Reject IE*", that the receiving node does not comprehend, the receiving node shall consider the procedure as unsuccessfully terminated and initiate local error handling.

Ignore IE and Notify Sender:

- If a message *initiating* a procedure is received containing one or more IEs/IE groups marked with "*Ignore IE and Notify Sender*" which the receiving node does not comprehend, the receiving node shall ignore the content of the not comprehended IEs/IE groups, continue with the procedure as if the not comprehended IEs/IE groups were not received (except for the reporting) using the understood IEs/IE groups, and report in the response message of the procedure that one or more IEs/IE groups have been ignored. In case the information received in the initiating message was insufficient to determine a value for all IEs that are required to be present in the response message, the receiving node shall instead terminate the procedure and initiate the Error Indication procedure.
- If a message *initiating* a procedure that does not have a message to report the outcome of the procedure is received containing one or more IEs/IE groups marked with "*Ignore IE and Notify Sender*" which the receiving node does not comprehend, the receiving node shall ignore the content of the not comprehended IEs/IE groups, continue with the procedure as if the not comprehended IEs/IE groups were not received (except for the reporting) using the understood IEs/IE groups, and initiate the Error Indication procedure to report that one or more IEs/IE groups have been ignored.
- If a *response* message is received containing one or more IEs/IE groups marked with "*Ignore IE and Notify Sender*" which the receiving node does not comprehend, the receiving node shall ignore the content of the not comprehended IEs/IE groups, continue with the procedure as if the not comprehended IEs/IE groups were not received (except for the reporting) using the understood IEs/IE groups and initiate the Error Indication procedure.

Ignore IE:

- If a message *initiating* a procedure is received containing one or more IEs/IE groups marked with "*Ignore IE*" which the receiving node does not comprehend, the receiving node shall ignore the content of the not comprehended IEs/IE groups and continue with the procedure as if the not comprehended IEs/IE groups were not received using the understood IEs/IE groups.
- If a *response* message is received containing one or more IEs/IE groups marked with "*Ignore IE*" which the receiving node does not comprehend, the receiving node shall ignore the content of the not comprehended IEs/IE groups.

When reporting not comprehended IEs/IE groups marked with "*Reject IE*" or "*Ignore IE and Notify Sender*" using a response message defined for the procedure, the *Information Element Criticality Diagnostics* IE shall be included in the *Criticality Diagnostics* IE for each reported IE/IE group. The *Repetition Number* IE shall be included in the *Information Element Criticality Diagnostics* IE if the reported IE/IE group was part of a "*SEQUENCE OF*" definition.

When reporting not comprehended IEs/IE groups marked with "*Reject IE*" or "*Ignore IE and Notify Sender*" using the Error Indication procedure, the *Procedure Code* IE, the *Triggering Message* IE, *Procedure Criticality* IE, the *Transaction Id* IE, and the *Information Element Criticality Diagnostics* IE shall be included in the *Criticality Diagnostics* IE for each reported IE/IE group. The *Repetition Number* IE shall be included in the *Information Element Criticality Diagnostics* IE if the reported IE/IE group was part of a "*SEQUENCE OF*" definition.

10.3.5 Missing IE or IE group

The receiving node shall treat the missing IE/IE group according to the criticality information for the missing IE/IE group in the received message specified in the version of the present document used by the receiver:

Reject IE:

- If a received message *initiating* a procedure is missing one or more IEs/IE groups with specified criticality "*Reject IE*"; none of the functional requests of the message shall be executed. The receiving node shall reject the procedure and report the missing IEs/IE groups using the message normally used to report unsuccessful outcome of the procedure. In case the information received in the initiating message was insufficient to determine a value for all IEs that are required to be present in the message used to report the unsuccessful outcome of the procedure, the receiving node shall instead terminate the procedure and initiate the Error Indication procedure.
- If a received message *initiating* a procedure that does not have a message to report unsuccessful outcome is missing one or more IEs/IE groups with specified criticality "*Reject IE*", the receiving node shall initiate the Error Indication procedure.
- If a received *response* message is missing one or more IEs/IE groups with specified criticality "*Reject IE*", the receiving node shall consider the procedure as unsuccessfully terminated and initiate local error handling.

Ignore IE and Notify Sender:

- If a received message *initiating* a procedure is missing one or more IEs/IE groups with specified criticality "*Ignore IE and Notify Sender*", the receiving node shall ignore that those IEs are missing and continue with the procedure based on the other IEs/IE groups present in the message and report in the response message of the procedure that one or more IEs/IE groups were missing. In case the information received in the initiating message was insufficient to determine a value for all IEs that are required to be present in the response message, the receiving node shall instead terminate the procedure and initiate the Error Indication procedure.

- If a received message *initiating* a procedure that does not have a message to report the outcome of the procedure is missing one or more IEs/IE groups with specified criticality "*Ignore IE and Notify Sender*", the receiving node shall ignore that those IEs are missing and continue with the procedure based on the other IEs/IE groups present in the message and initiate the Error Indication procedure to report that one or more IEs/IE groups were missing.
- If a received *response* message is missing one or more IEs/IE groups with specified criticality "*Ignore IE and Notify Sender*", the receiving node shall ignore that those IEs are missing and continue with the procedure based on the other IEs/IE groups present in the message and initiate the Error Indication procedure to report that one or more IEs/IE groups were missing.

Ignore IE:

- If a received message *initiating* a procedure is missing one or more IEs/IE groups with specified criticality "*Ignore IE*", the receiving node shall ignore that those IEs are missing and continue with the procedure based on the other IEs/IE groups present in the message.
- If a received *response* message is missing one or more IEs/IE groups with specified criticality "*Ignore IE*", the receiving node shall ignore that those IEs/IE groups are missing.

When reporting missing IEs/IE groups with specified criticality "*Reject IE*" or "*Ignore IE and Notify Sender*" using a response message defined for the procedure, the *Information Element Criticality Diagnostics* IE shall be included in the *Criticality Diagnostics* IE for each reported IE/IE group.

When reporting missing IEs/IE groups with specified criticality "*Reject IE*" or "*Ignore IE and Notify Sender*" using the Error Indication procedure, the *Procedure Code* IE, the *Triggering Message* IE, *Procedure Criticality* IE, the *Transaction Id* IE, and the *Information Element Criticality Diagnostics* IE shall be included in the *Criticality Diagnostics* IE for each reported IE/IE group.

10.3.6 IEs or IE groups received in wrong order or with too many occurrences or erroneously present

If a message with IEs or IE groups in wrong order or with too many occurrences is received or if IEs or IE groups with a conditional presence are present when the condition is not met (i.e. erroneously present), the receiving node shall behave according to the following:

- If a message *initiating* a procedure is received containing IEs or IE groups in wrong order or with too many occurrences or erroneously present, none of the functional requests of the message shall be executed. The receiving node shall reject the procedure and report the cause value "Abstract Syntax Error (Falsely Constructed Message)" using the message normally used to report unsuccessful outcome of the procedure. In case the information received in the initiating message was insufficient to determine a value for all IEs that are required to be present in the message used to report the unsuccessful outcome of the procedure, the receiving node shall instead terminate the procedure and initiate the Error Indication.
- If a message *initiating* a procedure that does not have a message to report unsuccessful outcome is received containing IEs or IE groups in wrong order or with too many occurrences or erroneously present, the receiving node shall terminate the procedure and initiate the Error Indication procedure, and use cause value "Abstract Syntax Error (Falsely Constructed Message)".
- If a *response* message is received containing IEs or IE groups in wrong order or with too many occurrences or erroneously present, the receiving node shall consider the procedure as unsuccessfully terminated and initiate local error handling.

10.4 Logical Error

Logical error situations occur when a message is comprehended correctly, but the information contained within the message is not valid (i.e. semantic error), or describes a procedure which is not compatible with the state of the receiver. In these conditions, the following behaviour shall be performed (unless otherwise specified) as defined by the class of the elementary procedure, irrespective of the criticality of the IEs/IE groups containing the erroneous values.

Class 1:

Protocol Causes:

Where the logical error occurs in a request message of a class 1 procedure, and the procedure has a message to report this unsuccessful outcome, this message shall be sent with an appropriate cause value. Typical cause values are:

1. Semantic Error.
2. Message not compatible with receiver state.

Where the logical error is contained in a request message of a class 1 procedure, and the procedure does not have a message to report this unsuccessful outcome, the procedure shall be terminated and the Error Indication procedure shall be initiated with an appropriate cause value.

Where the logical error exists in a response message of a class 1 procedure, the procedure shall be considered as unsuccessfully terminated and local error handling shall be initiated.

Class 2:

Where the logical error occurs in a message of a class 2 procedure, the procedure shall be terminated and the Error Indication procedure shall be initiated with an appropriate cause value.

10.5 Exceptions

The error handling for all the cases described hereafter shall take precedence over any other error handling described in the other subclauses of clause 10.

- If any type of error (Transfer Syntax Error, Abstract Syntax Error or Logical Error) is detected in the ERROR INDICATION message, it shall not trigger the Error Indication procedure in the receiving Node but local error handling.
- In case a response message or Error Indication message needs to be returned, but the information necessary to determine the receiver of that message is missing, the procedure shall be considered as unsuccessfully terminated and local error handling shall be initiated.
- If an error that terminates a procedure occurs, the returned cause value shall reflect the error that caused the termination of the procedure even if one or more abstract syntax errors with criticality “ignore and notify” have earlier occurred within the same procedure.

Annex A (informative): Guidelines for Usage of the Criticality Diagnostics IE

A.1 EXAMPLE MESSAGE Layout

Assume the following message format:

Table A.1

IE/Group Name	Presence	Range	IE type and reference	Semantics description	Criticality	Assigned Criticality
Message Type	M				YES	Reject
Transaction ID	M				-	
A	M				YES	reject
B	M				YES	reject
>E		1..<maxE>			EACH	ignore
>>F		1..<maxF>			-	
>>>G		0..3, ...			EACH	ignore
>>H		1..<maxH>			EACH	ignore
>>>G		0..3, ...			EACH	ignore and notify
>>G	M				YES	reject
>>J		1..<maxJ>			-	
>>>G		0..3, ...			EACH	reject
C	M				YES	reject
>K		1..<maxK>			EACH	ignore and notify
>>L		1..<maxL>			-	
>>>M	O				-	
D	M				YES	reject

NOTE: The IEs F, J, and L do not have assigned criticality. The IEs F, J, and L are consequently realised as the ASN.1 type SEQUENCE OF of "ordinary" ASN.1 type, e.g. INTEGER. On the other hand, the repeatable IEs with assigned criticality are realised as the ASN.1 type SEQUENCE OF of an IE object, e.g. ProtocolIE-Single-Container.

For the corresponding ASN.1 layout, see clause A.4.

A.2 Example on a Received EXAMPLE MESSAGE

Assume further more that a received message based on the above tabular format is according to figure A.1.

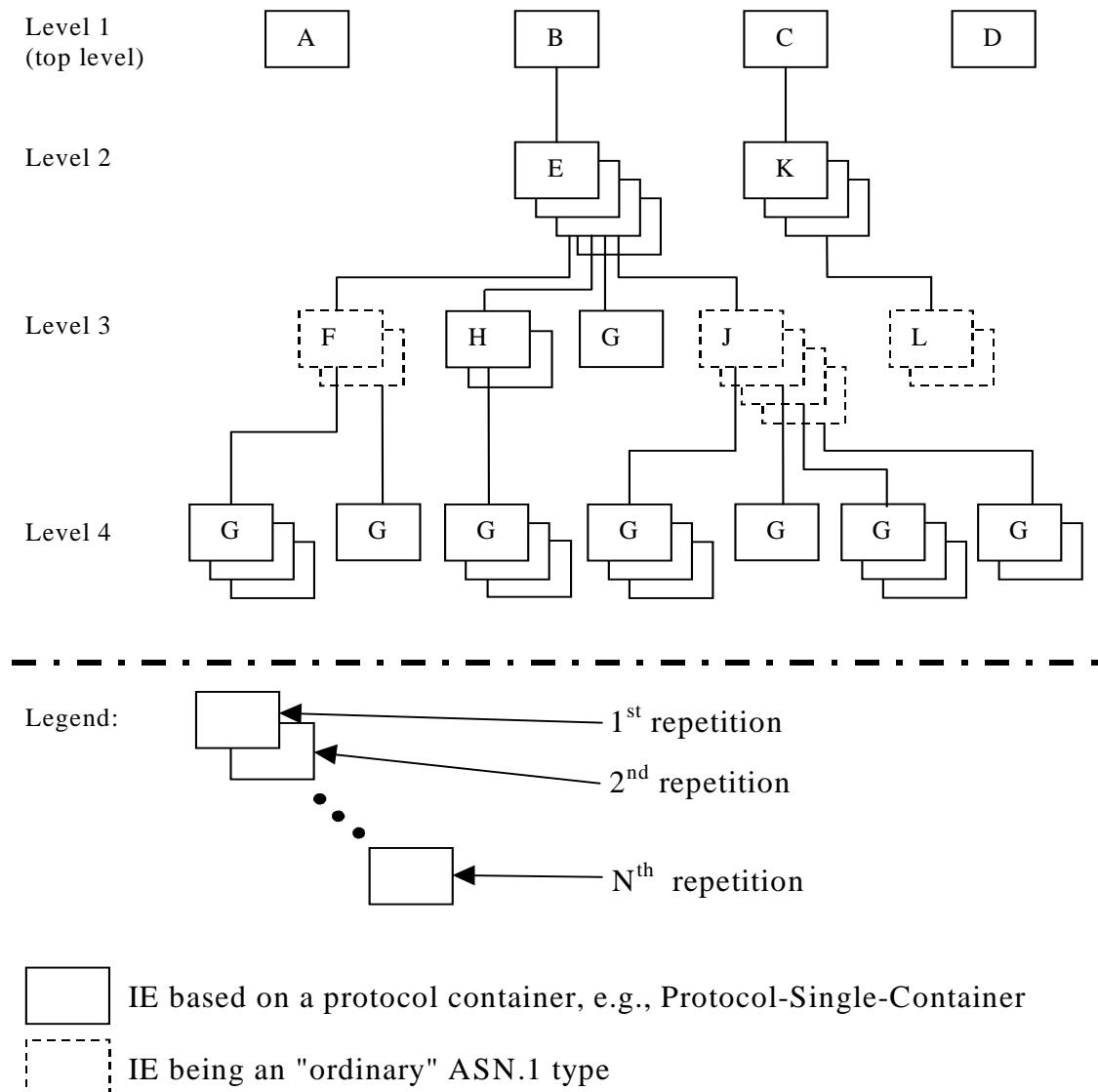


Figure A.1: Example of content of a received PCAP message based on the EXAMPLE MESSAGE

A.3 Content of Criticality Diagnostics

A.3.1 Example 1

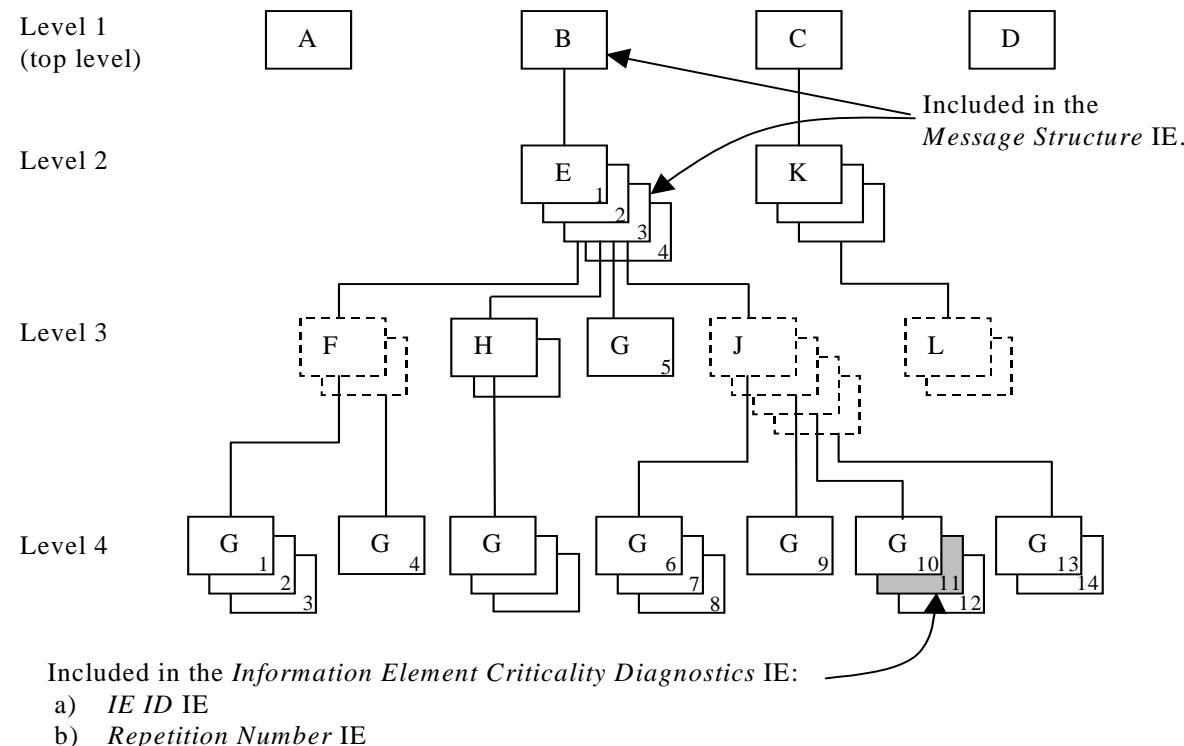


Figure A.2: Example of a received PCAP message containing a not comprehended IE

If there is an error within the instance marked as grey in the IE G in the IE J shown in the figure A.2, this will be reported within the *Information Element Criticality Diagnostics IE* within the *Criticality Diagnostics IE*s in table A.2.

Table A.2

IE name	Value	Comment
IE Criticality	Reject	Criticality for IE on the reported level, i.e. level 4.
IE ID	id-G	IE ID from the reported level, i.e. level 4.
Repetition Number	11	Repetition number on the reported level, i.e. level 4. (Since the IE E (level 2) is the lowest level included in the <i>Message Structure IE</i> this is the eleventh occurrence of IE G within the IE E (level 2).)
Type of Error	not understood	
<i>Message Structure, first repetition</i>		
>IE ID	id-B	IE ID from level 1.
<i>Message Structure, second repetition</i>		
>IE ID	id-E	IE ID from the lowest level above the reported level, i.e. level 2.
>Repetition Number	3	Repetition number from the lowest level above the reported level, i.e. level 2.

NOTE 1: The IE J on level 3 cannot be included in the *Message Structure IE* since they have no criticality of their own.

NOTE 2: The repetition number of the reported IE indicates the number of repetitions of IE G received up to the detected erroneous repetition, counting all occurrences of the IE G below the same instance of the previous level with assigned criticality (instance 3 of IE E on level 2).

A.3.2 Example 2

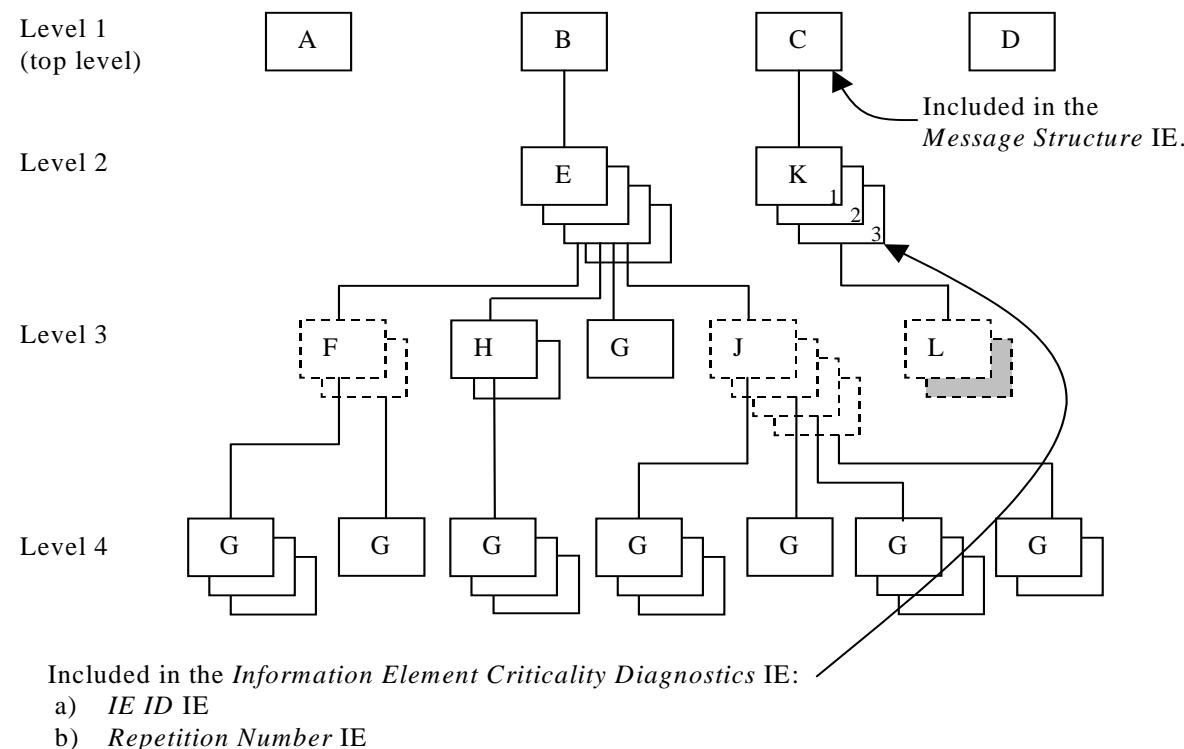


Figure A.3: Example of a received PCAP message containing a not comprehended IE

If there is an error within the second instance (marked as grey) in the sequence (IE L in the tabular format) on level 3 below IE K in the structure shown in the figure A.3, this will be reported within the *Information Element Criticality Diagnostics IE* within the *Criticality Diagnostics IE*s in table A.3.

Table A.3

IE name	Value	Comment
IE Criticality	ignore and notify	Criticality for IE on the reported level, i.e. level 2.
IE ID	id-K	IE ID from the reported level, i.e. level 2.
Repetition Number	3	Repetition number on the reported level, i.e. level 2.
Type of Error	not understood	
Message Structure, <i>first repetition</i>		
>IE ID	id-C	IE ID from the lowest level above the reported level, i.e. level 1.

NOTE: The IE L on level 3 cannot be reported individually included in the *Message Structure* IE since it has no criticality of its own.

A.3.3 Example 3

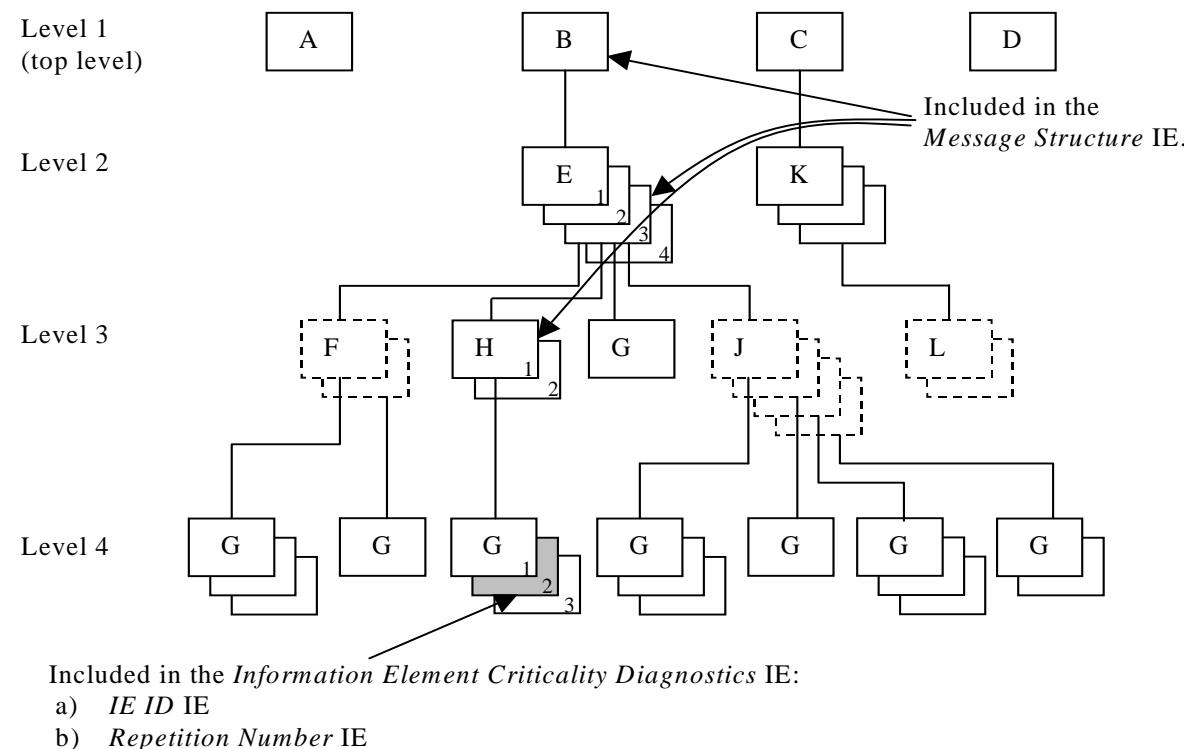


Figure A.4: Example of a received PCAP message containing a not comprehended IE

If there is an error within the instance marked as grey in the IE G in the IE H shown in the figure A.4, this will be reported within the *Information Element Criticality Diagnostics IE* within the *Criticality Diagnostics IE* as in table A.4.

Table A.4

IE name	Value	Comment
IE Criticality	ignore and notify	Criticality for IE on the reported level, i.e. level 4.
IE ID	id-G	IE ID from the reported level, i.e. level 4.
Repetition Number	2	Repetition number on the reported level, i.e. level 4.
Type of Error	not understood	
<i>Message Structure, first repetition</i>		
>IE ID	id-B	IE ID from level 1.
<i>Message Structure, second repetition</i>		
>IE ID	id-E	IE ID from level 2.
>Repetition Number	3	Repetition number from level 2.
<i>Message Structure, third repetition</i>		
>IE ID	id-H	IE ID from the lowest level above the reported level, i.e. level 3.
>Repetition Number	1	Repetition number from the lowest level above the reported level, i.e. level 3.

NOTE: The repetition number of level 4 indicates the number of repetitions of IE G received up to the detected erroneous repetition, counted below the same instance of the previous level with assigned criticality (instance 1 of IE H on level 3).

A.3.4 Example 4

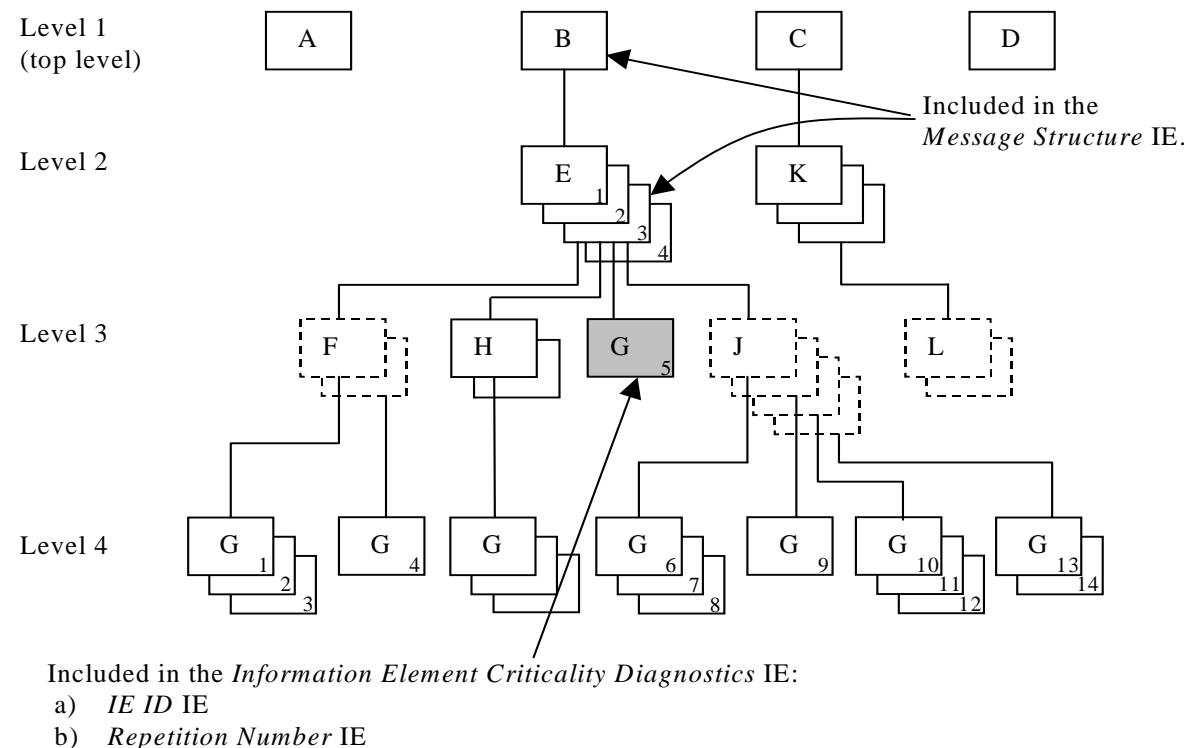


Figure A.5: Example of a received PCAP message containing a not comprehended IE

If there is an error within the instance marked as grey in the IE G in the IE E shown in the figure A.5, this will be reported within the *Information Element Criticality Diagnostics IE* within the *Criticality Diagnostics IE*, as in table A.5.

Table A.5

IE name	Value	Comment
IE Criticality	Reject	Criticality for IE on the reported level, i.e. level 3.
IE ID	id-G	IE ID from the reported level, i.e. level 3.
Repetition Number	5	Repetition number on the reported level, i.e. level 3. (Since the IE E (level 2) is the lowest level included in the <i>Message Structure</i> IE this is the fifth occurrence of IE G within the IE E (level 2).)
Type of Error	not understood	
<i>Message Structure, first repetition</i>		
>IE ID	id-B	IE ID from level 1.
<i>Message Structure, second repetition</i>		
>IE ID	id-E	IE ID from the lowest level above the reported level, i.e. level 2.
>Repetition Number	3	Repetition number from the lowest level above the reported level, i.e. level 2.

NOTE: The repetition number of the reported IE indicates the number of repetitions of IE G received up to the detected erroneous repetition, counting all occurrences of the IE G below the same instance of the previous level with assigned criticality (instance 3 of IE E on level 2).

A.3.5 Example 5

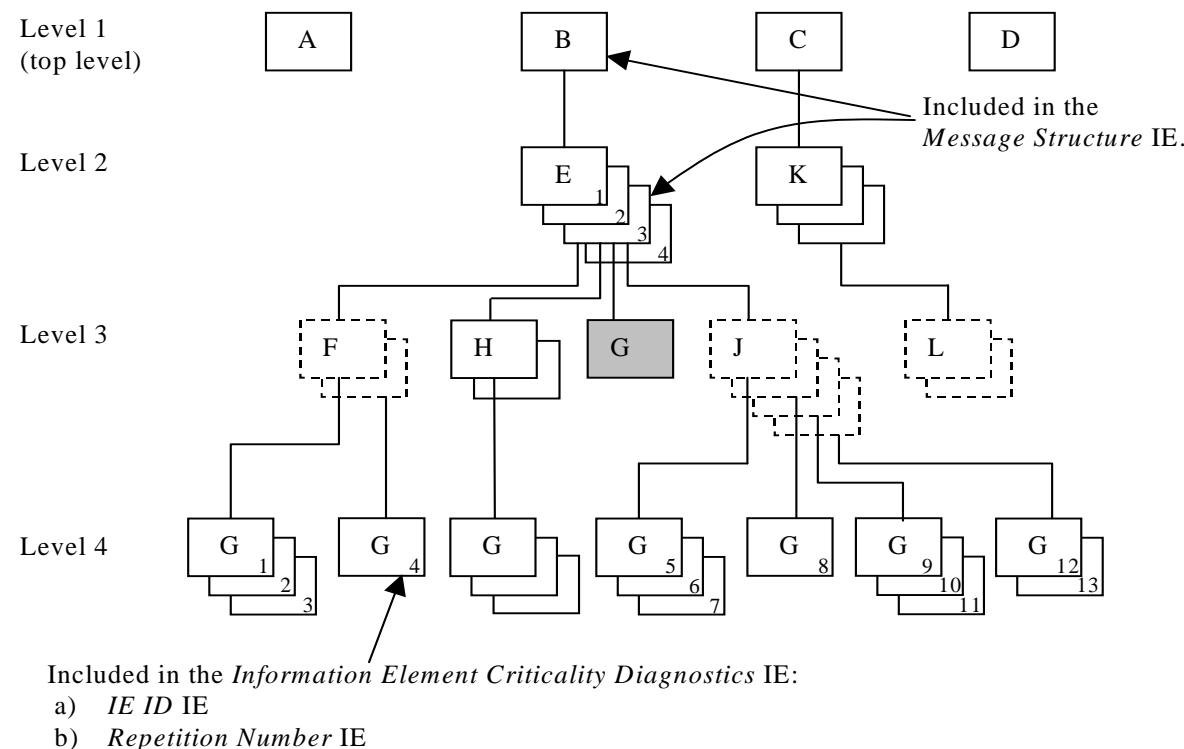


Figure A.6: Example of a received PCAP message with a missing IE

If the instance marked as grey in the IE G in the IE E shown in the figure A.6, is missing this will be reported within the *Information Element Criticality Diagnostics IE* within the *Criticality Diagnostics IE*, as in table A.6.

Table A.6

IE name	Value	Comment
IE Criticality	reject	Criticality for IE on the reported level, i.e. level 3.
IE ID	id-G	IE ID from the reported level, i.e. level 3.
Repetition Number	4	Repetition number up to the missing IE on the reported level, i.e. level 3. (Since the IE E (level 2) is the lowest level included in the <i>Message Structure</i> IE there have been four occurrences of IE G within the IE E (level 2) up to the missing occurrence.
Type of Error	missing	
Message Structure, <i>first repetition</i>		
>IE ID	id-B	IE ID from level 1.
Message Structure, <i>second repetition</i>		
>IE ID	id-E	IE ID from the lowest level above the reported level, i.e. level 2.
>Repetition Number	3	Repetition number from the lowest level above the reported level, i.e. level 2.

NOTE: The repetition number of the reported IE indicates the number of repetitions of IE G received up to but not including the missing occurrence, counting all occurrences of the IE G below the same instance of the previous level with assigned criticality (instance 3 of IE E on level 2).

A.4 ASN.1 of EXAMPLE MESSAGE

```

ExampleMessage ::= SEQUENCE {
  ProtocolIEs          ProtocolIE-Container      {{ExampleMessage-IEs}},
  ProtocolExtensions   ProtocolExtensionContainer {{ExampleMessage-Extensions}}  OPTIONAL,
  ...
}

ExampleMessage-IEs PCAP-PROTOCOL-IES ::= {
  { ID id-A  CRITICALITY reject  TYPE A  PRESENCE mandatory} |
  { ID id-B  CRITICALITY reject  TYPE B  PRESENCE mandatory} |
  { ID id-C  CRITICALITY reject  TYPE C  PRESENCE mandatory} |
  { ID id-D  CRITICALITY reject  TYPE D  PRESENCE mandatory} ,
  ...
}

B ::= SEQUENCE {
  e          E-List,
  iE-Extensions  ProtocolExtensionContainer { {B-ExtIEs} }  OPTIONAL,
  ...
}

B-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

```

```

E-List ::= SEQUENCE (SIZE (1..maxE)) OF ProtocolIE-Single-Container { {E-IEs} }

E-IEs PCAP-PROTOCOL-IES ::= {
  { ID id-E  CRITICALITY ignore  TYPE E  PRESENCE mandatory  }
}

E ::= SEQUENCE {
  f          F-List,
  h          H-List,
  g          G-List1,
  j          J-List,
  iE-Extensions  ProtocolExtensionContainer { {E-ExtIEs} }  OPTIONAL,
  ...
}

E-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

F-List ::= SEQUENCE (SIZE (1..maxF)) OF F

F ::= SEQUENCE {
  g          G-List2 OPTIONAL,
  iE-Extensions  ProtocolExtensionContainer { {F-ExtIEs} }  OPTIONAL,
  ...
}

F-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

G-List2 ::= SEQUENCE (SIZE (1..3, ...)) OF ProtocolIE-Single-Container { {G2-IEs} }

G2-IEs PCAP-PROTOCOL-IES ::= {
  { ID id-G  CRITICALITY ignore  TYPE G  PRESENCE mandatory  }
}

H-List ::= SEQUENCE (SIZE (1..maxH)) OF ProtocolIE-Single-Container { {H-IEs} }

H-IEs PCAP-PROTOCOL-IES ::= {
  { ID id-H  CRITICALITY ignore  TYPE H  PRESENCE mandatory  }
}

H ::= SEQUENCE {
  g          G-List3 OPTIONAL,
  iE-Extensions  ProtocolExtensionContainer { {H-ExtIEs} } OPTIONAL,
  ...
}

H-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
  ...
}

G-List3 ::= SEQUENCE (SIZE (1..3, ...)) OF ProtocolIE-Single-Container { {G3-IEs} }

```

```

G3-IEs PCAP-PROTOCOL-IES ::= {
    { ID id-G    CRITICALITY notify    TYPE G    PRESENCE mandatory  }
}

G-List1 ::= ProtocolIE-Single-Container { {G1-IEs} }

G1-IEs PCAP-PROTOCOL-IES ::= {
    { ID id-G    CRITICALITY reject    TYPE G    PRESENCE mandatory  }
}

J-List ::= SEQUENCE (SIZE (1..maxJ)) OF J

J ::= SEQUENCE {
    g          G-List4 OPTIONAL,
    iE-Extensions  ProtocolExtensionContainer { {J-ExtIEs} }  OPTIONAL,
    ...
}

J-ExtIEs    PCAP-PROTOCOL-EXTENSION ::= {
    ...
}

G-List4 ::= SEQUENCE (SIZE (1..3, ...)) OF ProtocolIE-Single-Container { {G4-IEs} }

G4-IEs PCAP-PROTOCOL-IES ::= {
    { ID id-G    CRITICALITY reject    TYPE G    PRESENCE mandatory  }
}

C ::= SEQUENCE {
    k          K-List,
    iE-Extensions  ProtocolExtensionContainer { {C-ExtIEs} }  OPTIONAL,
    ...
}

C-ExtIEs    PCAP-PROTOCOL-EXTENSION ::= {
    ...
}

K-List ::= SEQUENCE (SIZE (1..maxK)) OF ProtocolIE-Single-Container { {K-IEs} }

K-IEs PCAP-PROTOCOL-IES ::= {
    { ID id-K    CRITICALITY notify    TYPE K    PRESENCE mandatory  }
}

K ::= SEQUENCE {
    l          L-List,
    iE-Extensions  ProtocolExtensionContainer { {K-ExtIEs} }  OPTIONAL,
    ...
}

K-ExtIEs    PCAP-PROTOCOL-EXTENSION ::= {
    ...
}

```

```
L-List ::= SEQUENCE (SIZE (1..maxL)) OF L

L ::= SEQUENCE {
    m                  M    OPTIONAL,
    iE-Extensions     ProtocolExtensionContainer { {L-ExtIEs} }    OPTIONAL,
    ...
}

L-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
    ...
}

ExampleMessage-Extensions PCAP-PROTOCOL-EXTENSION ::= {
```

Annex B (informative):

Change history

Change history							
Date	TSG #	TSG Doc.	CR	Rev	Subject/Comment	Old	New
06/2001	12	RP-010402			Approved at TSG RAN #12 and placed under Change Control	-	5.0.0
09/2001	13	RP-010603	002	1	Correction to the Error handling of the ERROR INDICATION message	5.0.0	5.1.0
09/2001	13	RP-010603	003		Proposed CR to 25.453 on Semantics Description of C/No	5.0.0	5.1.0
09/2001	13	RP-010603	004		Proposed CR to 25.453 on Clause 10	5.0.0	5.1.0
09/2001	13	RP-010603	005	1	Error handling of the Erroneously Present Conditional Ies	5.0.0	5.1.0
09/2001	13	RP-010603	006	1	Clarification of chapter 10	5.0.0	5.1.0
09/2001	13	RP-010603	007		PCAP Criticality	5.0.0	5.1.0
12/2001	14	RP-010875	008	1	Bitstrings ordering	5.1.0	5.2.0
12/2001	14	RP-010875	009	1	Reference corrections	5.1.0	5.2.0
12/2001	14	RP-010875	010	1	Clarification for the definition of the ASN.1 constants	5.1.0	5.2.0
12/2001	14	RP-010875	012	1	Procedure Code Criticality in Error Indication	5.1.0	5.2.0
12/2001	14	RP-010875	013	2	Addition of amendment to clarify the PER encoding of bitstrings	5.1.0	5.2.0
12/2001	14	RP-010875	014	1	Clarification of the Transaction ID	5.1.0	5.2.0
12/2001	14	RP-010875	015		Correction the Clause 10 Error Handling	5.1.0	5.2.0
-3/2002	15	RP-020211	016		Modification on the Object Identifier	5.2.0	5.3.0
06/2002	16	RP-020432	017	2	Criticality Information Decoding Failure Handling	5.3.0	5.4.0
06/2002	16	RP-020432	018	1	Clarification for the usage of the cause value	5.3.0	5.4.0
03/2003	19	RP-030065	023		CR on GPS Almanac and Satellite Health	5.4.0	5.5.0
03/2003	19	RP-030065	024		CR on GPS Measured Results	5.4.0	5.5.0
03/2003	19	RP-030067	026		Alignment of "Uncertainty Ellipse" with RRC	5.4.0	5.5.0
03/2003	19	RP-030070	027		Correction for the Information Exchange Initiation procedure	5.4.0	5.5.0
03/2003	19	RP-030084	022	2	CR on revising the position calculation function and definition of SAS to support all REL-4 UE positioning methods	5.5.0	6.0.0
06/2003	20	RP-030324	032	1	Alignment of the Requested Data Value Information IE description	6.0.0.	6.1.0
06/2003	20	RP-030325	034		GPS trigger condition	6.0.0.	6.1.0
06/2003	20	RP-030341	035		Position Calculation Extension for TDD	6.0.0.	6.1.0
06/2003	20	RP-030322	037	1	"On Modification" and "Periodic" reporting alignment for Information Exchange procedures	6.0.0.	6.1.0
06/2003	20	RP-030322	044		CR on Criticality Aspects	6.0.0.	6.1.0
06/2003	20	RP-030322	045		CR on Information Exchange Initiation Request for GPS Navigation Model	6.0.0.	6.1.0
06/2003	20	RP-030322	046		CR on DGPS Parameters	6.0.0.	6.1.0
06/2003	20	RP-030322	047		CR on Removal of Information Exchange Object Type	6.0.0.	6.1.0
06/2003	20	RP-030322	048		CR on Information Report of GPS Almanac and Satellite Health	6.0.0.	6.1.0
06/2003	20	RP-030326	050		Correction of Failure message used for logical errors	6.0.0.	6.1.0
09/2003	21	RP-030442	052		Correction to an incorrect implementation in the Requested Data Value Information IE	6.1.0	6.2.0
09/2003	21	RP-030445	054		Alignment of title and sub-clause text of chapter 10.3.4.2	6.1.0	6.2.0
09/2003	21	RP-030446	059		Removal of the note in chapter 10	6.1.0	6.2.0

Change history								
Date	TSG #	TSG Doc.	CR	Rev	Subject/Comment	Old	New	
09/2003	21	RP-030454	060		Improvement of position calculation with pathloss	6.1.0	6.2.0	
12/2003	22	RP-030697	061		Improvement of position calculation through set enlargement	6.2.0	6.3.0	
12/2003	22	RP-030683	064		Information Exchange Initiation behavior correction	6.2.0	6.3.0	
03/2004	23	RP-040053	068		Alignment with 23.032 correction of Included Angle for Ellipsoid Arc	6.3.0	6.4.0	
03/2004	23	RP-040075	069		Initial UE Position IE only mandatory necessary for GPS	6.3.0	6.4.0	
03/2004	23	RP-040072	071		PCAP Review	6.3.0	6.4.0	
06/2004	24	RP-040184	072	1	Correction to usage of INITIAL UE POSITION	6.4.0	6.5.0	
09/2004	25	RP-040306	074	1	Introduction of the requested accuracy and an indication of achieved accuracy in Position Calculation procedure over lupc interface	6.5.0	6.6.0	
12/2004	26	RP-040441	076		outdated ITU-T reference	6.6.0	6.7.0	
03/2005	27	RP-050055	078	1	Corrections to descriptions of GPS Almanac and Ephemeris fields	6.7.0	6.8.0	
06/2005	28	RP-050217	082	2	Correction of deletion of Information Exchange Context	6.8.0	6.9.0	
09/2005	29	RP-050441	083	1	Addition of the U-TDOA positioning method to the UTRAN	6.9.0	7.0.0	
12/2005	30	RP-050705	086	2	Addition of TDD aspects of the U-TDOA positioning method	7.0.0	7.1.0	
12/2005	30	RP-050701	087		PCAP Review	7.0.0	7.1.0	
12/2005	30	RP-050706	088		Wording Alignment for Procedure Text	7.0.0	7.1.0	
03/2006	31	RP-060072	084	10	Enabling the Providing of Velocity	7.1.0	7.2.0	
03/2006	31	RP-060071	089	1	Completion of SAS-centric mode	7.1.0	7.2.0	
03/2006	31	RP-060073	090	1	Introduction of 7.68Mcps TDD option	7.1.0	7.2.0	
06/2006	32	RP-060290	093	2	Release 7 Timing Advance (3.84 Mpcps and 7.68 Mcps TDD)	7.2.0	7.3.0	
06/2006	32	RP-060386	094	1	Correction of positioning confidence reporting inconsistencies	7.2.0	7.3.0	
09/2006	33	RP-060510	095	3	Addition of Periodic Location Procedures	7.3.0	7.4.0	
09/2006	33	RP-060509	096	2	Extended WCDMA Cell Range	7.3.0	7.4.0	
12/2006	34	RP-060705	097		Correction of Round Trip Time for Extended Cell Range	7.4.0	7.5.0	
12/2006	34	RP-060837	098	1	Consistency of Specification Notations	7.4.0	7.5.0	
03/2007	35	RP-070052	101	1	Presence inconsistency	7.5.0	7.6.0	
03/2007	35	RP-070064	102	2	UE Rx-Tx Time Difference Type 1	7.5.0	7.6.0	
06/2007	36	RP-070340	103	2	Support for additional measurements in Cell-ID positioning method and Information Exchange	7.6.0	7.7.0	
06/2007	36	RP-070337	105	2	Introduction of GANSS (Galileo and Additional Navigation Systems) in PCAP	7.6.0	7.7.0	
06/2007	36	RP-070474	106	2	Introduction of Extended RNC-ID	7.6.0	7.7.0	
09/2007	37	RP-070727	104	8	SAS-Centric A-GPS UE requesting additional Assistance Data	7.7.0	7.8.0	
09/2007	37	RP-070579	108		Corrections for ASN.1	7.7.0	7.8.0	
12/2007	38	RP-070842	109	1	PCAP Review	7.8.0	7.9.0	
12/2007	38	RP-070845	110		Addition of GPS Reference Time Uncertainty	7.8.0	7.9.0	
12/2007	38	RP-070844	111	1	Some corrections for 1.28Mcps TDD	7.8.0	7.9.0	
03/2008	39	RP-080075	112	1	Impacts of RRC GANSS changes	7.9.0	7.10.0	
06/2008	40	RP-080300	113	1	GANSS Corrections	7.10.0	7.11.0	
12/2008	42	RP-080839	114		GANSS ASN.1 Correction	7.11.0	7.12.0	
12/2008	42	RP-080852	115	1	Support for additional navigation satellite systems in PCAP	7.11.0	8.0.0	

History

Document history		
V8.0.0	January 2009	Publication